

Rasterization, or “What is `glBegin(GL_LINES)` really doing?”

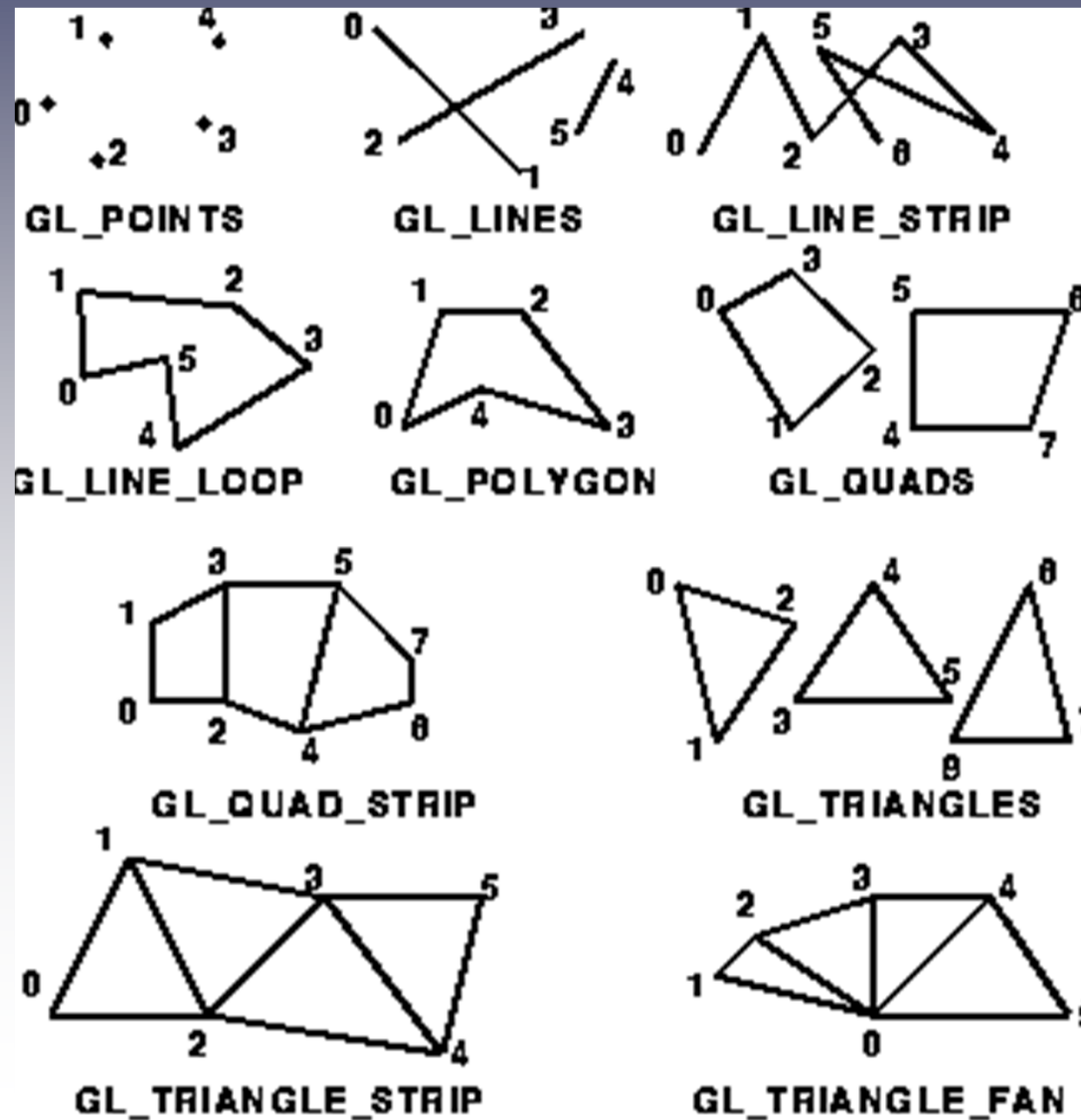
Prof. Christopher Rasmussen

for Prof. Yu's CISC 440/640

Outline

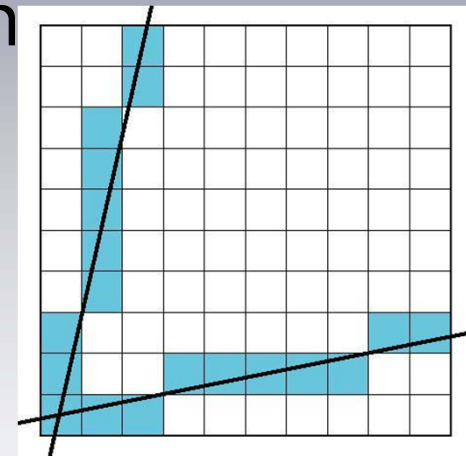
- Rasterizing lines
 - DDA/parametric algorithm
 - Midpoint/Bresenham's algorithm
- Rasterizing polygons/triangles

OpenGL Geometric Primitives



Rasterization: What is it?

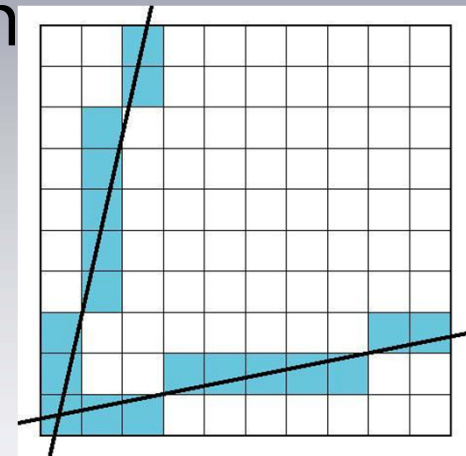
- How to go from **floating-point coords** of geometric primitives' vertices to **integer coordinates** of pixels on screen
- Geometric primitives
 - Points: Round vertex location in screen coordinates



from Angel

Rasterization: What is it?

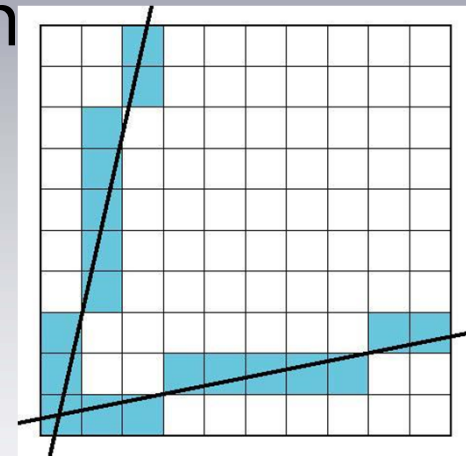
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 - Lines: Can do this for endpoints, but what about in between?



from Angel

Rasterization: What is it?

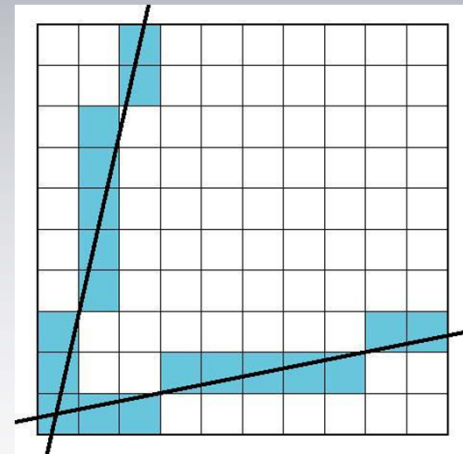
- How to go from **floating-point coords** of geometric primitives' vertices to **integer coordinates** of pixels on screen
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 - Points: Round vertex location in screen coordinates
 - Lines: Can do this for endpoints, but what about in between?
 - Polygons: How to fill area bounded by edges?



from Angel

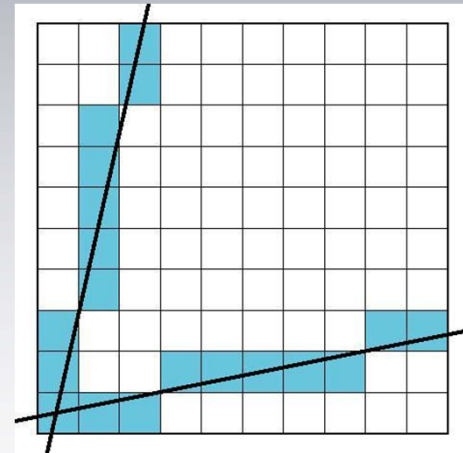
Rasterizing Lines: Goals

- Draw pixels as close to the ideal line as possible



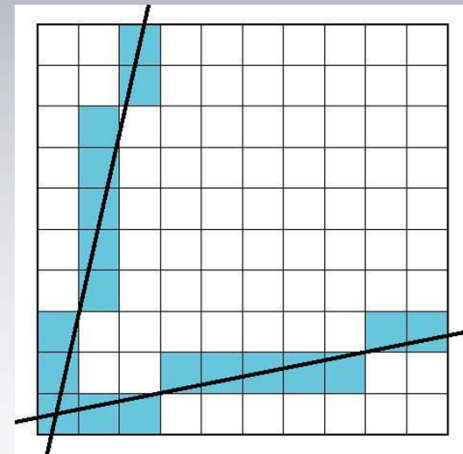
Rasterizing Lines: Goals

- Draw pixels as close to the ideal line as possible
- Use the minimum number of pixels without leaving any gaps



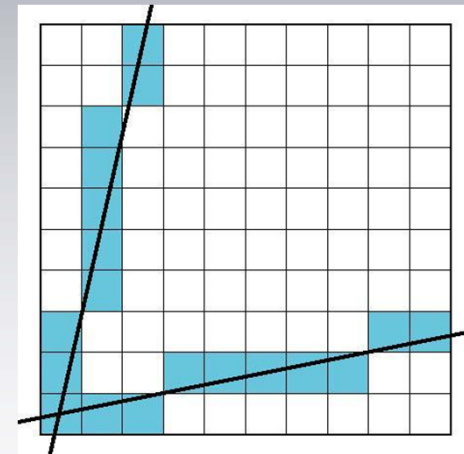
Rasterizing Lines: Goals

- Draw pixels as close to the ideal line as possible
- Use the minimum number of pixels without leaving any gaps
- Do it efficiently



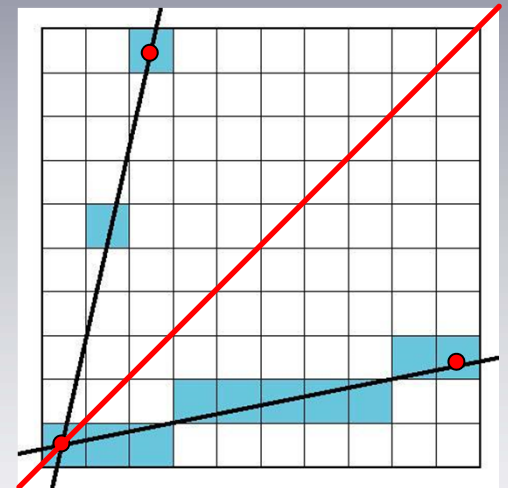
Rasterizing Lines: Goals

- Draw pixels as close to the ideal line as possible
- Use the minimum number of pixels without leaving any gaps
- Do it efficiently
- Extras
 - Handle different line styles
 - Width
 - Stippling (dotted and dashed lines)
 - Join styles for connected lines
 - Minimize aliasing (“jaggies”)



DDA/Parametric Line Drawing

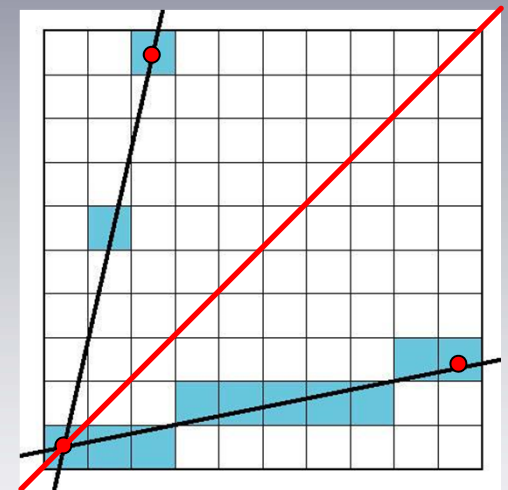
- DDA stands for Digital Differential Analyzer, the name of a class of old machines used for plotting functions
- Slope-intercept form of a line: $y = mx + b$
 - $m = dy/dx$
 - b is where the line intersects the Y axis



from Angel

DDA/Parametric Line Drawing

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- Slope-intercept form of a line: $y = mx + b$
 - $m = dy/dx$
 - b is where the line intersects the Y axis
- DDA's basic idea: If we increment the x coordinate by 1 pixel at each step, the slope of the line tells us how much to increment y per step
 - I.e., $m = dy/dx$, so for $dx = 1$, $dy = m$



from Angel

DDA/Parametric Line Drawing

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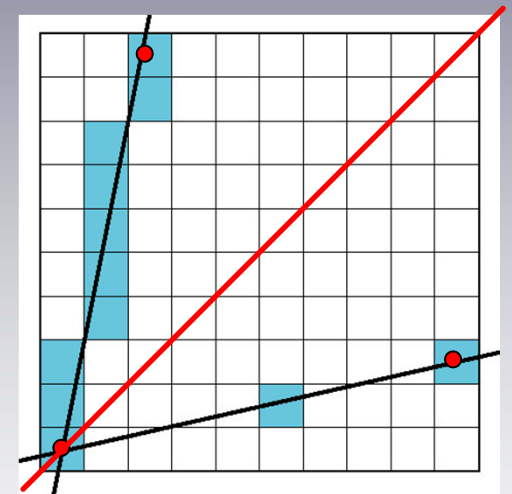
- b is where the line intersects the Y axis

- DDA's basic idea: If we increment the x coordinate by 1 pixel at each step, the slope of the line tells us how much to increment y per step

- I.e., $m = dy/dx$, so for $dx = 1$, $dy = m$

- This only works if $m \leq 1$ —otherwise there are gaps

- Solution: Reverse axes and step in Y direction. Since now $dy = 1$, we get $dx = 1/m$



from Angel

DDA: Algorithm

1. Given endpoints $(\mathbf{x}_0, \mathbf{y}_0), (\mathbf{x}_1, \mathbf{y}_1)$
 - Integer coordinates: Round if endpoints were originally real-valued
 - Assume $(\mathbf{x}_0, \mathbf{y}_0)$ is to the left of $(\mathbf{x}_1, \mathbf{y}_1)$: Swap if they aren't

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2. Then we can compute slope:

$$m = dy/dx = (y_1 - y_0) / (x_1 - x_0)$$

DDA: Algorithm

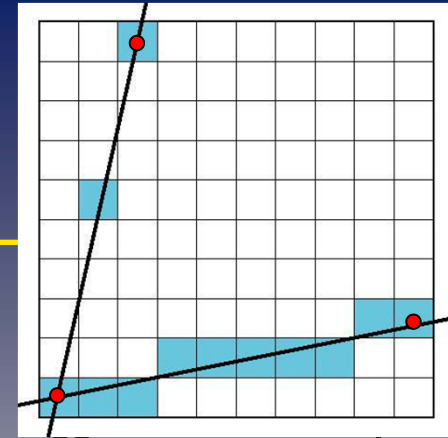
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3. Iterate

DDA: Algorithm



3. Iterate

- If $|\mathbf{m}| \leq 1$: Iterate integer \mathbf{x} from \mathbf{x}_0 to \mathbf{x}_1 , incrementing by 1 each step
 - Initialize real $\mathbf{y} = \mathbf{y}_0$
 - At each step, $\mathbf{y} += \mathbf{m}$, and plot point $(\mathbf{x}, \text{round}(\mathbf{y}))$
- Else $|\mathbf{m}| > 1$: Iterate integer \mathbf{y} from \mathbf{y}_0 to \mathbf{y}_1 , incrementing (or decrementing) by 1
 - Initialize real $\mathbf{x} = \mathbf{x}_0$
 - At each step, $\mathbf{x} += 1/\mathbf{m}$, and plot $(\text{round}(\mathbf{x}), \mathbf{y})$

Midpoint/Bresenham's line drawing

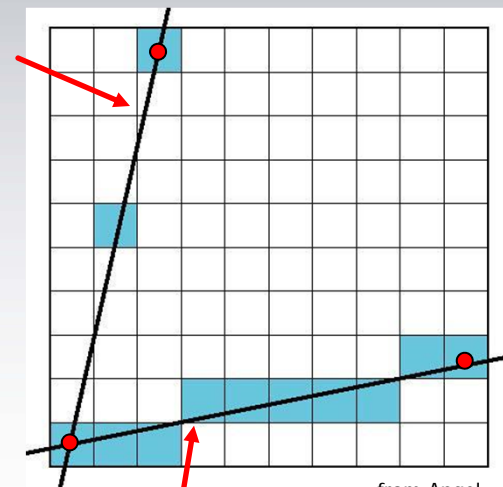
- DDA is somewhat slow
 - Floating-point calculations, rounding are relatively expensive
- Big idea: Avoid rounding, do everything with integer arithmetic for speed
- Assume slope between 0 and 1
 - Again, handle lines with other slopes by using symmetry

Midpoint line drawing: Line equation

- Recall that the slope-intercept form of the line is $y = (dy/dx)x + b$
- Multiplying through by dx , we can rearrange this in **implicit form**:

$$F(x, y) = dy x - dx y + dx b = 0$$

$$9x - 2y = 0$$



from Angel

$$2x - 9y = 0$$

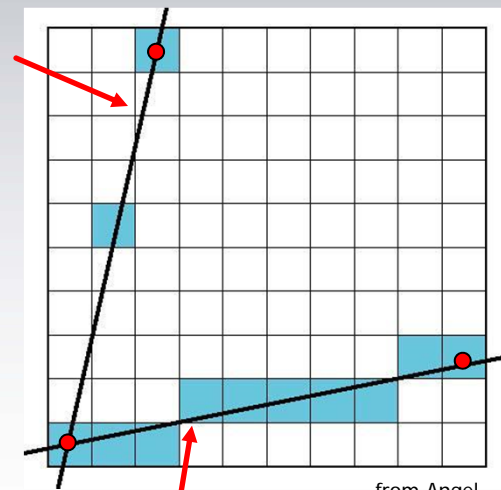
Midpoint line drawing: Line equation

- Recall that the slope-intercept form of the line is $y = (dy/dx)x + b$
- Multiplying through by dx , we can rearrange this in **implicit form**:

$$F(x, y) = dy x - dx y + dx b = 0$$

- F is:
 - Zero for points on the line
 - Positive for points **below** the line (**right** if slope > 1)
 - Negative for points **above** the line (**left** if slope > 1)
- Examples: $(0, 1)$, $(1, 0)$, etc.

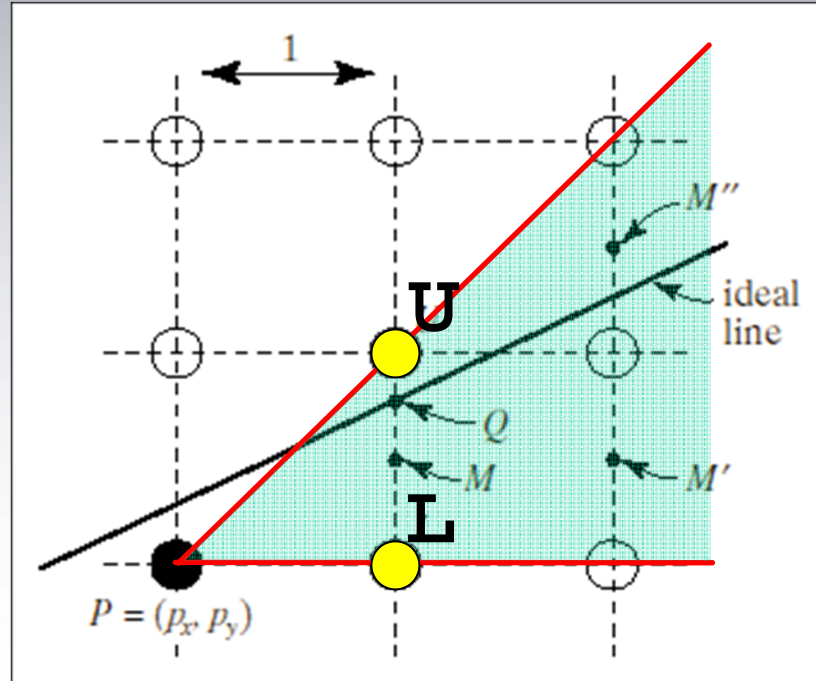
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$$2x - 9y = 0$$

Midpoint line drawing: The Decision

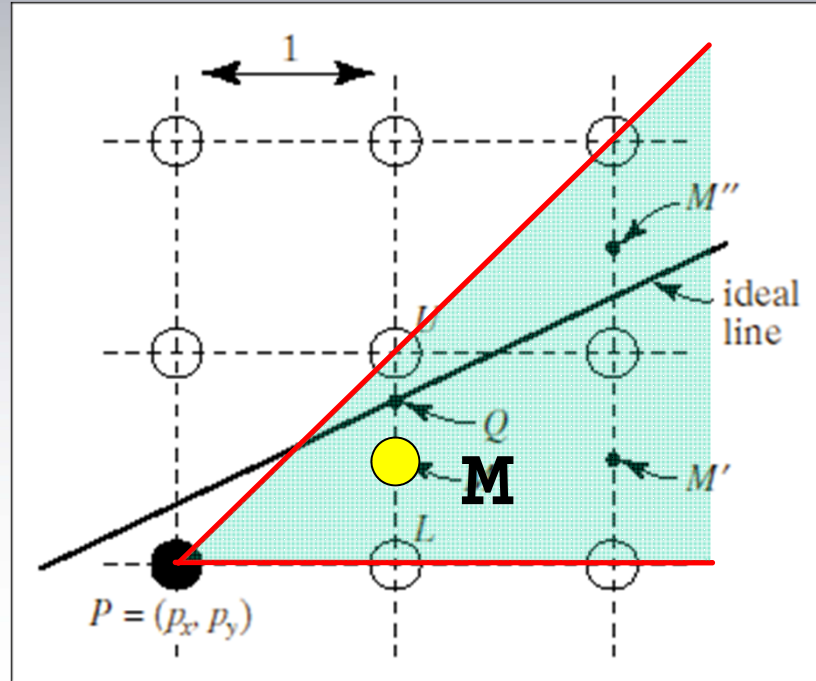
- Given our assumptions about the slope, after drawing (\mathbf{x}, \mathbf{y}) the only choice for the next pixel is between the upper pixel $\mathbf{U} = (\mathbf{x}+1, \mathbf{y}+1)$ and the lower one $\mathbf{L} = (\mathbf{x}+1, \mathbf{y})$
- We want to draw the one closest to the "ideal" line



from Hill

Midpoint line drawing: Midpoint decision

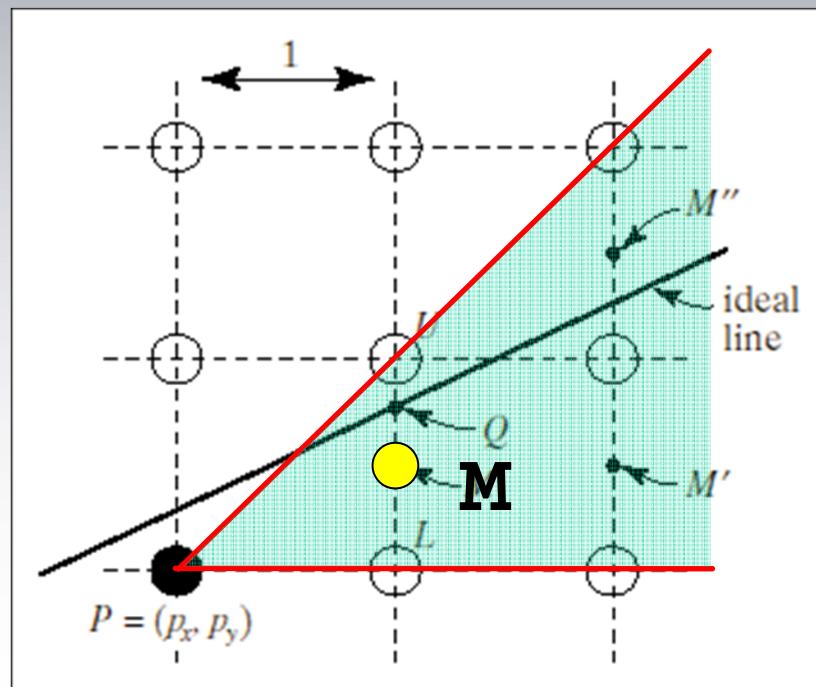
- After drawing (\mathbf{x}, \mathbf{y}) , in order to choose the next pixel to draw we consider the **midpoint** $\mathbf{M} = (\mathbf{x}+1, \mathbf{y}+0.5)$
 - If \mathbf{M} is **on** the line, then \mathbf{U} and \mathbf{L} are equidistant from the line



from Hill

Midpoint line drawing: Midpoint decision

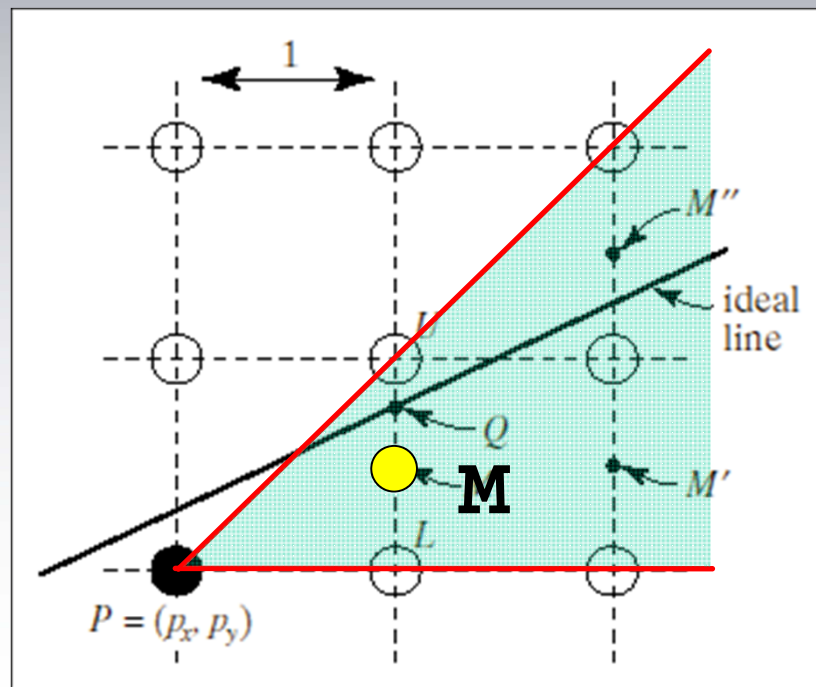
- After drawing (x, y) , in order to choose the next pixel to draw we consider the **midpoint** $\mathbf{M} = (x+1, y+0.5)$
 - If \mathbf{M} is **on** the line, then \mathbf{U} and \mathbf{L} are equidistant from the line
 - If \mathbf{M} is **below** the line, pixel \mathbf{U} is closer to the line than pixel \mathbf{L}



from Hill

Midpoint line drawing: Midpoint decision

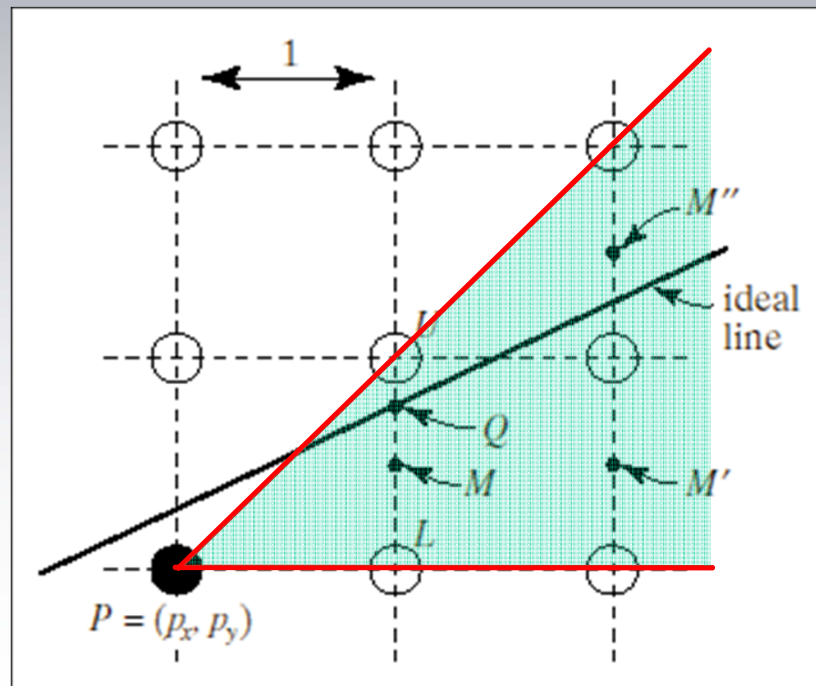
- After drawing (x, y) , in order to choose the next pixel to draw we consider the **midpoint $M = (x+1, y+0.5)$**
 - If **M** is **on** the line, then **U** and **L** are equidistant from the line
 - If **M** is **below** the line, pixel **U** is closer to the line than pixel **L**
 - If **M** is **above** the line, then **L** is closer than **U**



from Hill

Midpoint line drawing: Midpoint decision

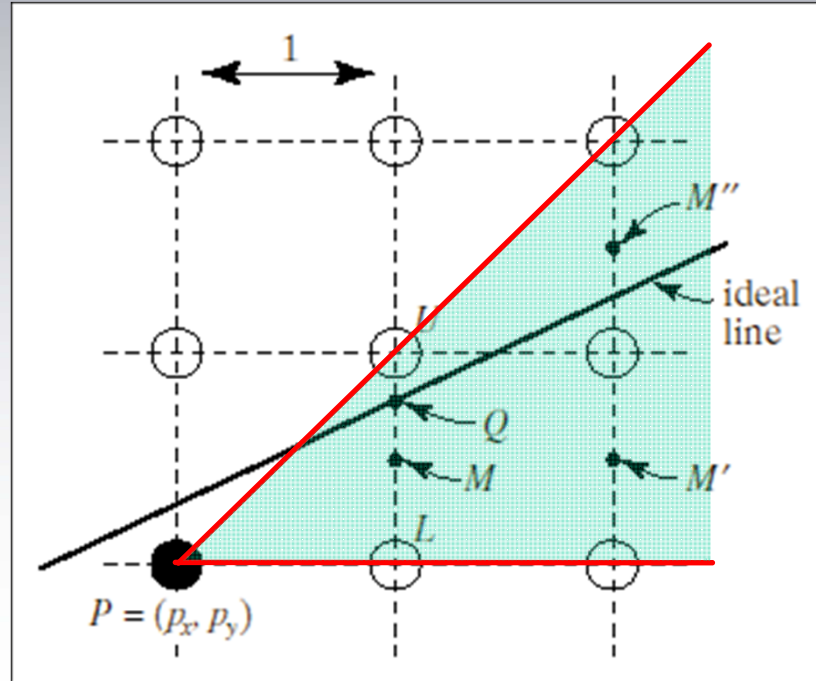
- So F is a **decision function** about which pixel to draw:
 - If $F(M) = F(x+1, y+0.5) > 0$ (M below the line), pick U
 - If $F(M) = F(x+1, y+0.5) \leq 0$ (M above or on line), pick L



from Hill

Midpoint line drawing: Implementation

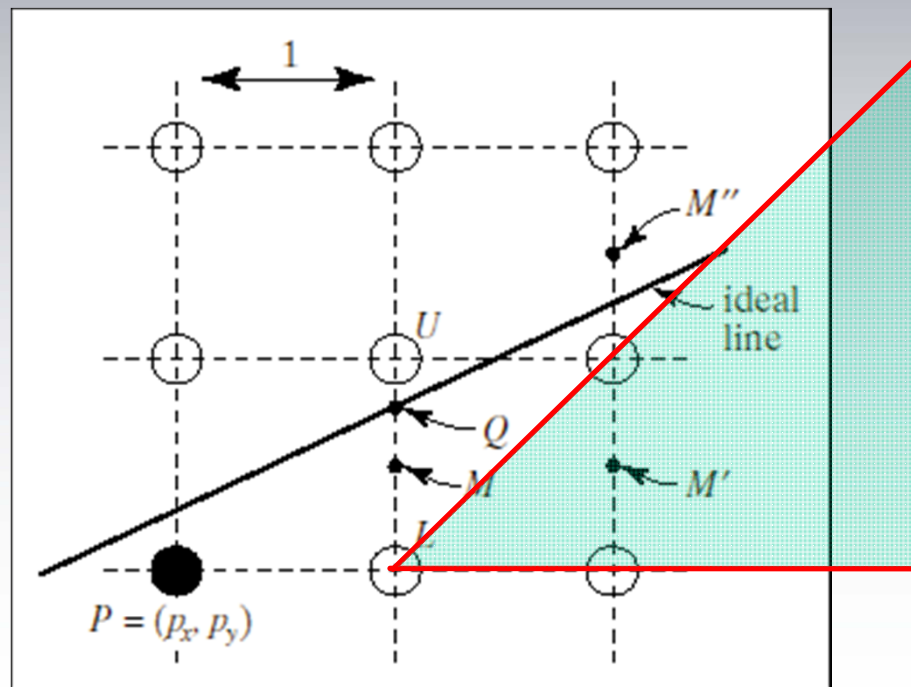
- Key efficiency insight: \mathbf{F} does not have to be fully evaluated every step
- Suppose we do the full evaluation once and get $\mathbf{F}(\mathbf{x}+1, \mathbf{y}+0.5)$



from Hill

Midpoint line drawing: Implementation

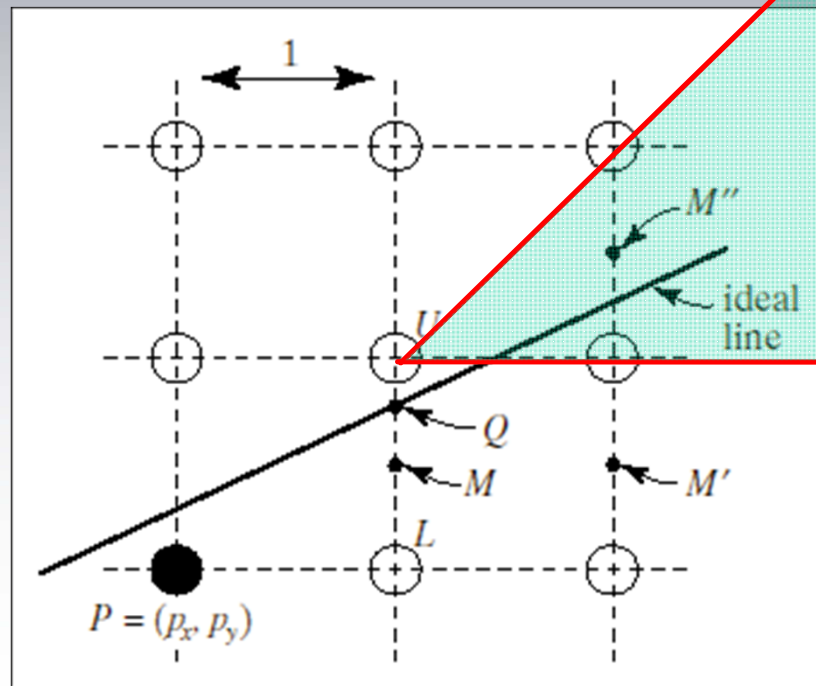
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from Hill

Midpoint line drawing: Implementation

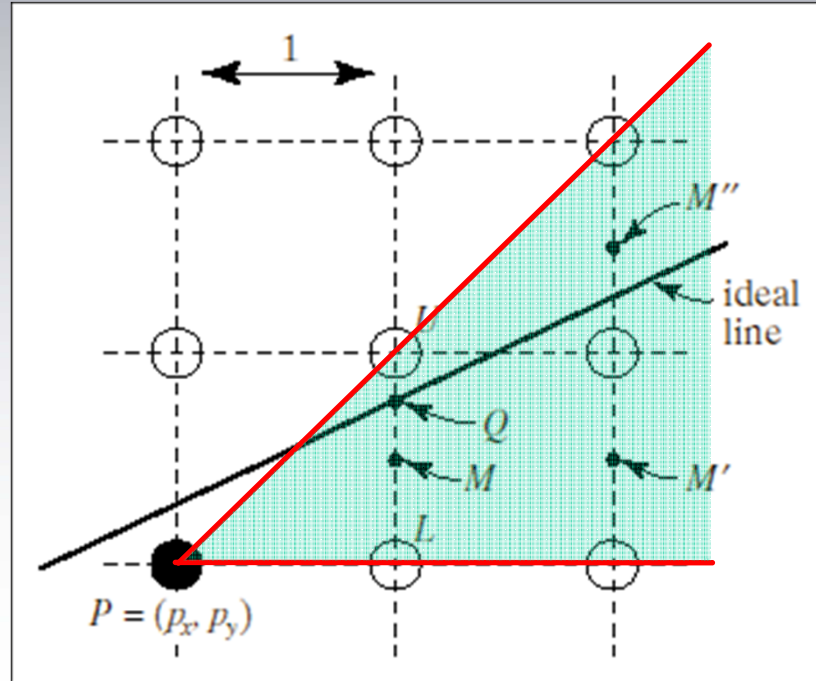
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 - If we choose \mathbf{L} , next midpoint to evaluate \mathbf{M}' is at $\mathbf{F}(\mathbf{x}+2, \mathbf{y}+0.5)$
 - If we choose \mathbf{U} , next midpoint \mathbf{M}'' would be at $\mathbf{F}(\mathbf{x}+2, \mathbf{y}+1.5)$



from Hill

Midpoint line drawing: Implementation

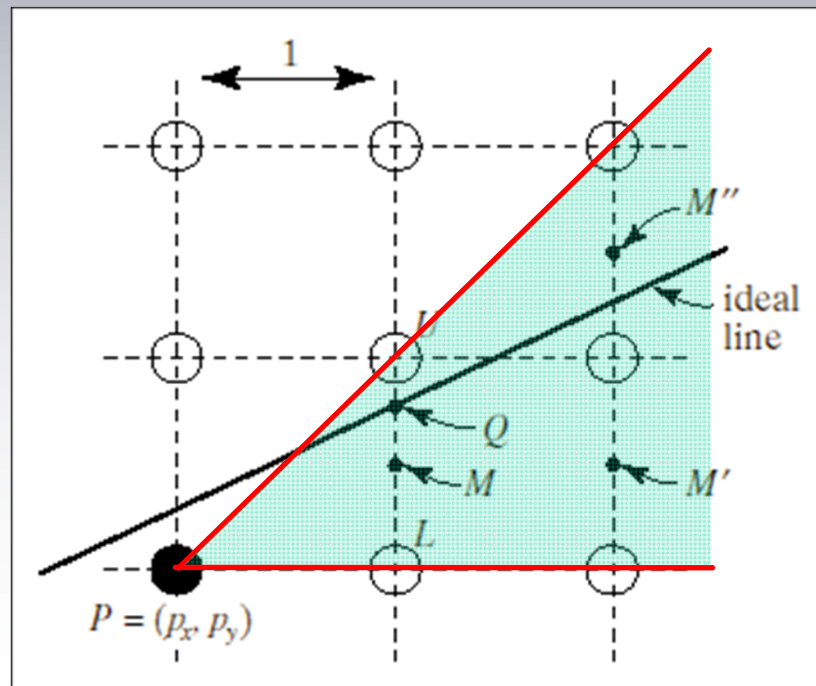
- Expanding these out using $F(x, y) = dy \cdot x - dx \cdot y + dx \cdot b$:
 - $F_M = F(x + 1, y + 0.5) = dy(x + 1) - dx(y + 0.5) + dx \cdot b$
 - $F_{M'} = F(x + 2, y + 0.5) = dy(x + 2) - dx(y + 0.5) + dx \cdot b$
 - $F_{M''} = F(x + 2, y + 1.5) = dy(x + 2) - dx(y + 1.5) + dx \cdot b$
- Note that $F_{M'} = F_M + dy$ and $F_{M''} = F_M + dy - dx$



from Hill

Midpoint line drawing: Implementation

- Expanding these out using $F(x, y) = dy \cdot x - dx \cdot y + dx \cdot b$:
 - $F_M = F(x + 1, y + 0.5) = dy(x + 1) - dx(y + 0.5) + dx \cdot b$
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- Note that $F_{M'} = F_M + dy$ and $F_{M''} = F_M + dy - dx$
- So depending on whether we choose **L** or **U**, we just have to add **dy** or **dy - dx**, respectively, to the old value of **F** in order to get the new value



from Hill

Midpoint line drawing: Algorithm

- To initialize, we do a full calculation of F at the first midpoint next to the left line endpoint:

$$\begin{aligned}F(x_0 + 1, y_0 + 0.5) &= dy(x_0 + 1) - dx(y_0 + 0.5) + dx b \\ &= dy x_0 - dx y_0 + dx b + dy - 0.5 dx \\ &= F(x_0, y_0) + dy - 0.5 dx\end{aligned}$$

- But $F(x_0, y_0) = 0$ since it's on the line, so our first $F = dy - 0.5 dx$
- **Only the sign matters for the decision**, so to make it an **integer value** we multiply by 2 to get $2F = 2 dy - dx$
- To update, keep current values for x and y and a running total for F :
 - When **L** is chosen: $F += 2dy$ and $x++$
 - When **U** is chosen: $F += 2(dy - dx)$ and $x++, y++$

Line drawing speed

- 100,000 random lines in 500 x 500 window (average of 5 runs)
- DDA: 6.8 seconds
- Midpoint: 2.5 seconds
- OpenGL using **GL_LINES** (in software): 1.6 seconds

Extensions

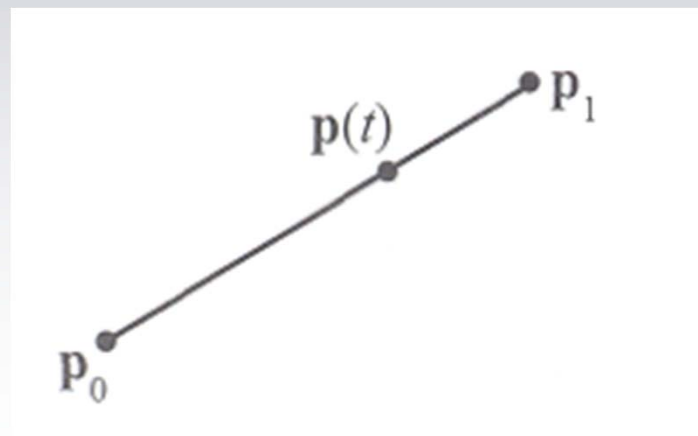
- How to draw thick (>1 pixel wide) lines?
 - Nested Bresenham's (perpendicular to main line at each step, or series of parallel lines)
- Stippled/dashed lines
 - Add state (pen up/down) inside loop
 - OpenGL: `glLineStipple(factor, pattern), glEnable(GL_LINE_STIPPLE)`

PATTERN	FACTOR	
0x00FF	1	_____
0x00FF	2	_____
0x0C0F	1	_ _ _ _ _
0x0C0F	3	_ _ _ _ _
0xAAAA	1	- - - - -
0xAAAA	2	- - - - -
0xAAAA	3	_ _ _ _ _
0xAAAA	4	_ _ _ _ _

Blending via Linear Interpolation

- Different colors at endpoints can be blended as we rasterize: vary color with distance fraction
- Parametric definition of a line segment:

$$\begin{aligned}\mathbf{p}(t) &= \mathbf{p}_0 + t(\mathbf{p}_1 - \mathbf{p}_0), \text{ where } t \in [0, 1] \\ &= \mathbf{p}_0 - t \mathbf{p}_0 + t \mathbf{p}_1 \\ &= (1 - t)\mathbf{p}_0 + t \mathbf{p}_1\end{aligned}$$

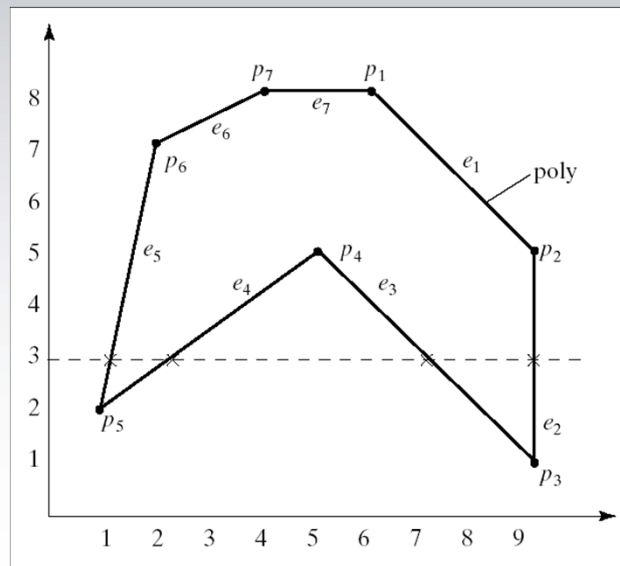


like a "blend" of the two endpoints

from Akenine-Möller & Haines

Polygon Rasterization

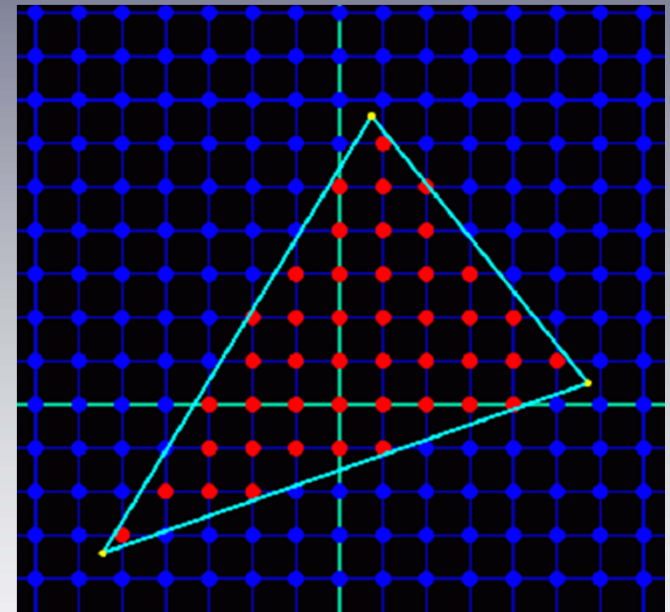
- Given a set of vertices, want to fill the interior
- Basic procedure:
 - Iterate over **scan lines** between top and bottom vertex
 - For each scan line, find all intersections with polygon edges
 - Sort intersections by x-value and fill pixel runs between even-odd pairs of intersections



from Hill

Rasterizing triangles

- Special case of polygon rasterization
 - Exactly two **active** edges at all times
- One method:
 - Fill scanline table between top and bottom vertex with leftmost and rightmost side by using DDA or midpoint algorithm to follow edges
 - Traverse table scanline by scanline, fill run from left to right



General polygons → triangles

- Can convert arbitrary polygon to set of triangles via **tessellation** (e.g., **gluTess*()** functions)

