

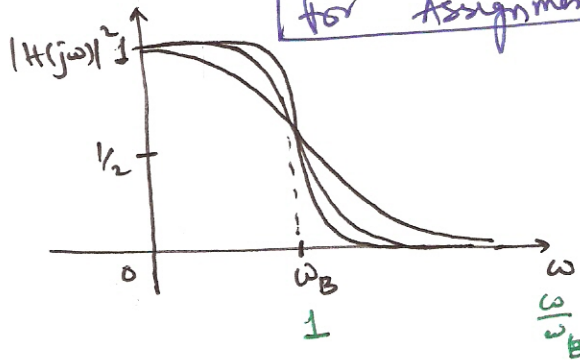
Butterworth LP filter Example

(A1)

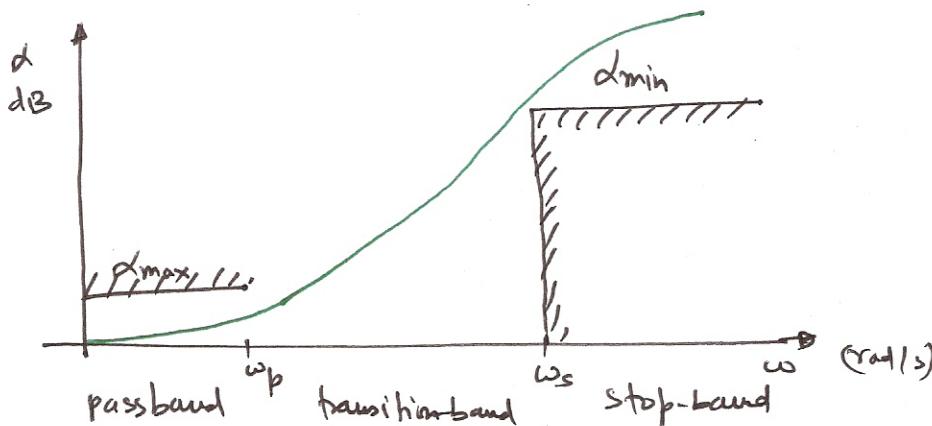
for Assignment # 1

$$H(s) = \frac{L}{1 + \left(\frac{s}{\omega_B}\right)^n}$$

$$\Rightarrow |H(j\omega)|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_B}\right)^{2n}}$$



← normalized w.r.t ω_B .



Attenuation:

$$\alpha(\omega) = -20 \log |H(\omega)|$$

$$|H(\omega)| = 10^{-\frac{\alpha(\omega)}{20}}$$

Define passband corner at $\omega=1 \Rightarrow$ normalize ω as $\frac{\omega}{\omega_p}$

$\epsilon \rightarrow$ "ripple width"

$$\Rightarrow |H(j\omega)|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_p}\right)^{2n}} = \frac{1}{1 + \epsilon^2 \left(\frac{\omega}{\omega_p}\right)^{2n}} \quad \leftarrow \text{renormalized}$$

at $\frac{\omega}{\omega_p} = 1 \Rightarrow$

$$|H(j1)|^2 = \frac{1}{1 + \left(\frac{\omega_p}{\omega_p}\right)^{2n}} = \frac{1}{1 + \epsilon^2}$$

$$\Rightarrow \epsilon = \left(\frac{\omega_p}{\omega_B}\right)^n$$

$$\Rightarrow \boxed{\omega_B = \epsilon^{-1/n} \omega_p} \rightarrow (1)$$

\Rightarrow At the passband corner

$$\alpha_{\max} = 10 \log(1 + \epsilon^2)$$

$$\Rightarrow \boxed{\epsilon^2 = 10^{\frac{0.1 \alpha_{\max}}{-1}} - 1} \rightarrow (2)$$

At the passband:

$$d_{min} = 10 \log (1 + \epsilon^2 \omega_s^{2n}) \longrightarrow \textcircled{3}$$

from $\textcircled{2}$ and $\textcircled{3}$

$$d_{min} = 10 \log [1 + (10^{\frac{0.1 d_{max}}{-1}}) \omega_s^{2n}]$$

$$\Rightarrow \boxed{\omega_s^{2n} = \frac{10^{\frac{0.1 d_{min}}{-1}} - 1}{10^{\frac{0.1 d_{max}}{-1}} - 1}}$$

$$\Rightarrow \boxed{n = \frac{\log \left[\frac{10^{\frac{0.1 d_{min}}{-1}} - 1}{10^{\frac{0.1 d_{max}}{-1}} - 1} \right]}{2 \log \omega_s}} \longrightarrow \textcircled{4} \leftarrow \text{gives the order.}$$

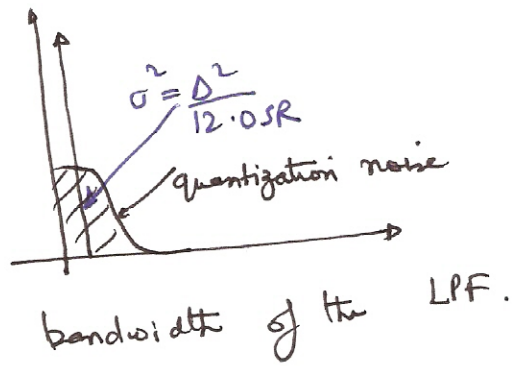
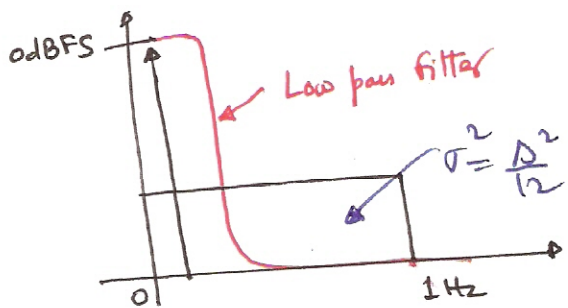
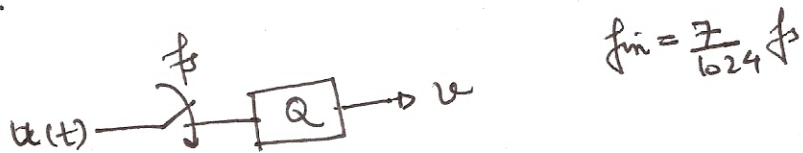
Design procedure:

- ① using $\textcircled{3}$ ϵ^2 ② determine parameter $\epsilon \rightarrow$ sets d_{max}
- ② using ϵ^2 ④ calculate the degree n and round it to the next largest integer
- ③ Calculate the normalizing frequency $\omega_B = \epsilon^{-1/n} \omega_p$
 \hookrightarrow 3dB Bandwidth

Matlab functions:

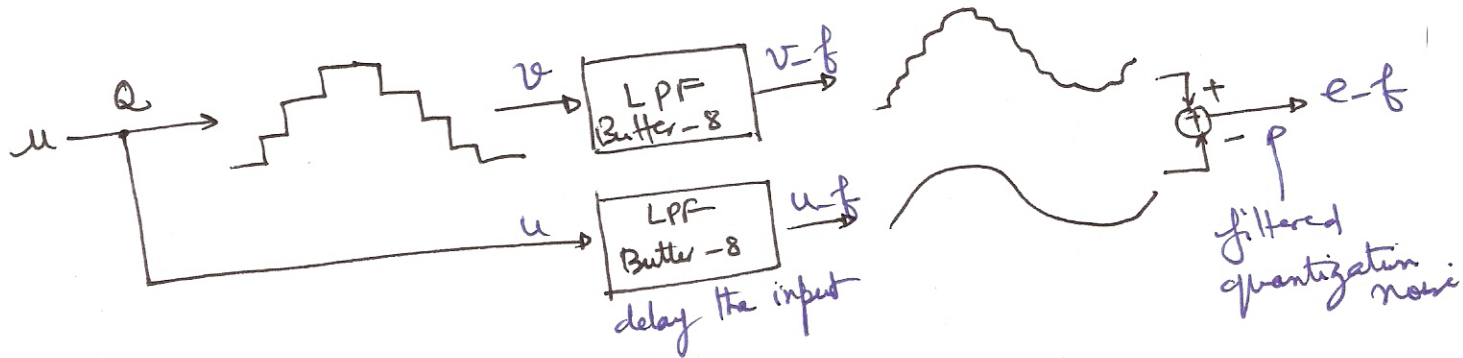
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Oversampling:



Noise now confined to the bandwidth of the LPF.
 Use 8th order Butterworth filter

see Matlab file: Oversampling.m

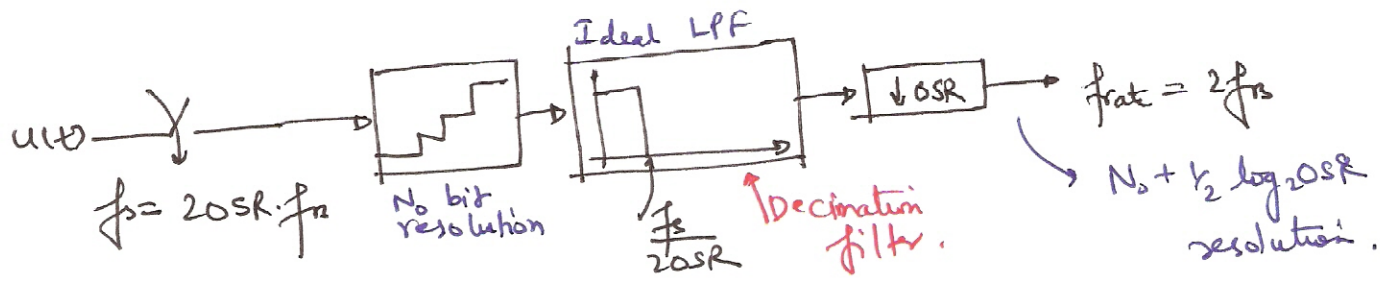


Bandwidth = $\frac{f_s}{2 \cdot OSR}$

oversampling \Rightarrow SNR has increased by a factor close to the oversampling ratio, OSR.

$N_{inc} = 0.5 \log_2 OSR$

1/2 bit increase per doubling in OSR.

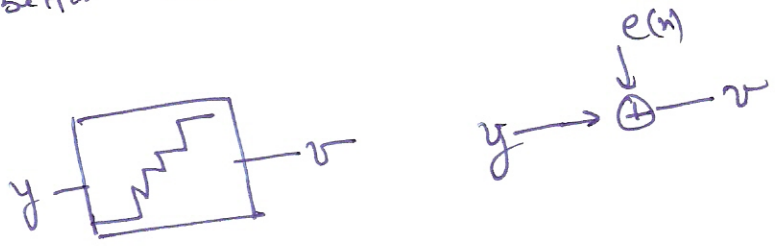


$$SNR = 10 \log_{10} \left(\frac{A^2/2}{\frac{DL}{12 \cdot OSR}} \right) = \frac{(2^{N+1/2})^2}{\left(\frac{DL}{12 \cdot OSR} \right)}$$

$$= 10 \log_{10} \left(\frac{3}{2} \cdot 2^{2N} \cdot OSR \right)$$

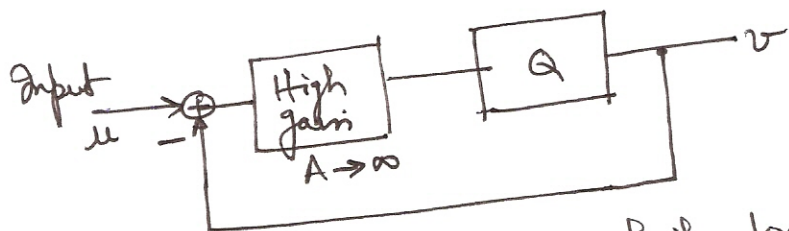
$$SNR = 6.02N + 1.76 + \boxed{10 \log_{10} OSR} \leftarrow \text{Extra term}$$

- End to end system looks like a Nyquist rate ADC with effective resolution $N + \frac{1}{2} \log_2 OSR$.
 ↳ uses only N_0 bit quantizer (cheap quantizer)
- Trading analog complexity with digital complexity.
 - Digital Decimation filter is automatically synthesized
 ↳ Variable coding
 - More effort on optimizing analog portion of the circuit.
- Can we do better than $\frac{1}{2}$ bit per doubling in OSR?



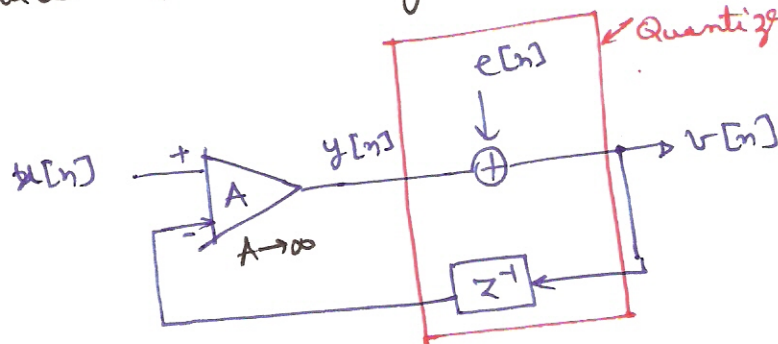
use feedback to reduce error $e(n)$?

③



reduce $|u-v|$ using high loop gain?

Consider



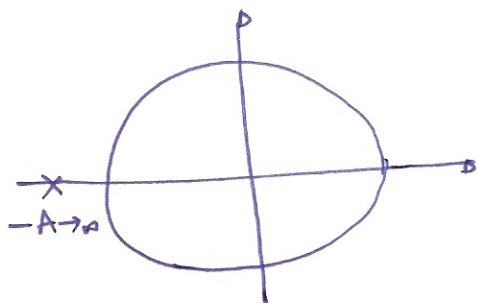
will this feedback scheme work in this sampled-data system?

$$(U(z) - z^{-1}V(z))A + E(z) = V(z)$$

$$AV(z) + E(z) = V(z)(1 + Az^{-1})$$

$$\Rightarrow V(z) = \left(\frac{A}{1 + Az^{-1}}\right) X(z) + \frac{E(z)}{1 + Az^{-1}}$$

\Rightarrow system pole at $-A \rightarrow -\infty$
 \Rightarrow system is not stable at all!



error $|u-v| \rightarrow \infty$ as $A \rightarrow \infty$
 error $|u-v|$ blows up,

Ex. $v[0] = 0$

\Rightarrow ex: $|u-v|_0 = -1 \Rightarrow y = -100$

$\Rightarrow |u-v|_1 = -100 \Rightarrow y = +10^4$

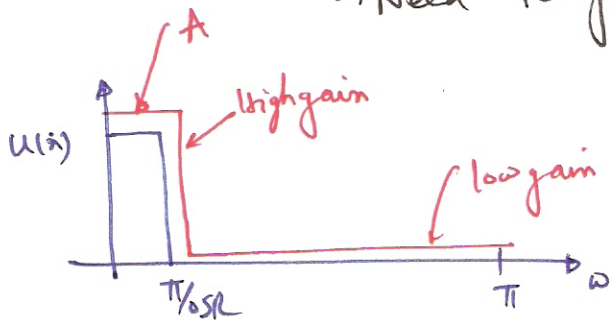
The geometric series explodes.

Doesn't work at all!

Too much delay in the loop causes instability.

→ A constant large gain doesn't work.

↳ Need to find another way to stabilize the loop.



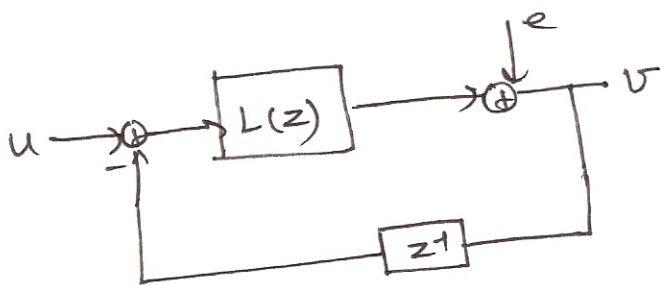
~~U(t)~~ $u(t)$ has low frequency content compared to f_s .

• Apply high gain at low frequencies to reduce quantization noise.

• At high frequencies, keep the gain low to stabilize the loop.

→ Use frequency dependent gain.

• Replace A by $L(z)$ ⇒ Loop filter



$$|L(z)| \rightarrow \infty \text{ at } z=1$$

$$\Rightarrow |u-v| \rightarrow 0$$

* Example ⇒ 1st order : $L(z) = \frac{1}{1-z^{-1}}$

$$[U(z) - z^{-1}V(z)]L(z) + E(z) = V(z)$$

$$\Rightarrow U(z)L(z) + E(z) = V(z)(1+z^{-1})$$

$$\Rightarrow V(z) = \underbrace{\frac{L(z)}{1+z^{-1}L(z)}}_{\text{STF}(z)} U(z) + \underbrace{\frac{1}{1+z^{-1}L(z)}}_{\text{NTF}(z)} E(z)$$

uncorrelated with $U(z)$.

$$\text{STF}(z) = \frac{1}{1 + \frac{z^{-1}}{1-z^{-1}}} = 1$$

$$\text{NTF}(z) = \frac{1}{1 + \frac{z^{-1}}{1-z^{-1}}} = (1-z^{-1}) \rightarrow \text{High pass response}$$

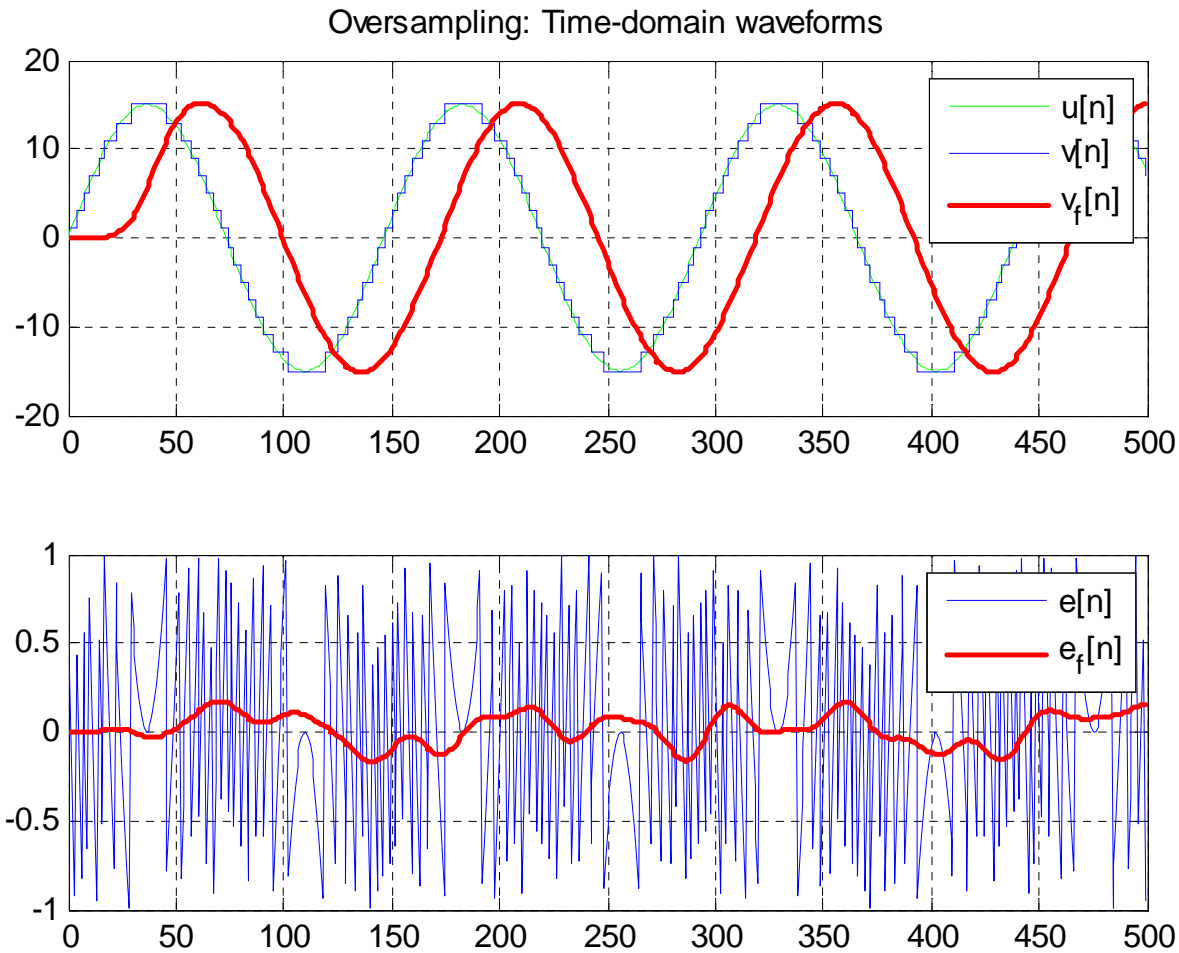
ECE 697 Delta-Sigma Converters Design

Lecture#6 Slides

Vishal Saxena

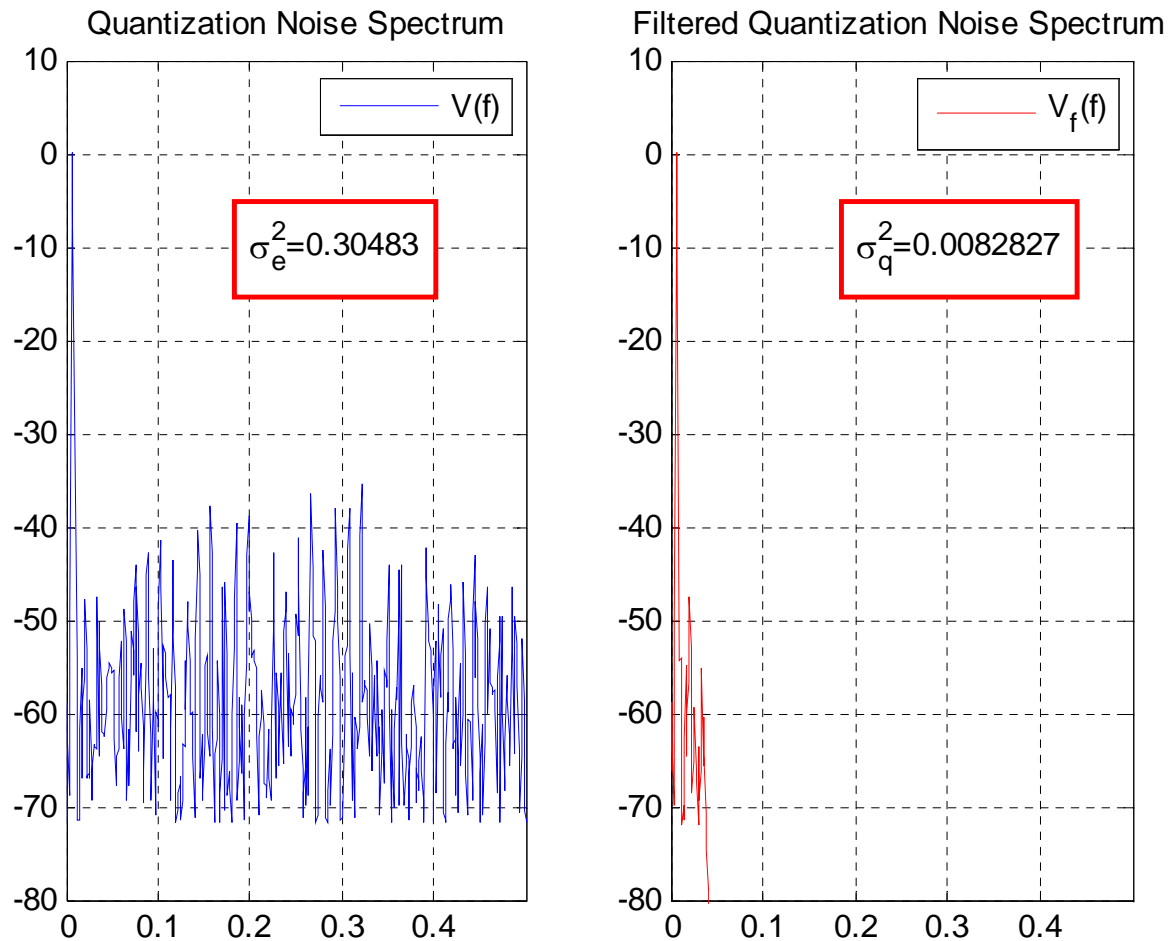
(vishalsaxena@u.boisestate.edu)

Oversampling



File: oversampling1.m

Oversampling



File: oversampling1.m