

ECE615 Mixed-Signal IC Design

Lecture 18 Slides: ΔΣ Architectures

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CIFB (Cascade of Integrators with Distributed Feedback)



□ Cascade of delaying integrators:

- Feedback coefficients a's realize the zeros of L₁ and thus the NTF and STF poles.
- Feed-in coefficients **b**'s determine zeros of L_0 and thus the STF zeros.
- State scaling coefficients c's are used for dynamic range scaling.
- Implements Butterworth NTF.

CRFB (Cascade of Resonators with Distributed Feedback)



- Combine a non-delaying and a delaying integrator with local feedback around them, to form a stable resonator.
 - Local feedback coefficients g's realize the complex zeros in the NTF.
 - Implements NTF with complex zeros. $z_i = e^{\pm j\sqrt{g_1}}$
- For odd-order, use an integrator in the front to avoid noise coupling due to g.

CIFB with Resonators



A resonator can also be formed with two delaying integrators Resonator poles outside the unit circle. $z_i = e^{1 \pm j\sqrt{g_1}}$

- Locally unstable but works fine in a stable loop-filter.
- Relaxes settling requirements on the op-amps and implements complex NTF zeros.

CIFF (Cascade of Integrators with Feed-Forward Summation)



Cascade of delaying integrators:

- Feedforward coefficients a's realize the zeros of L₁ and thus the NTF and STF poles.
- Feed-in coefficients b's determine zeros of L₀ and thus the STF zeros.
- State scaling coefficients c's are used for dynamic range scaling.
- Implements Butterworth NTF.

CRFF (Cascade of Resonators with Feed-Forward Summation)



- □ Use resonators with feedforward summation.
 - Local feedback coefficients g's realize the complex zeros in the NTF.
 - Implements NTF with complex zeros. $z_i = e^{\pm j\sqrt{g_1}}$
- For odd-order, use an integrator in the front to avoid noise coupling due to g.

CIFF with Resonators



- □ Uses resonators formed with two delaying integrators.
 - Resonator poles outside the unit circle. $z_i = e^{1 \pm j\sqrt{g_1}}$

Low-Distortion CIFF Topology



$$b_1 = b_{N+1} = 1$$
$$STF(z) = 1$$