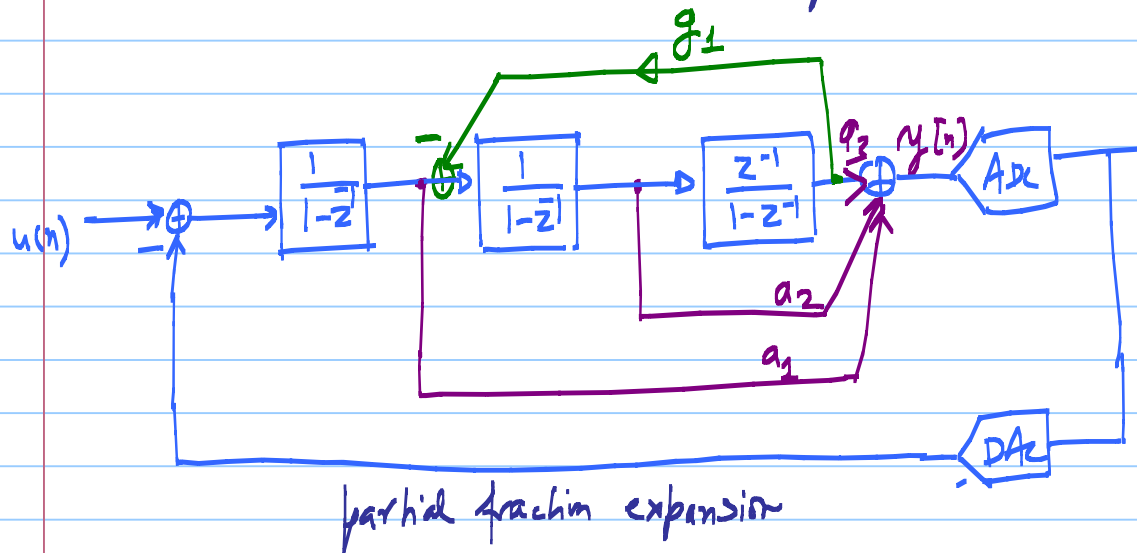


ECE 615 - Lecture 21

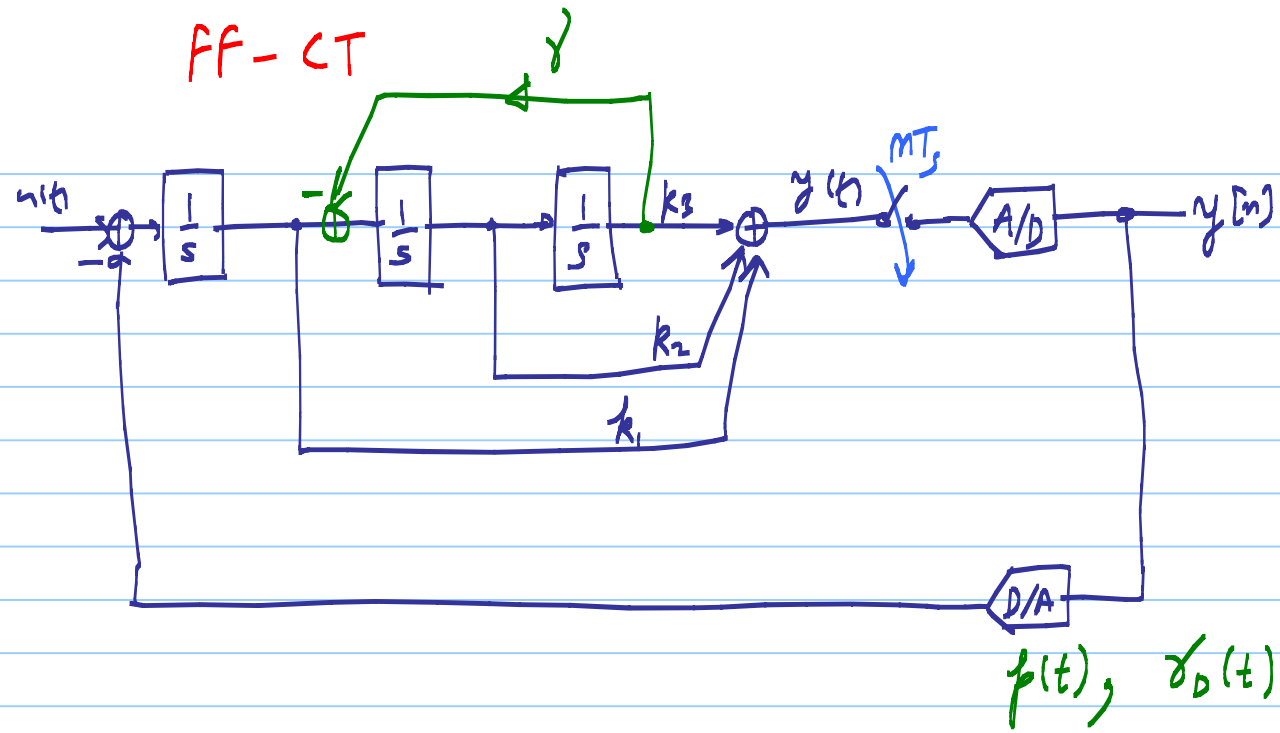
3rd-order NTF : Numerical Fitting Method \rightarrow realize $dsm_ct()$



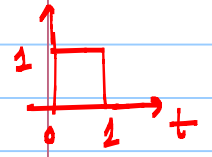
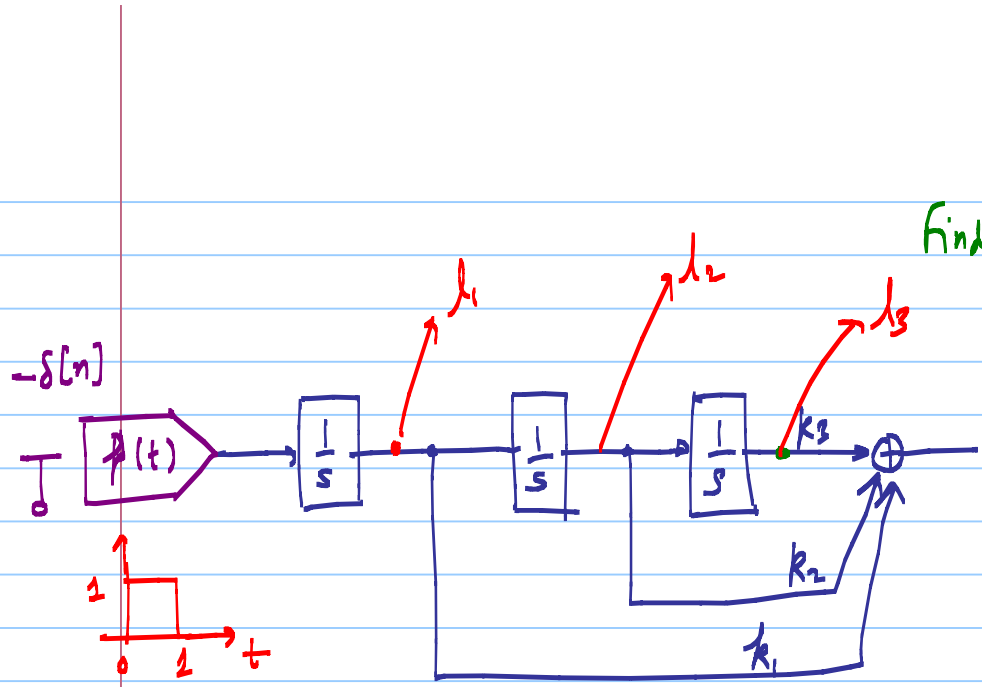
$$g_1 = 0$$

$$L(z) = \frac{1}{1-z^{-1}} + \frac{(\cdot)}{(1-z^{-1})^2} + \frac{(\cdot)}{(1-z^{-1})^3}$$

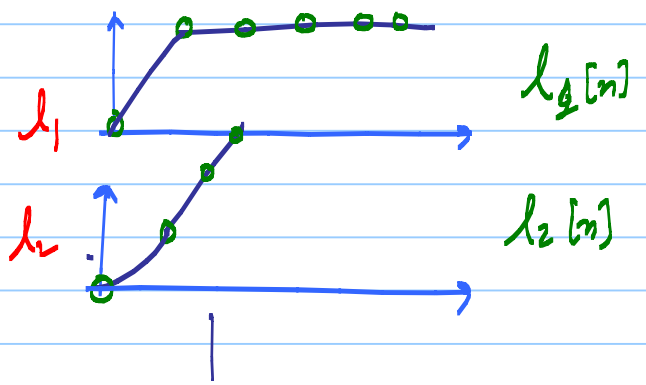
↓ Tables
L(s)

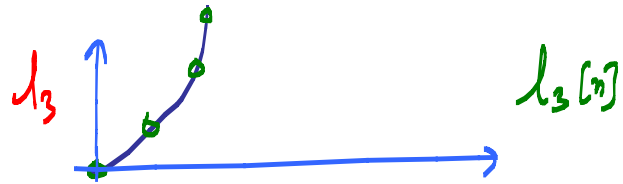


Find $k = [k_1 \ k_2 \ k_3]$



$f_s = 1 \text{ Hz}$





loop impulse response $l[n]$ = DAC pulse shape passing through the loop filter & then sampled at the clock rate (f_s).

$$\begin{array}{c} \frac{1}{s} \quad \frac{1}{s^2} \quad \frac{1}{s^3} \\ \left[\begin{array}{ccc} | & | & | \\ l_1 & l_2 & l_3 \\ | & | & | \end{array} \right] \underbrace{\begin{array}{c} k_1 \\ k_2 \\ k_3 \end{array}}_k = \underbrace{\begin{array}{c} l(\omega) \\ l(\omega) \\ l(\omega) \\ \vdots \end{array}}_l \quad N \times 1 \text{ vector}
 \end{array}$$

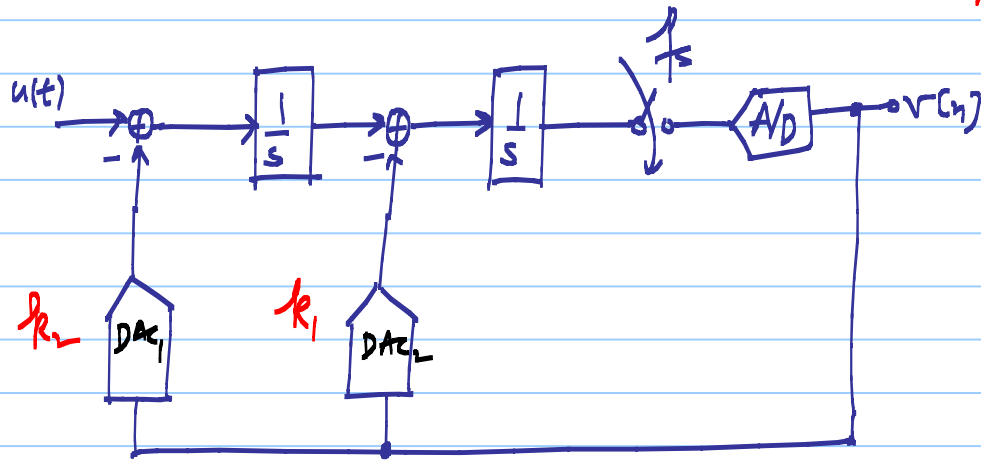
LMS filter $\Rightarrow \mathbf{k}^* = (C^T C)^{-1} C^T \mathbf{d}$

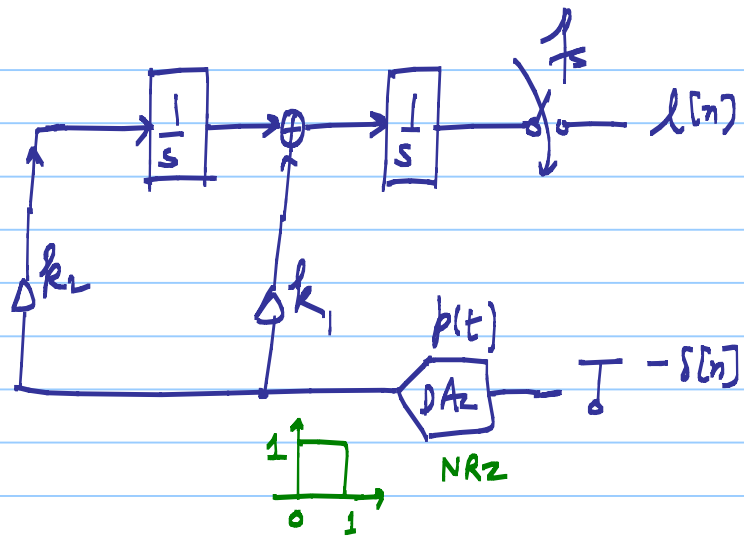
* least-squares fit to the
 $\mathbf{d}(n)$, and we obtain

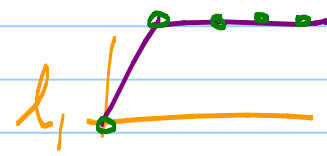
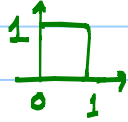
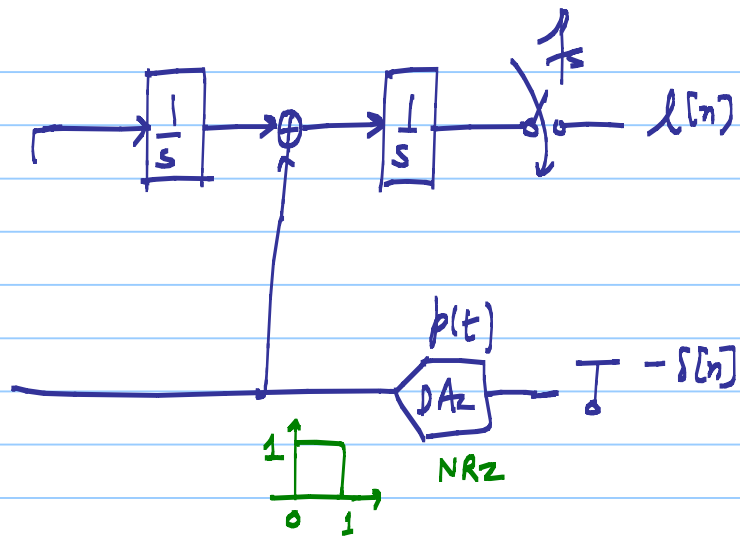
$$\begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$$

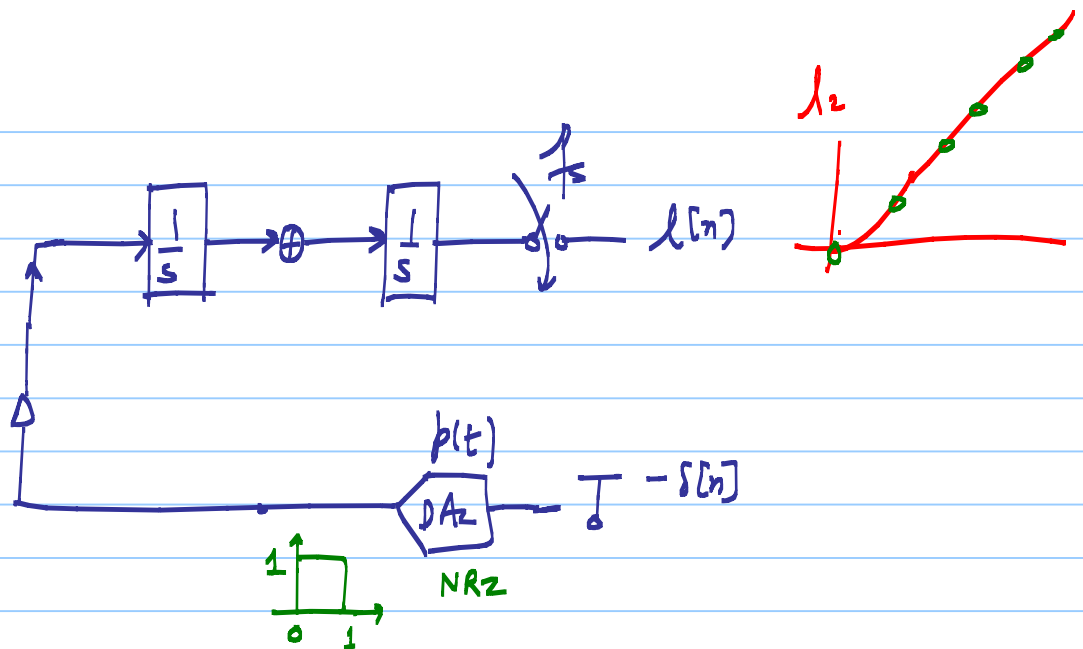
Feedback Topology (2nd-order)

$$L(s) = \frac{k_1}{s} + \frac{k_2}{s^2}$$





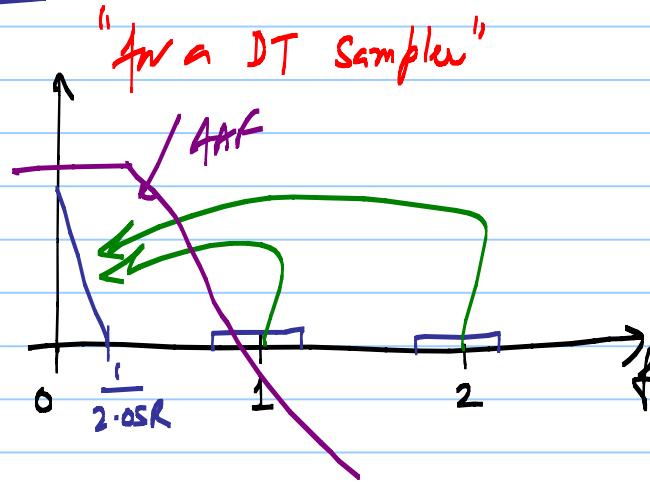
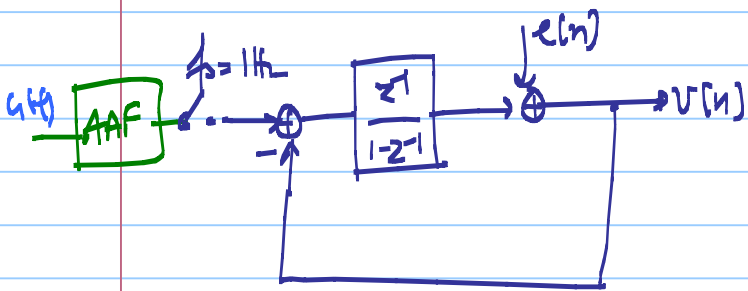
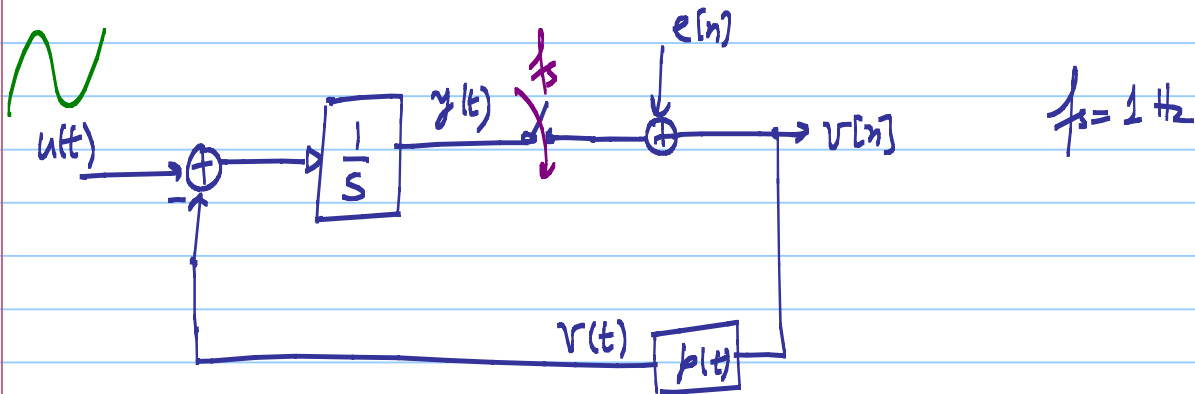


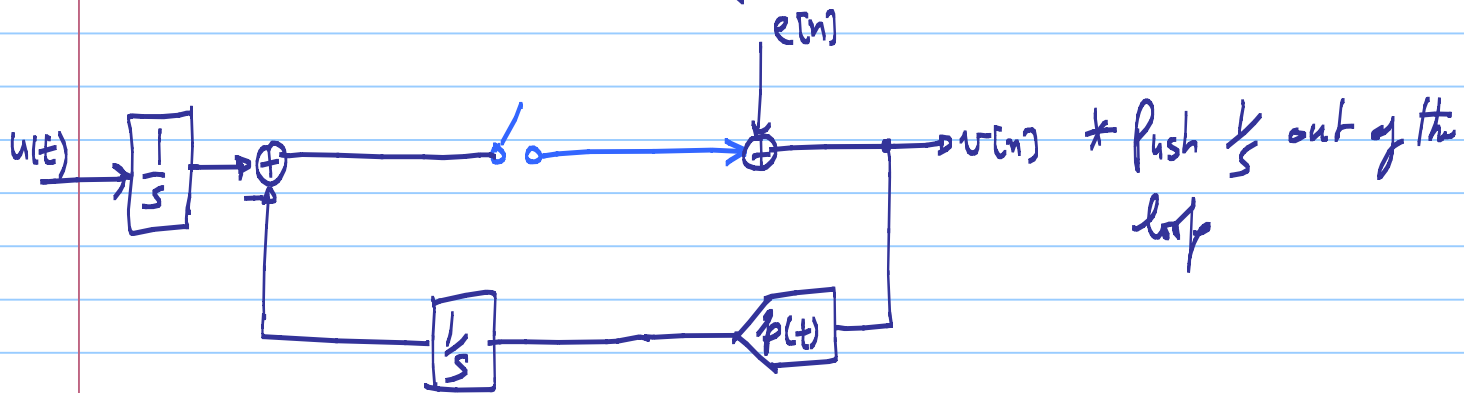
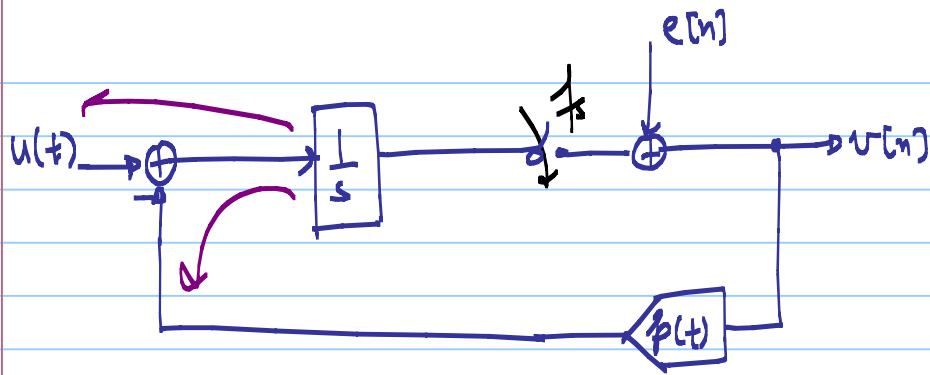


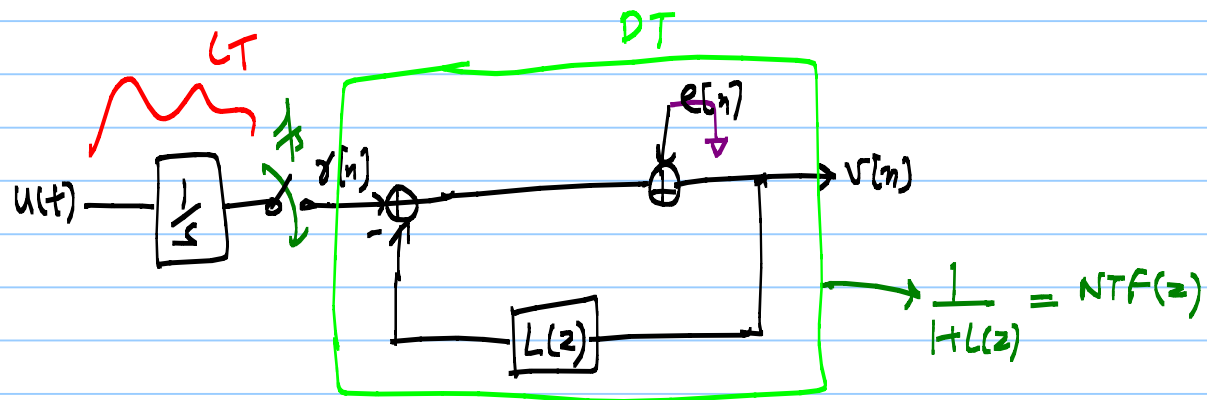
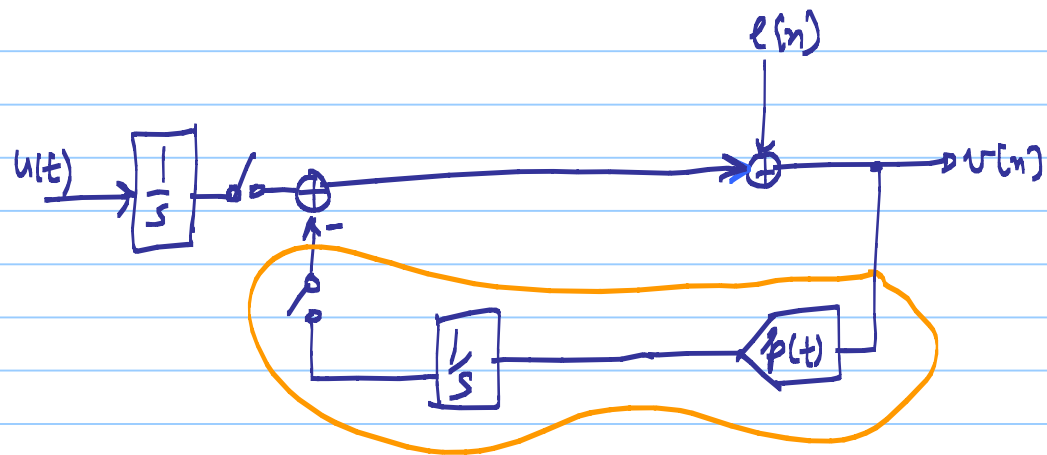
$$\begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_2 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_2 \end{bmatrix} = \begin{bmatrix} 1(0) \\ 1(1) \\ \vdots \end{bmatrix}$$

"We'll see STF later"

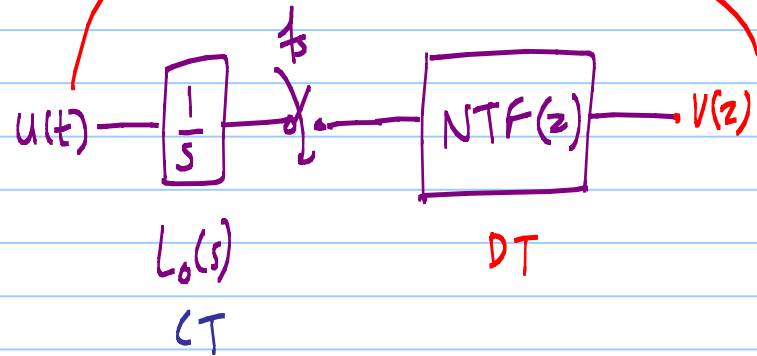
Anti-alias filtering in CT- $\Delta\Sigma_s$







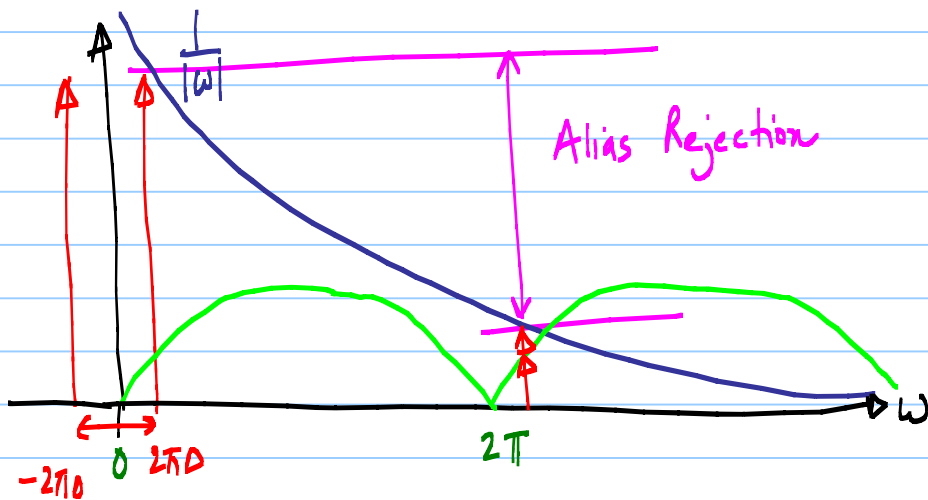
STF(j ω) \leftrightarrow CT FT



$$AAF(s) = \frac{1}{s}$$

↓

$$L_o(j\omega) = \frac{1}{j\omega}$$



* for a sinusoidal input of frequency $2\pi D$,
 the alias rejection at frequency $2\pi(1+D)$

$$\frac{1}{2\pi(1+D)}$$

$$|STF(j\omega)| = |L_0(j\omega)| \cdot |NTF(e^{j\omega})|$$

