

ECE 614 - Lecture 20

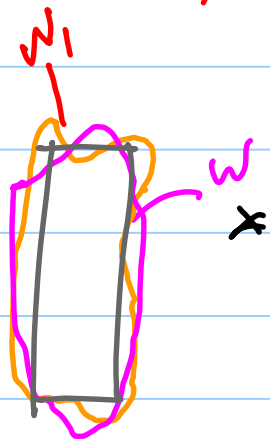
Note Title

10/30/2014

Mismatch:

①

$\Delta W, \Delta L$



photolith
induced geometric
variation

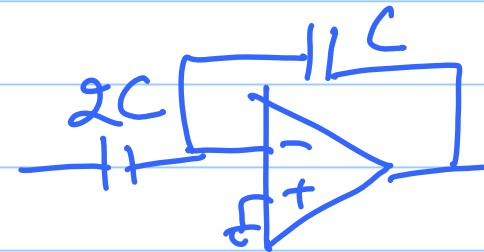
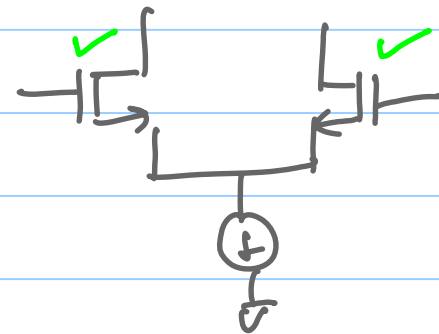
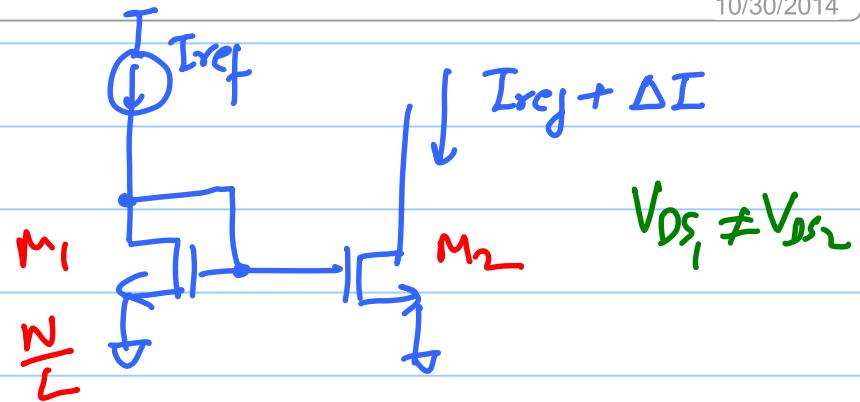
②

ΔV_{THN}



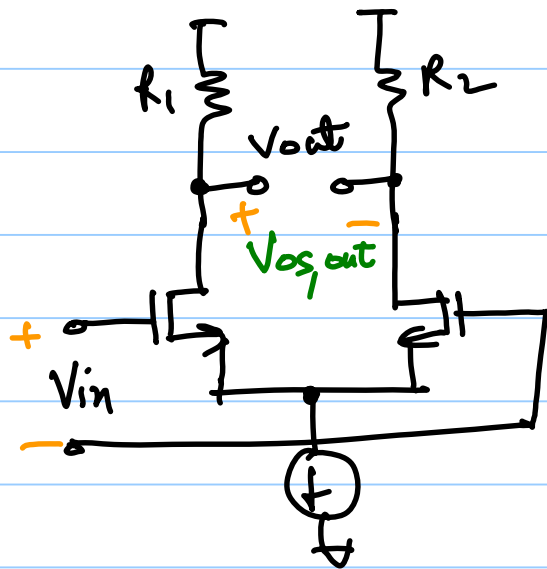
doping levels
tox variation

process gradient



Mismatch leads to $\Rightarrow$ DC offsets ✓
 $\hookrightarrow$ finite even-order distortion in FD circuits
 $\hookrightarrow$ lower CM rejection

DC offsets:



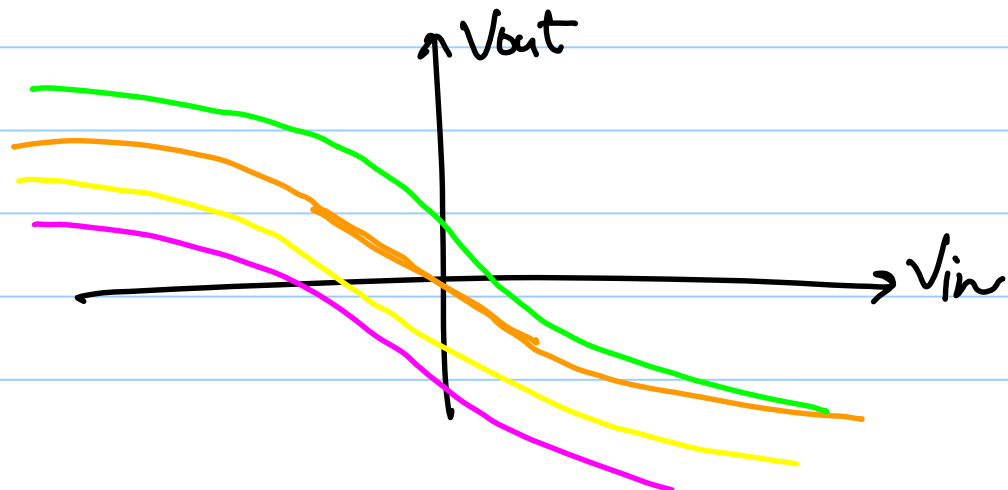
Ideally
 $V_{in} = 0$,

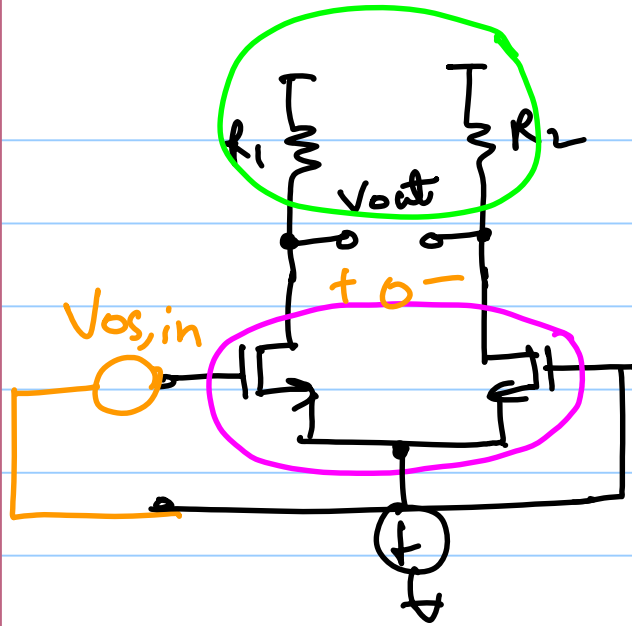
$V_{out} = 0$

with mismatch

$V_{out} = V_{os, out}$

random
but fixed
quantity





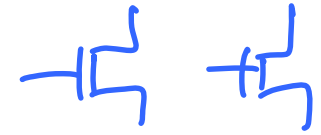
* It's more meaningful to specify the input-referred offset voltage

$$|V_{os,in}| = \frac{|V_{os,out}|}{A}$$

↑ input that forces the output to zero

$V_{os,in} \Rightarrow$ random
zero mean
 $\sqrt{V_{os}}$

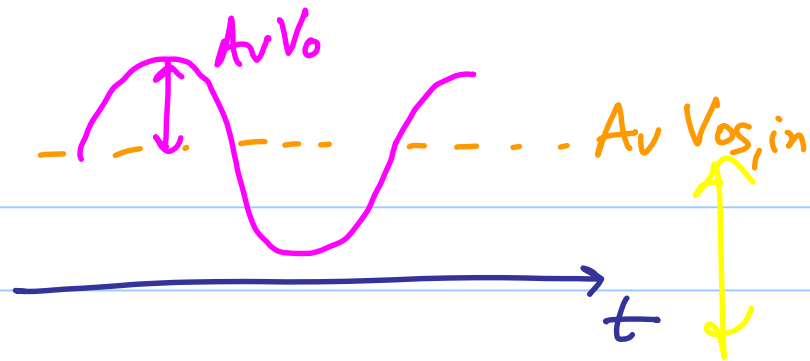
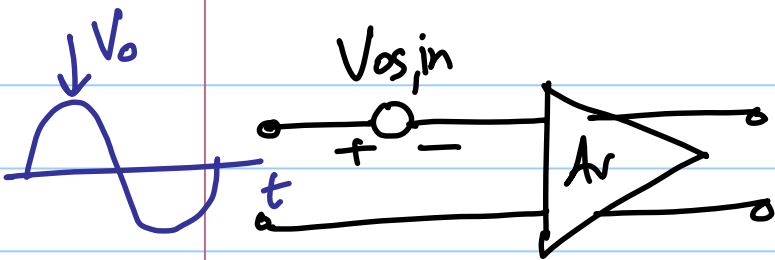
Pelgrom's paper



$$\sigma_{\Delta V_{THN}} = \frac{A_{V_{THN}}}{\sqrt{WL}} \quad \text{Area}$$

$$\sigma_{\Delta (\mu_n C_{ox} \frac{W}{L})} = \frac{A_k}{\sqrt{WL}}$$

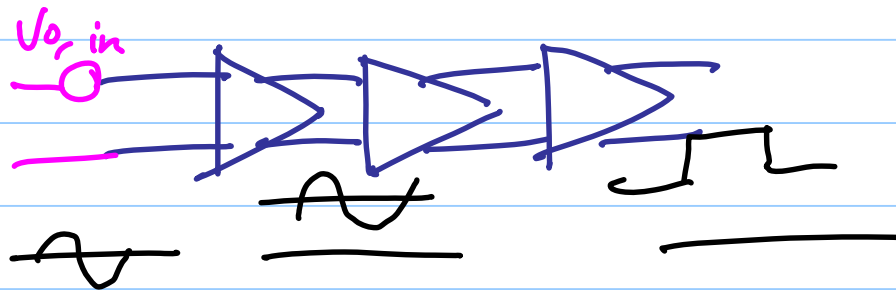
more mismatch as $W, L \downarrow$



* output contains amplified $V_{Os,in}$

①

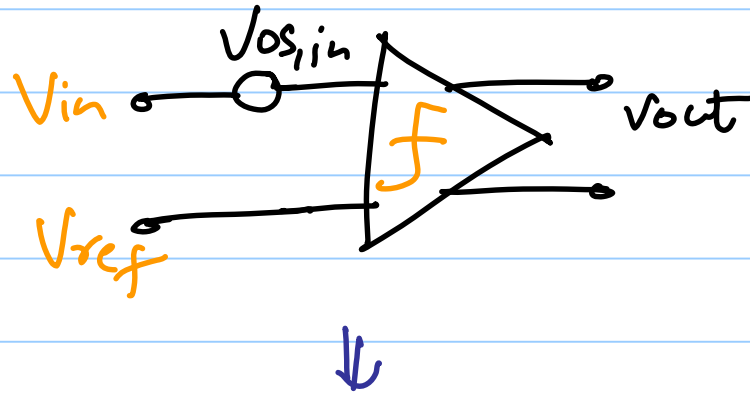
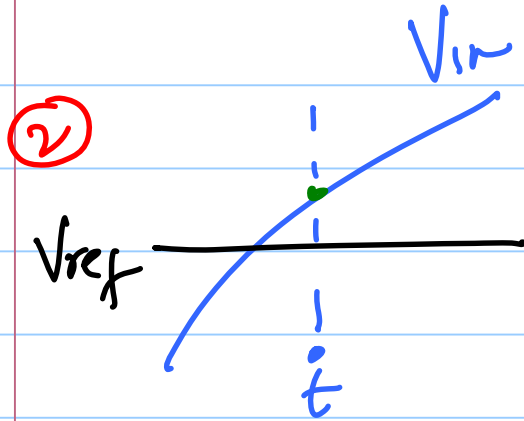
Direct coupled amplifier stages



60dB gain

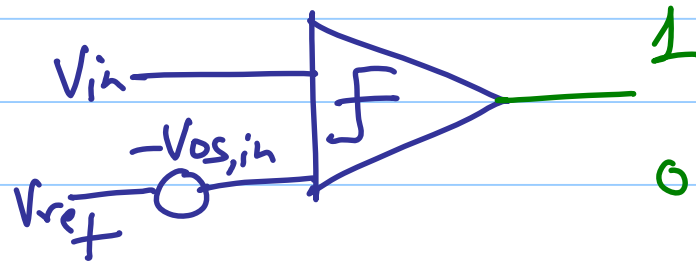
The offset can saturate the later stages

$\Rightarrow$ need to cancel offset

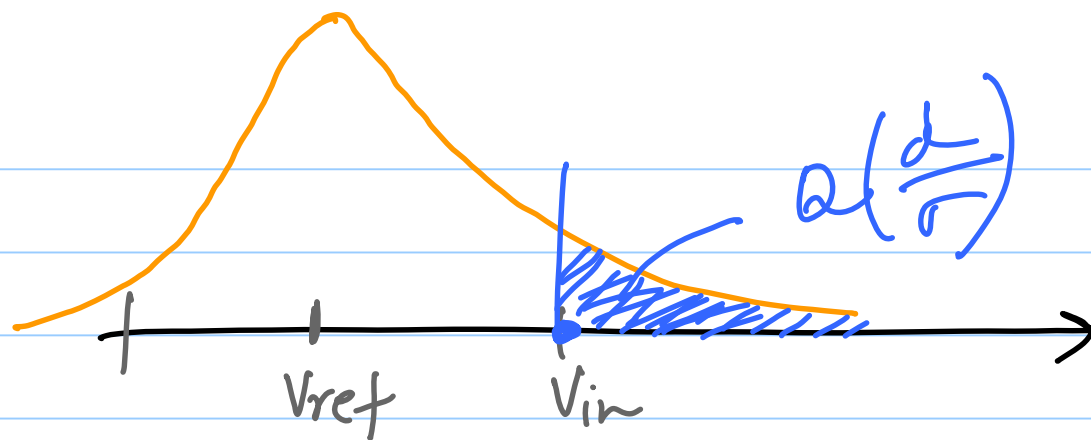


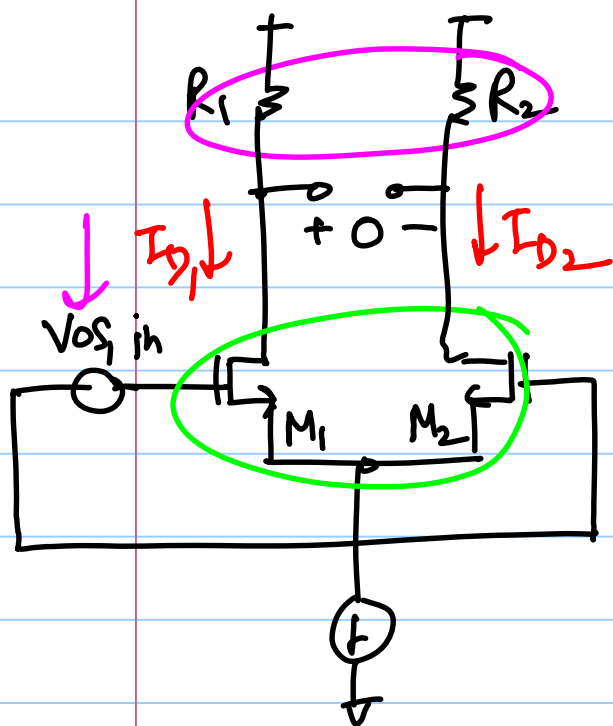
$$f_E = Q\left(\frac{d}{\sigma}\right)$$

$$= Q\left(\frac{|V_{in} - V_{ref}|}{\sigma_{V_{os}}}\right)$$



Comparator will make errors





$$V_{THN1} = V_{THN}$$

$$\left(\frac{W}{L}\right)_1 = \frac{W}{L}$$

$$R_1 = R_D$$

$$V_{THN2} = V_{THN} + \Delta V_{THN}$$

$$\left(\frac{W}{L}\right)_2 = \frac{W}{L} + \Delta\left(\frac{W}{L}\right)$$

$$R_2 = R_D + \Delta R$$

$$\text{For } V_{out} = 0 \Rightarrow I_{D1} R_1 = I_{D2} R_2$$

$$\text{We know, } I_{D1} \neq I_{D2}$$

$$\text{Let } I_{D1} = I_D \text{ \& } I_{D2} = I_D + \Delta I_D$$

$$\boxed{\lambda = \gamma = 0}$$

$$V_{OS,in} = V_{GS1} - V_{GS2}$$

$$= \sqrt{\frac{2I_{D1}}{\mu_n C_{ox} \left(\frac{W}{L}\right)_1}} + V_{THN1} - \sqrt{\frac{2I_{D2}}{\mu_n C_{ox} \left(\frac{W}{L}\right)_2}} - V_{THN2}$$

$$= \sqrt{\frac{2I_D}{\mu_n C_{ox} W/L}} \left[1 - \sqrt{\frac{1 + \frac{\Delta I_D}{I_D}}{1 + \frac{\Delta(W/L)}{(W/L)}}} \right] - \Delta V_{THN}$$

$$\sqrt{1+\epsilon} \approx 1 + \frac{\epsilon}{2}$$

$$(\sqrt{1+\epsilon})^{-1} \approx 1 - \frac{\epsilon}{2}$$

$$V_{OS,in} \Rightarrow = \sqrt{\frac{2I_D}{\beta}} \left\{ 1 - \left(1 + \frac{\Delta I_D}{R_D} \right) \left[1 - \frac{\Delta(W/L)}{2(W/L)} \right] \right\} - \Delta V_{THN}$$

$$I_{D1} R_{D1} = I_{D2} R_{D2} \quad \therefore V_{out} = 0$$

$$\Rightarrow \frac{\Delta I_D}{I_D} = - \frac{\Delta R_D}{R_D}$$

$$V_{os, in} = \frac{V_{ov}}{2} \left[\frac{\Delta R_D}{R_D} + \frac{\Delta(W/L)}{W/L} \right] - \Delta V_{THN}$$

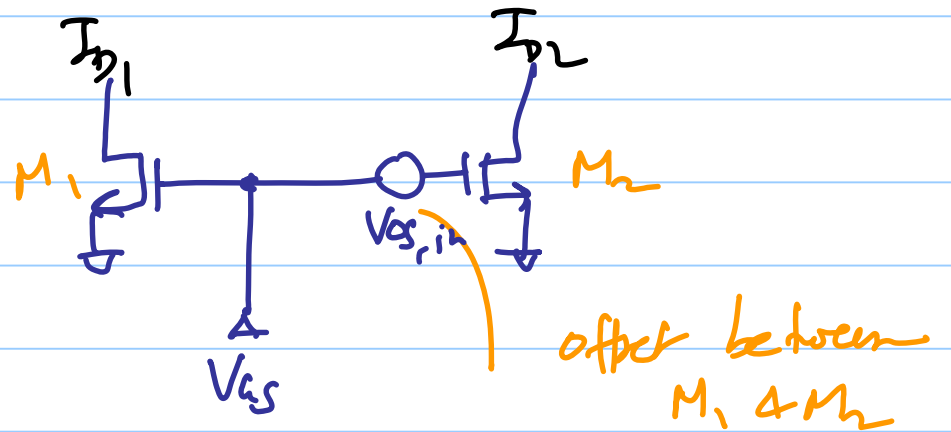
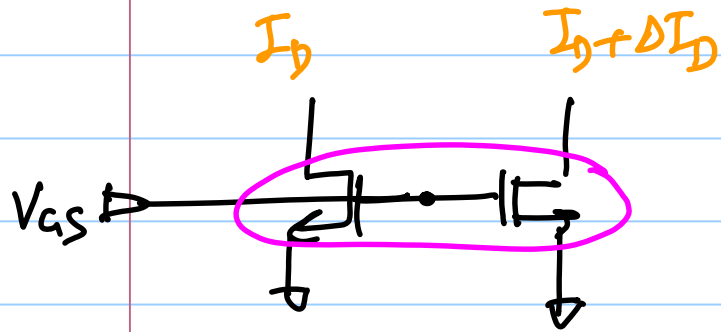
sign is irrelevant

offset depends on device mismatches
& biasing condition $V_{ov} = V_{GS} - V_{THN}$

① ΔV_{THN} is directly referred to the input

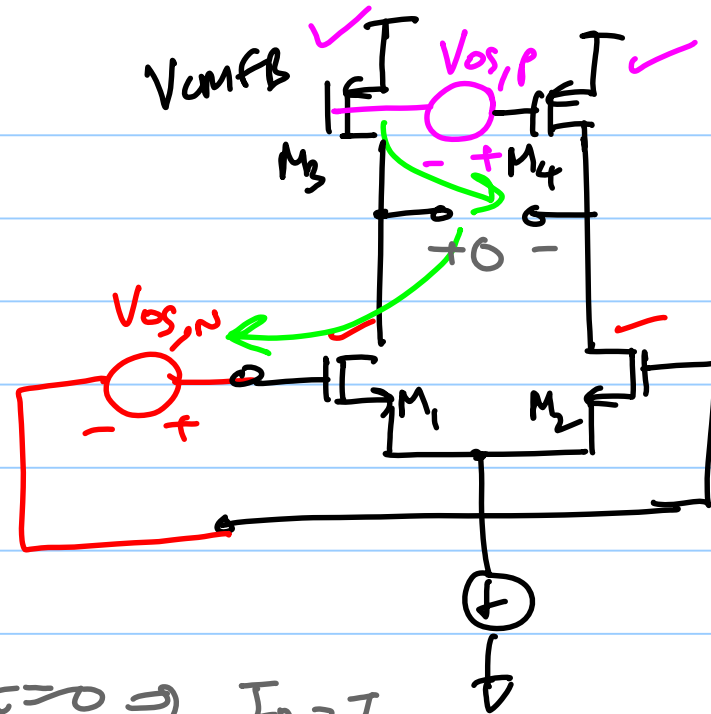
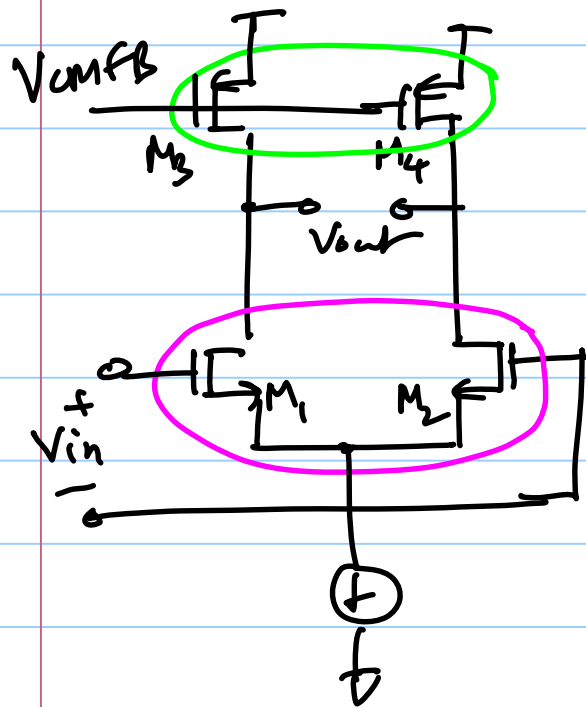
② Contribution of ΔR_D & $\Delta(W/L)$ increases with V_{ov}

$$\sigma_{V_{os, in}}^2 = \left(\frac{V_{ov}}{2} \right)^2 \left[\underbrace{\frac{\sigma_{\Delta R_D}^2}{R_D^2}}_{\text{sensitivity}} + \underbrace{\frac{\sigma_{\Delta(W/L)}^2}{(W/L)^2}}_{\text{sensitivity}} \right] + \sigma_{\Delta V_{THN}}^2$$



for $I_{D1} = I_{D2}$

$$V_{GS,in} = \frac{V_{OV}}{2} \left[\frac{\Delta(\check{w/L})}{\check{w/L}} \right] + \Delta\check{V_{thn}}$$



for $V_{out} = 0 \Rightarrow$

$$I_{D1} = I_{D2}$$

$$I_{D3} = I_{D4}$$

for a diff-pair with $I_{D1} = I_{D2}$

$$V_{os,n} = \frac{V_{ov,n}}{2} \left[\frac{\Delta(w/L)}{w/L} \right]_n + \Delta V_{THn} \checkmark$$

$$V_{os,p} = \frac{V_{ov,p}}{2} \left[\frac{\Delta(w/L)}{w/L} \right]_p + \Delta V_{THp}$$

from tricks used in noise analysis

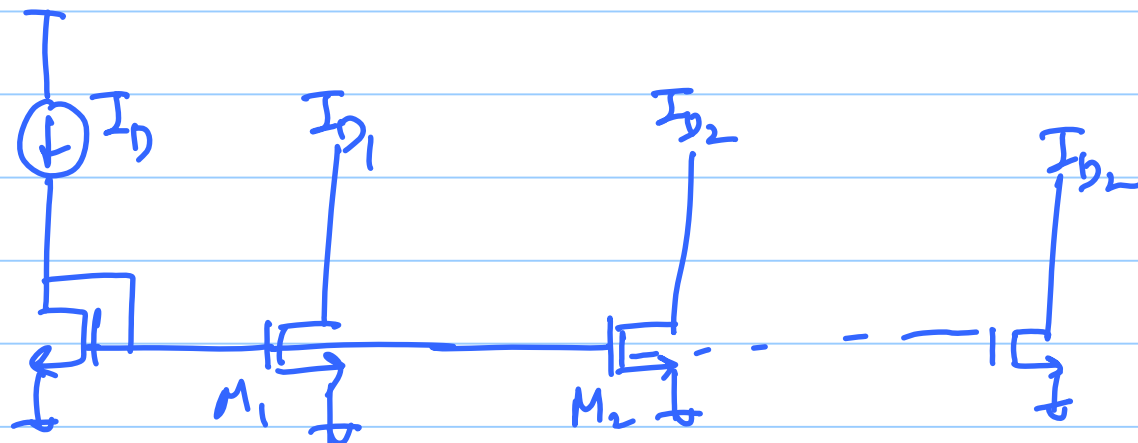
$$V_{os,n} = V_{os,n} + V_{os,p} \cdot \left(\frac{g_{mp}}{g_{mn}} \right)$$

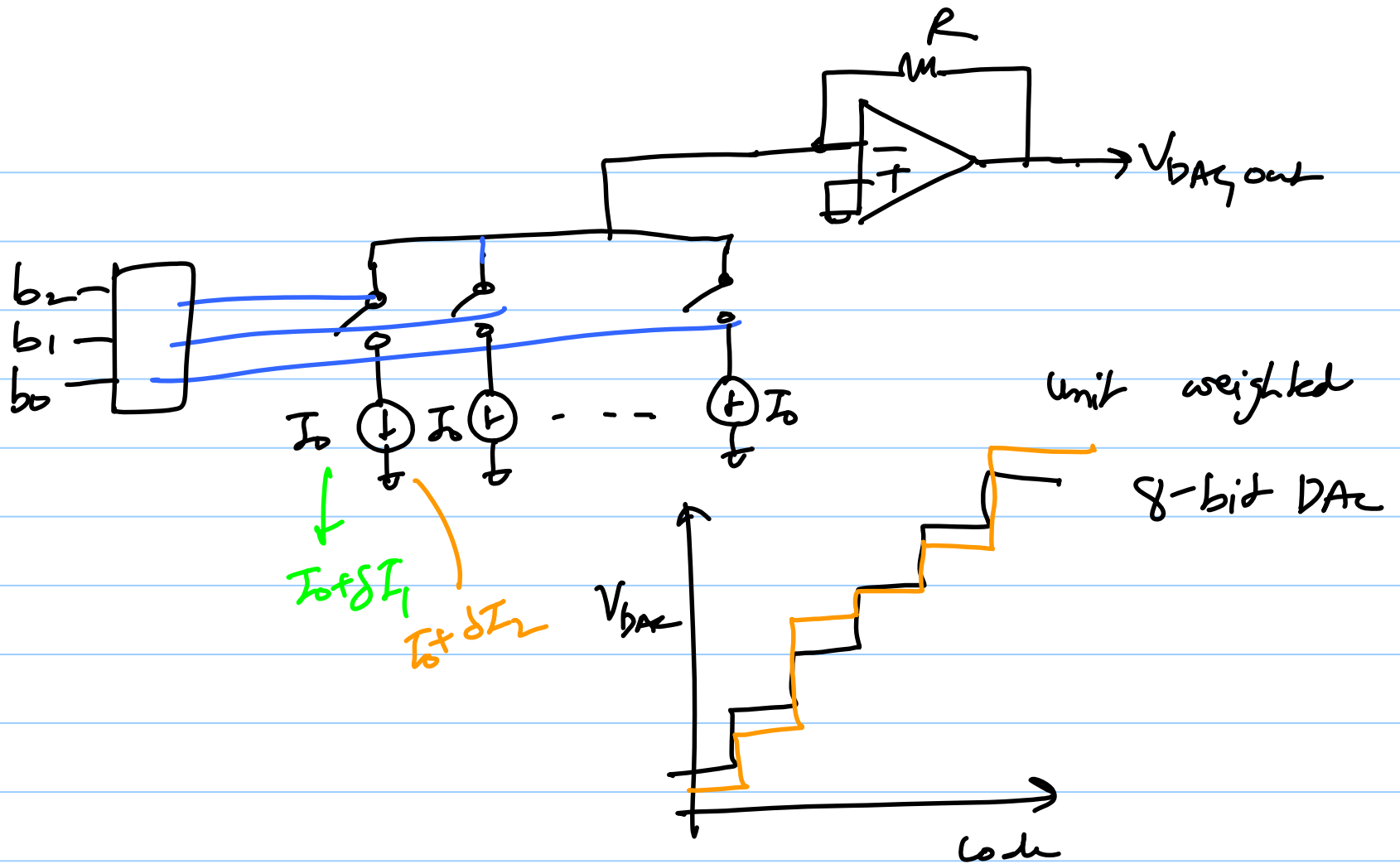
$$\sqrt{V_{os,n}^2} = \sqrt{V_{os,n}^2 + \left(\frac{g_{mp}}{g_{mn}} \right)^2 V_{os,p}^2}$$

$\downarrow$
 $f(V_{os,n}, \Delta V_{THn})$
 reduce by WL $\uparrow$
 V_{ovb}

$\downarrow$
 $f(V_{os,p}, \Delta V_{THp})$
 max g_{mn}
 min g_{mp}
 "Monte-Carlo simulation"
 ADE-XL

Current Sources :





Current mismatch

$$\frac{\Delta I_D}{I_D} = \frac{\Delta(w/L)}{w/L} - \frac{2 \Delta V_{THN}}{(V_{GS} - V_{THN})}$$

to minimize $\frac{\Delta I_D}{I_D}$, maximize V_{OV}
to use large Area