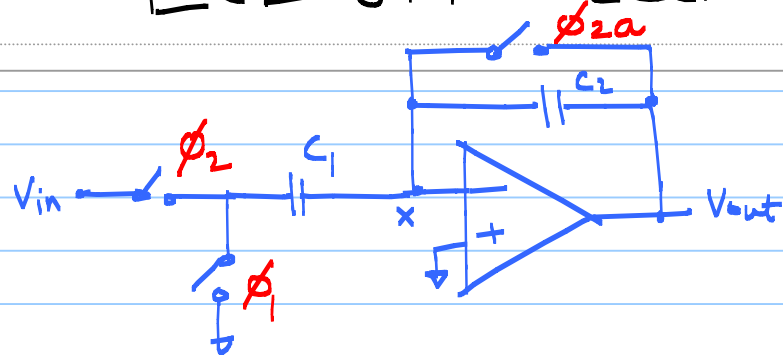


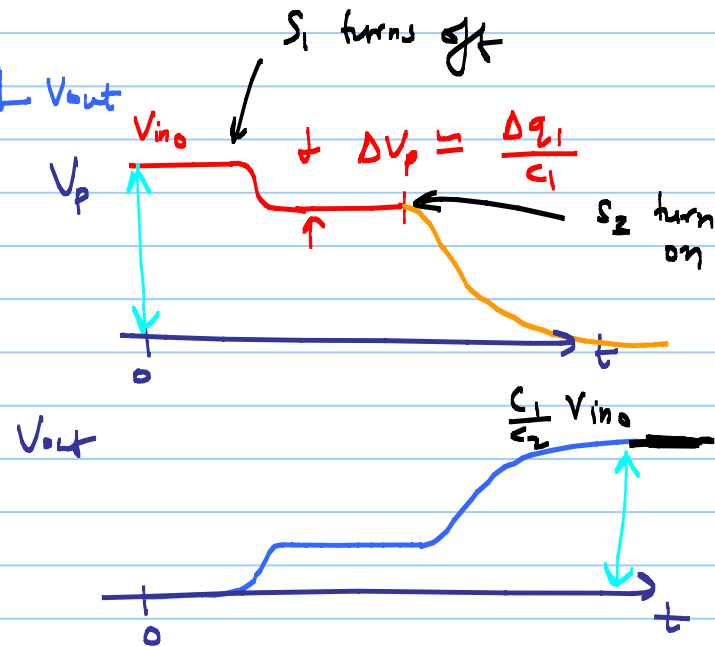
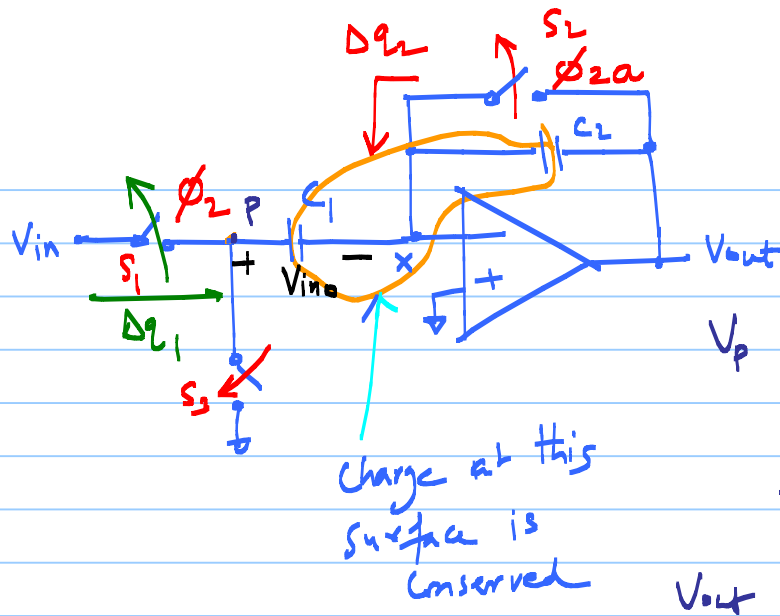
ECE 614 - Lecture 17

Note Title

10/30/2012



$$V_{out} = + \frac{C_1}{C_2} V_{in}$$



* intermediate perturbation due to charge injected by S_1 , doesn't change the final V_{out}

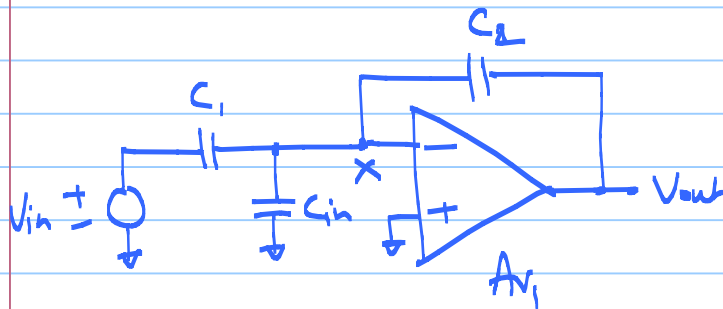
↳ charge at node-X is conserved

* used as a precise gain stage 2^M , $M=1, 2, \dots$

precision Considerations

The nominal gain of this $+\frac{C_1}{C_2}$

0.1% matching
layout technique



gain error $\epsilon = \frac{1}{\beta A_v}$

$$(V_{out} - V_x) s C_2 = V_x s C_{in} + (V_x - V_{in}) s C_1 \rightarrow \textcircled{1}$$

$$V_{out} = -A_v \cdot V_x \rightarrow \textcircled{2}$$

Closed loop
gain

$$\frac{V_{out}}{V_{in}} = \frac{C_1}{C_2 + \frac{C_2 + C_1 + C_{in}}{A_v}} \approx \frac{C_1}{C_2} \left[1 - \frac{C_2 + C_1 + C_{in}}{C_2} \frac{1}{A_v} \right]$$

gain error $= \frac{1}{\beta A_v}$

$\beta = \frac{C_2}{C_2 + C_1 + C_{in}}$

* gain error increases with $\left(\frac{C_1}{C_2}\right)$

$$\frac{C_1}{C_2} \uparrow, \beta \downarrow \Rightarrow \Sigma \uparrow$$

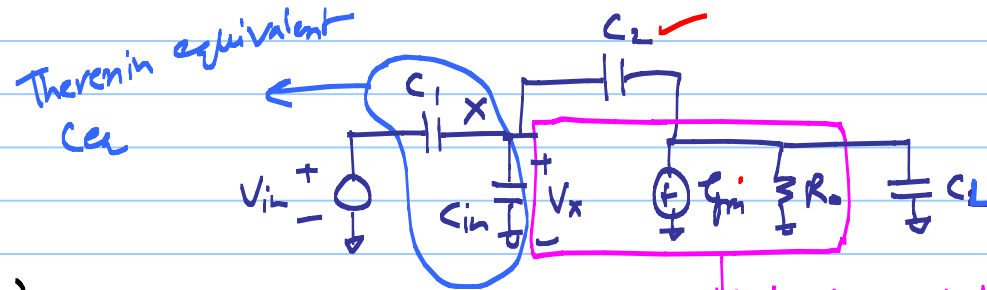
$$* \beta = \frac{C_2}{C_2 + C_1 + C_{in}} \leftarrow \text{minimize}$$

speed Considerations :

Time-constant during amplification phase

$$\tau_{amp} = \frac{C_L C_{eq} + C_L C_2 + C_{eq} C_2}{g_m C_2}$$

← similar to τ_{amp} of
S/H when
 $C_{in} \leftarrow C_1 + C_{in}$



$$\frac{V_{out}}{V_{in}}(s)$$

$C_L \leftarrow$ load

$C_{eq} \leftarrow C_1 + C_{in}$

$$\beta = \frac{C_2}{C_1 + C_2 + C_{in}} \text{ is smaller than}$$

β of S/H

$f_{2dB} = \beta f_{un}$ is also smaller
 $\Rightarrow$ slower than a S/H S/c circuit

* for larger nominal gain $\frac{C_1}{C_2} \uparrow$
 $\Rightarrow f_{2+12} \downarrow$

$\rightarrow$ need faster opamp (faster) for settling in given time T_{S2}

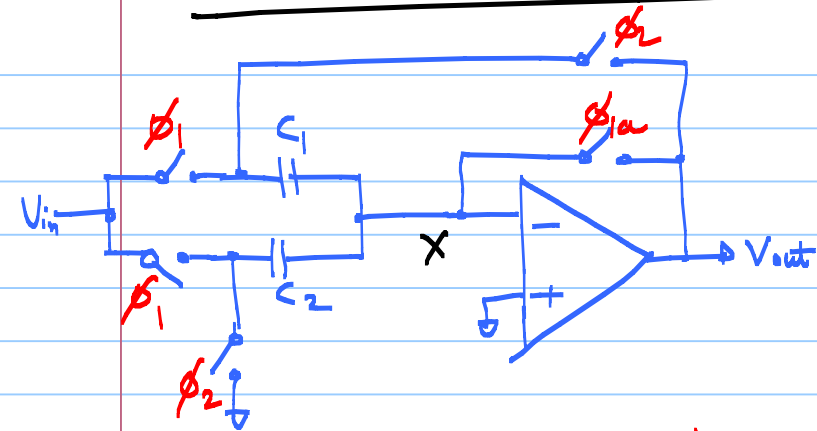
* lower C_{in}

* neglecting C_{in}

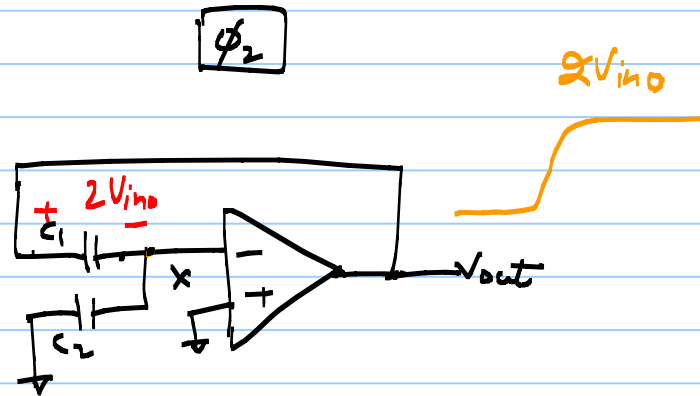
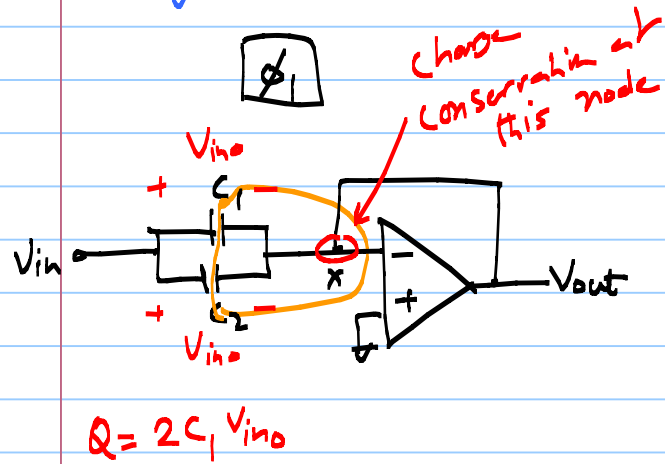
$$\frac{C_1}{C_2} = 2$$

* we have
$$\beta = \frac{C_2}{C_1 + C_2 + C_{in}} = \frac{C_2}{3C_2} = \frac{1}{3}$$

Precision Multiplier circuit



$$C_1 = C_2$$



Here,

$$\beta = \frac{C_1}{C_1 + C_2 + C_{in}} = \frac{C_1}{2C_1 + C_{in}}$$

$\downarrow$
 C_1

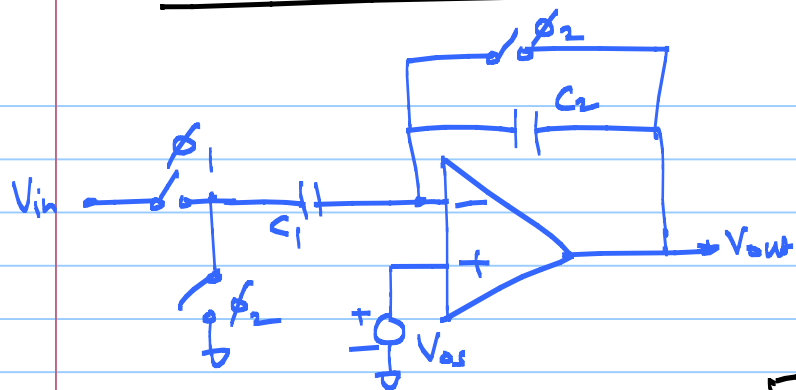
for $C_{in} = 0$ $\beta = \frac{1}{2}$

↳ relaxes precision and settling requirements on the opamp

↳ trade-off $\Rightarrow$ 2x C_{in} in the sampling phase

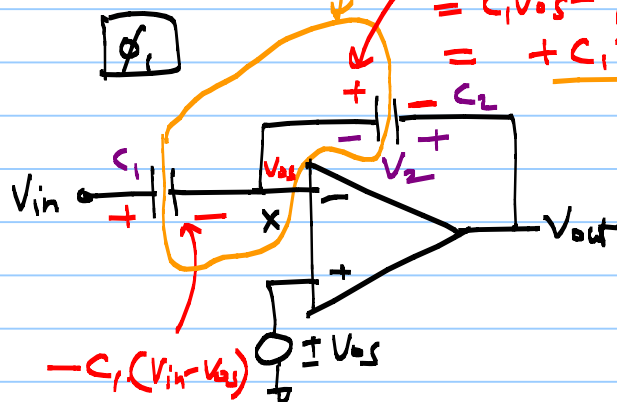
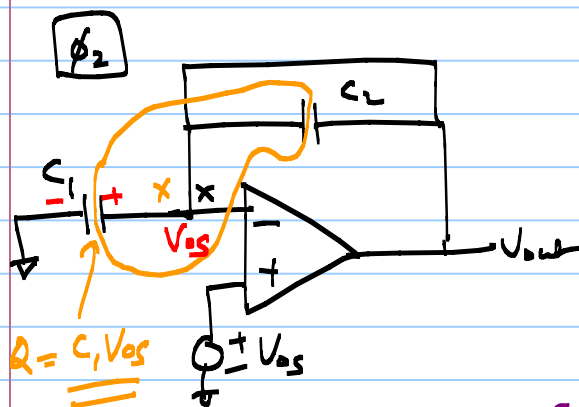
Effect of Offset

$$V_{out} = -\frac{C_1}{C_2} V_{in}$$



total charge on this surface = $C_1 V_{os}$

charge on this plate
 $= C_1 V_{os} - [-C_1 (V_{in} - V_{os})]$
 $= +C_1 V_{in}$



$$+C_1 V_{in} = -C_2 (V_2)$$

$$\Rightarrow V_2 = -\frac{C_1}{C_2} V_{in}$$

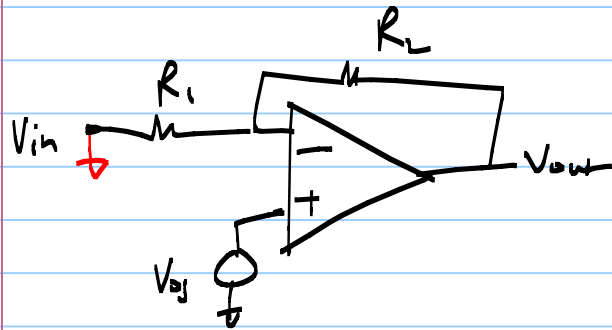
$$\Rightarrow \boxed{V_{out} = \underline{V_{os}} - \frac{C_1}{C_2} V_{in}}$$

$$V_{os} - \frac{C_1}{C_2} (V_{in} \cancel{+ V_{os}})$$

$\Rightarrow$ inherent input offset cancellation
 $\hookrightarrow$ no offset in the voltage V_2

$$\Rightarrow V_{out} = -\frac{C_1}{C_2} V_{in} + \underline{V_{os}} \quad \leftarrow \begin{array}{l} \text{DC shift in the} \\ \text{output} \end{array}$$

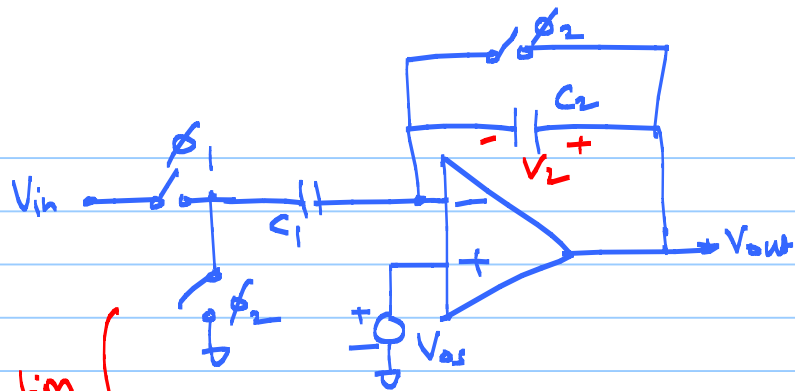
2nd CT amplifier case



$$V_{out} = -\frac{R_f}{R_i} V_{in} + V_{os} \left(1 + \frac{R_f}{R_i}\right)$$

$$= -\frac{R_f}{R_i} (V_{in} - V_{os}) + V_{os}$$

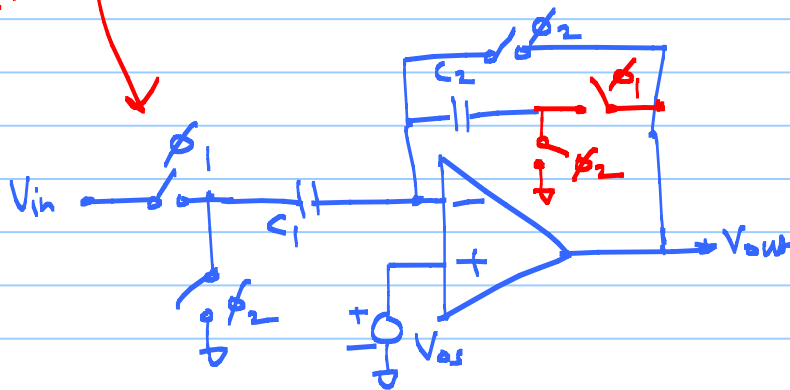
↑ this offset effect is
absent in the SC
amplifier case



$$V_{out} = V_{os} + V_2$$

$\uparrow -\frac{C_1}{C_2} V_{in}$

modification



$$\frac{-V_{os} + V_{os} + V_{sig}}{V_{sig}}$$

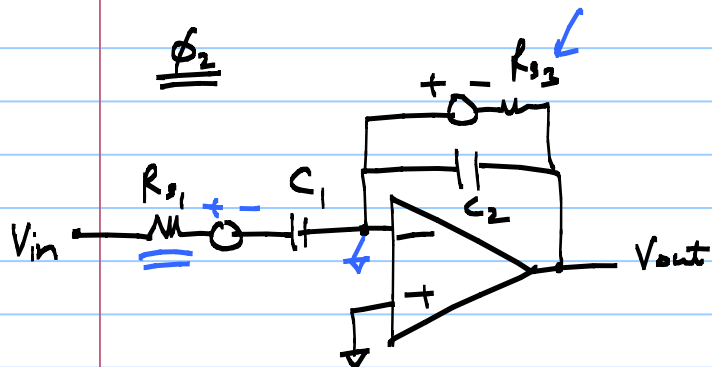
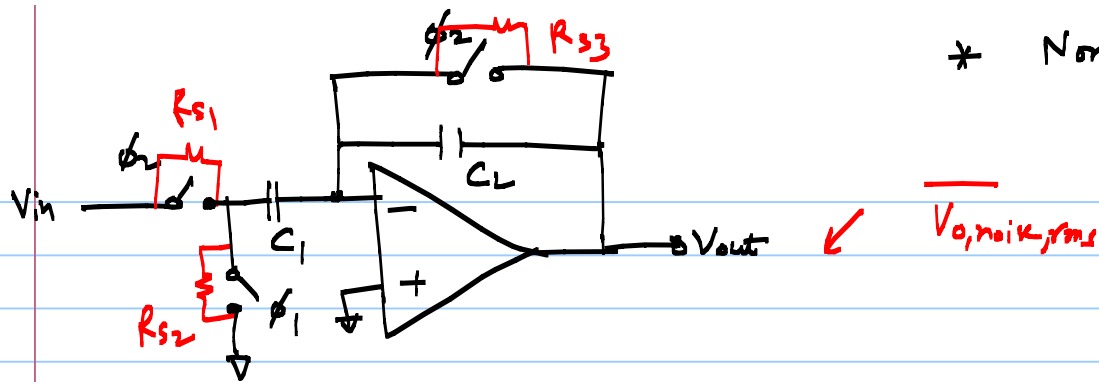
ϕ_2 : charging C_2 to V_{os} instead of 0

ϕ_1 : $V_{out} = -\frac{C_1}{C_2} V_{in} \rightarrow$ offset is completely removed

Thermal Noise

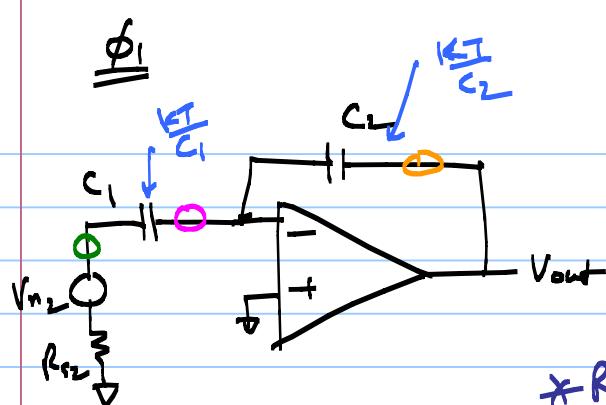
- * Assume that the switches are noisy
& the opamp $\overline{V_{n,in}}$ is negligible

* Noninverting amplifier



R_{s1} $\Rightarrow C_1$ has a noise variance of $\frac{KT}{C_1}$

R_{s3} $\Rightarrow C_2$ has noise variance $\frac{KT}{C_2}$



* $R_{S1} \Rightarrow$ in $\phi_2 \rightarrow \frac{kT}{C_1}$
is amplified by $\left(\frac{C_1}{C_2}\right)^2$

$\Rightarrow \frac{kT}{C_1} \left(\frac{C_1}{C_2}\right)^2$ ①

* $R_{S2} \Rightarrow$ in $\phi_2 \rightarrow \frac{kT}{C_2}$ is held ②

* $R_{S2} \Rightarrow$ Results in noise variance $\frac{kT}{C_1}$ on C_1 during ϕ_1 phase

$\downarrow$
 $\frac{kT}{C_1} \left(\frac{C_1}{C_2}\right)^2$ at the output ③

$$\begin{aligned} \text{Total output noise} &= 2 \frac{kT}{C_1} \left(\frac{C_1}{C_2} \right)^2 + \frac{kT}{C_2} \\ \text{Variance} &= \frac{kT}{C_1} \left[2 \left(\frac{C_1}{C_2} \right)^2 + \frac{C_1}{C_2} \right] \longrightarrow \textcircled{1} \end{aligned}$$

$$\begin{aligned} \Rightarrow \text{input referred noise} &= \frac{\frac{kT}{C_1} \left[2 \left(\frac{C_1}{C_2} \right)^2 + \frac{C_1}{C_2} \right]}{\left(\frac{C_1}{C_2} \right)^2} \\ \text{Variance} &= \frac{kT}{C_1} \left[2 + \frac{C_2}{C_1} \right] \end{aligned}$$

$$\text{for gain of 2} \Rightarrow \frac{C_1}{C_2} = 2$$

$$\Rightarrow \text{input-referred noise variance} = 2.5 \frac{kT}{C_1}$$

$$\overline{V_{in, \text{noise}, \text{rms}}} = \sqrt{2.5 \frac{kT}{C_1}}$$