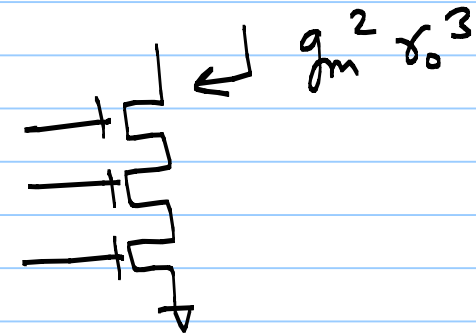
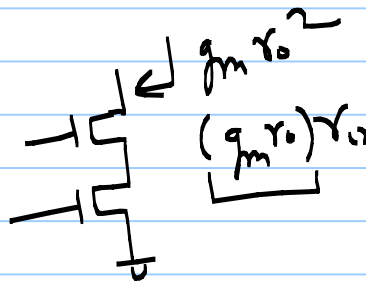
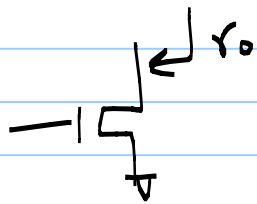


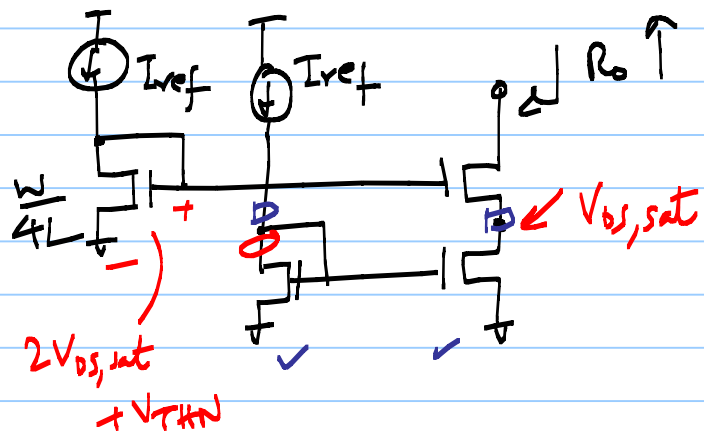
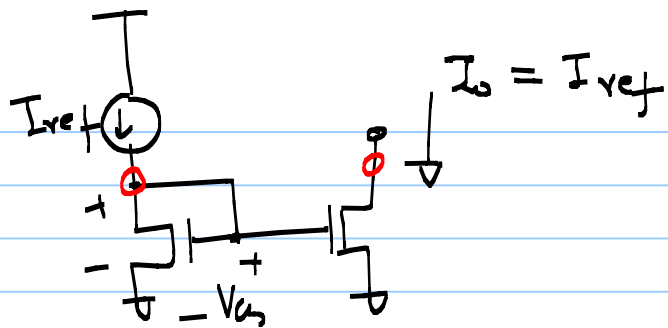
ECE 5411 - Lecture 11.

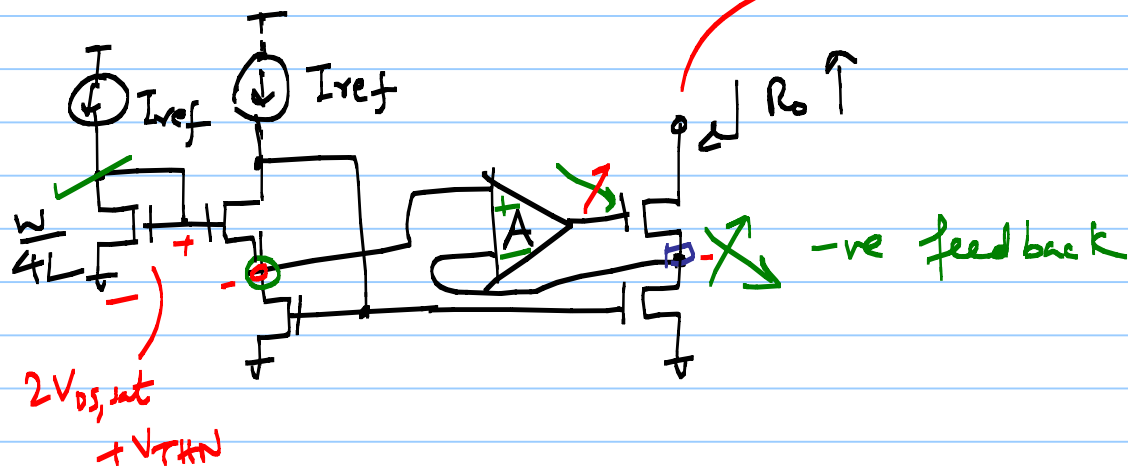
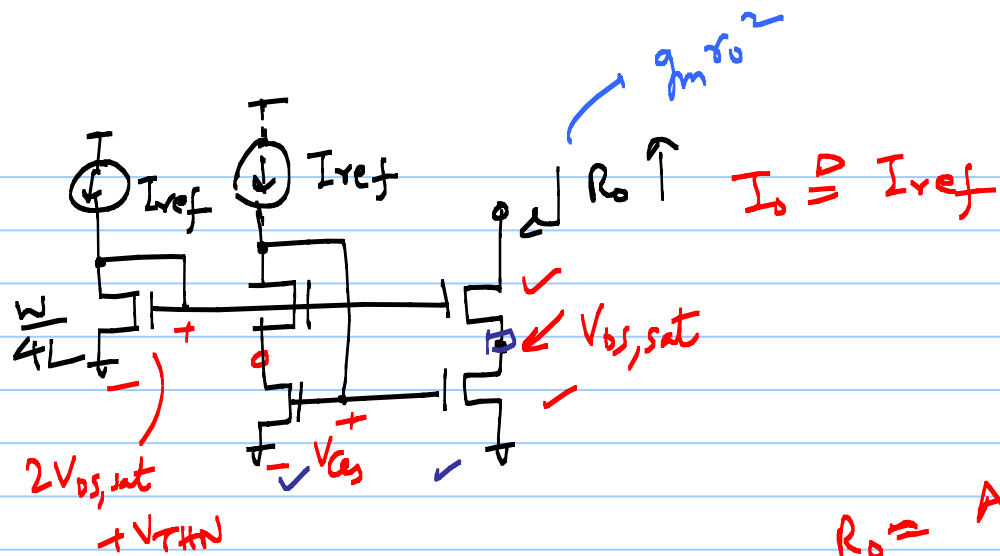
Note Title

2/28/2011



(-) swing





Op-amp symbol and transfer function:

$$A(s) = \frac{A_0}{(1 + s/\omega_p)}$$
 "Laker"

Single-Stage Amplifiers

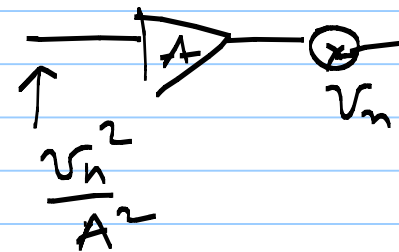
amplify an analog or digital signal

↳ drive a load

↳ overcome noise
of a subsequent stage

↳ provide logic levels
to a digital gate

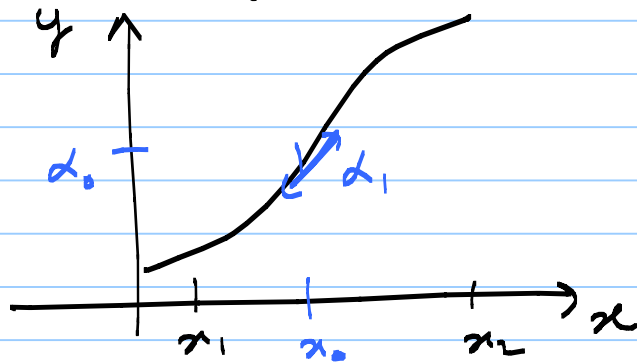
↳ in feedback systems



* Single-stage amplifiers → low-frequency behavior

* input-output characteristics of an amplifier

$$y(t) = \alpha_0 + \alpha_1 x(t) + \underbrace{\alpha_2 x^2(t) + \dots + \alpha_n x^n(t)}_{x_1 \leq x \leq x_2},$$



Small-signal amplitude

$$y(t) \approx \underbrace{\alpha_0}_{\text{operating point}} + \underbrace{\alpha_1 x(t)}_{\text{Small-signal gain}}$$

operating
point

Small-signal
gain

for $\alpha_1 x(t) \ll \alpha_0$, the bias point is disturbed negligible.

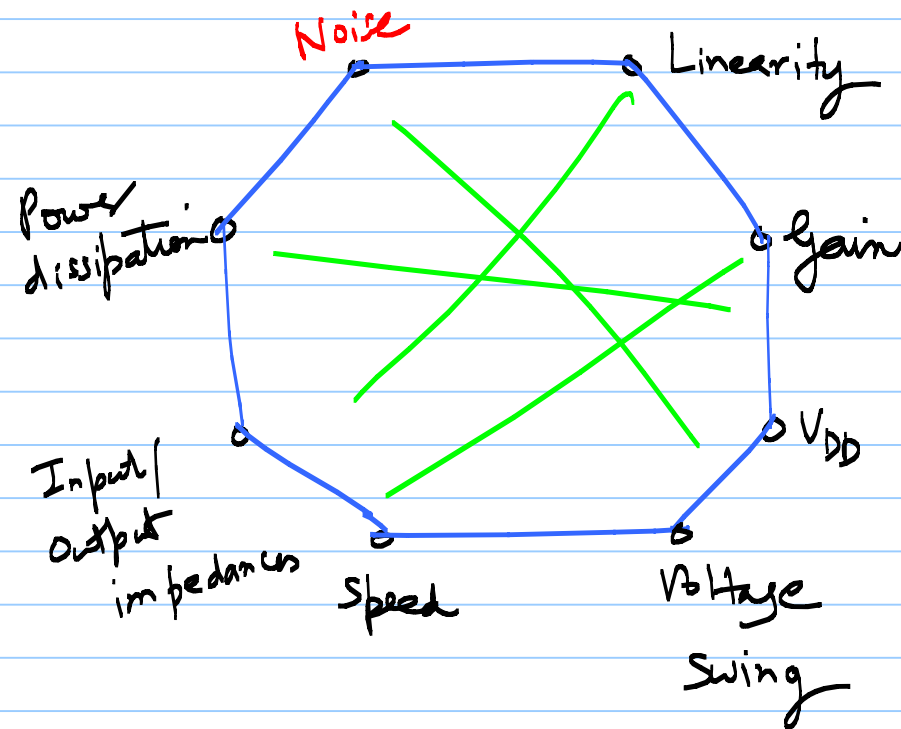
$$\Delta y = \alpha_1 \Delta x$$

As $x(t)$ increases in magnitude

$\Rightarrow$ large-signal behavior

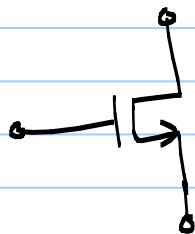
$\Rightarrow$ higher-order terms start manifesting
 $\rightarrow$ distortion

"Analog design Octagon"



◦ variability ↗
◦ mismatch ↘

multidimensional design "trade-offs" problem.

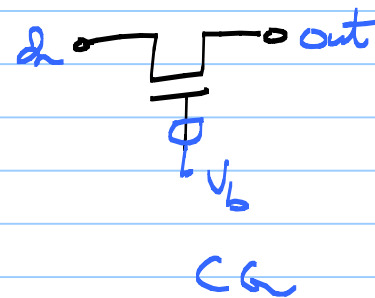
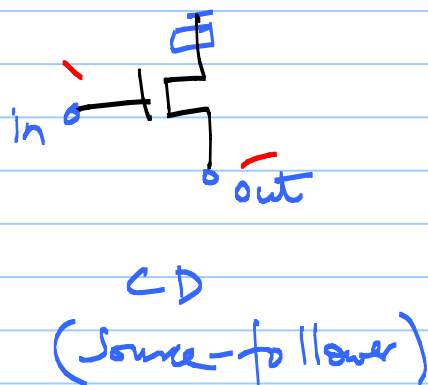
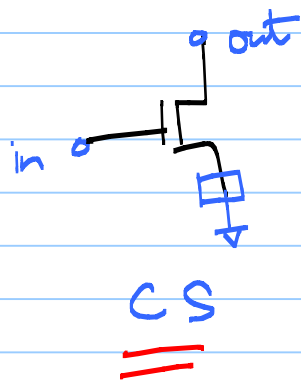


3-terminals

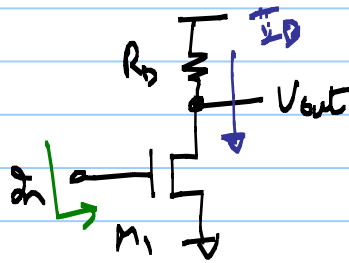
- 1- input
- 2- output

$$3C_2 = 3$$

~~3~~



Common Source Stage

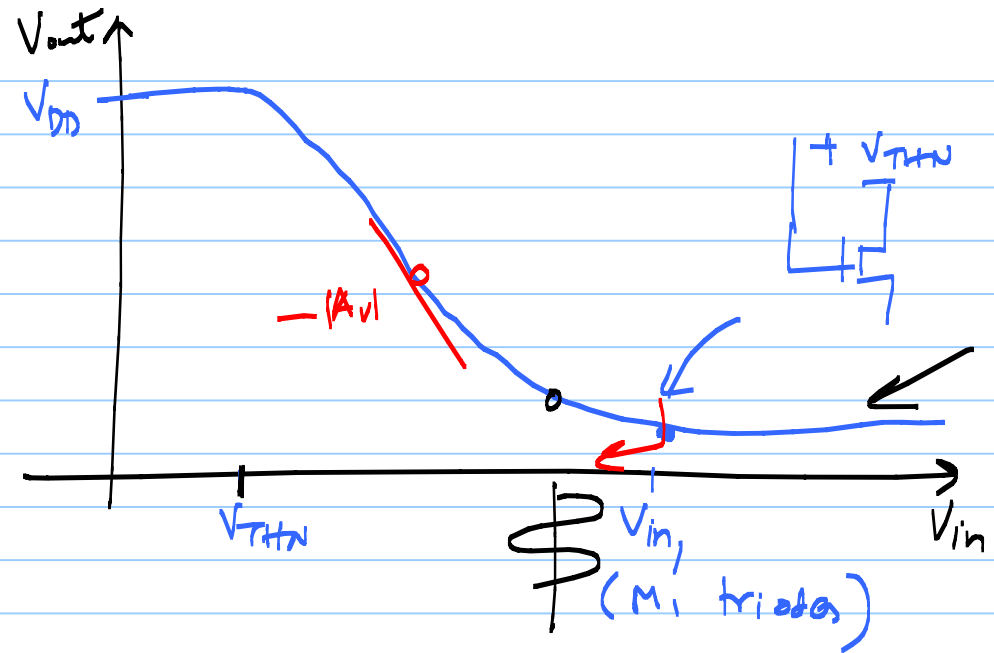


@ low-freq

Z_{in} is very high

Initially $v_{in}=0$, $v_{out}=V_{DD}$

$v_{in} \geq V_{THN}$, V_{DD} is sufficiently large

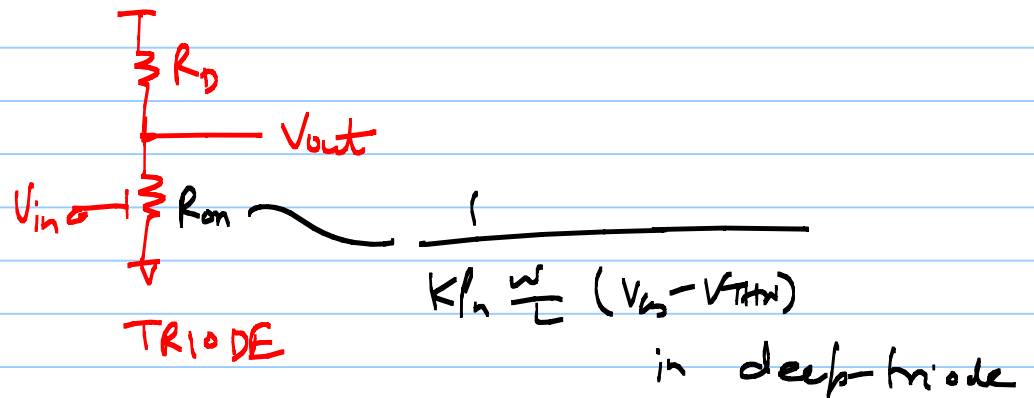
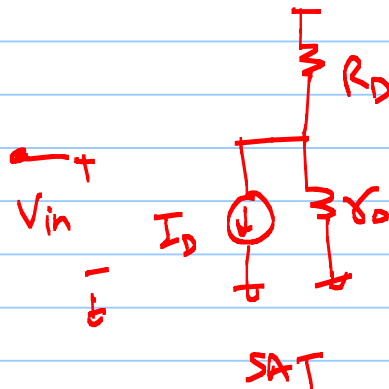


$$V_{out} = V_{DD} - I_D \cdot R_D$$

$$V_{out} = V_{DD} - R_D \cdot \frac{K P_n}{2} \frac{W}{L} (V_{in} - V_{THN})^2 \longrightarrow \textcircled{1}$$

If we increase V_{in} further, M_1 triodes

$$V_{out} = V_{DD} - R_D \cdot K P_n \frac{W}{L} \left[(V_{in} - V_{THN}) V_{out} - \frac{V_{out}^2}{2} \right] \longrightarrow \textcircled{2}$$

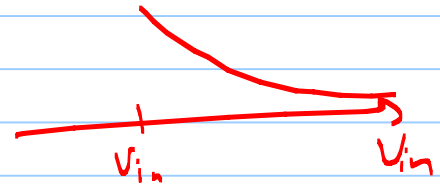


In triode:

$$V_{out} = V_{DD} \frac{R_D}{R_D + R_{on}} = \frac{V_{DD}}{1 + K P_n \frac{W}{L} (\underline{V_{in}} - V_{THN})}$$

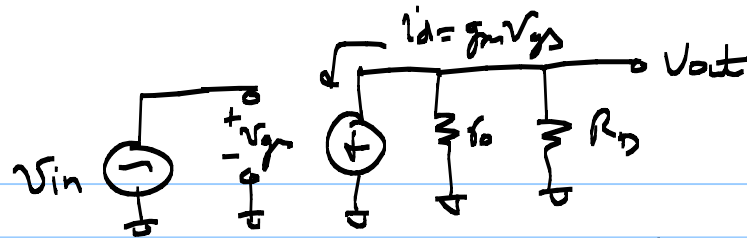
In saturation:

$$V_{out} = V_{DD} - R_D \cdot \frac{K P_n}{2} \frac{W}{L} (V_{in} - V_{THN})^2, \quad \lambda = 0$$



Small-signal
Voltage gain

$$A_v = \frac{\partial V_{out}}{\partial V_{in}} = -R_D \cdot K P_n \frac{W}{L} (\underline{V_{in}} - V_{THN})$$
$$= \underline{\underline{-g_m R_D}}$$



$$v_{out} = -i_d (r_o \parallel R_D)$$

$$= -g_m v_{gs} (r_o \parallel R_D)$$

$$\Rightarrow$$

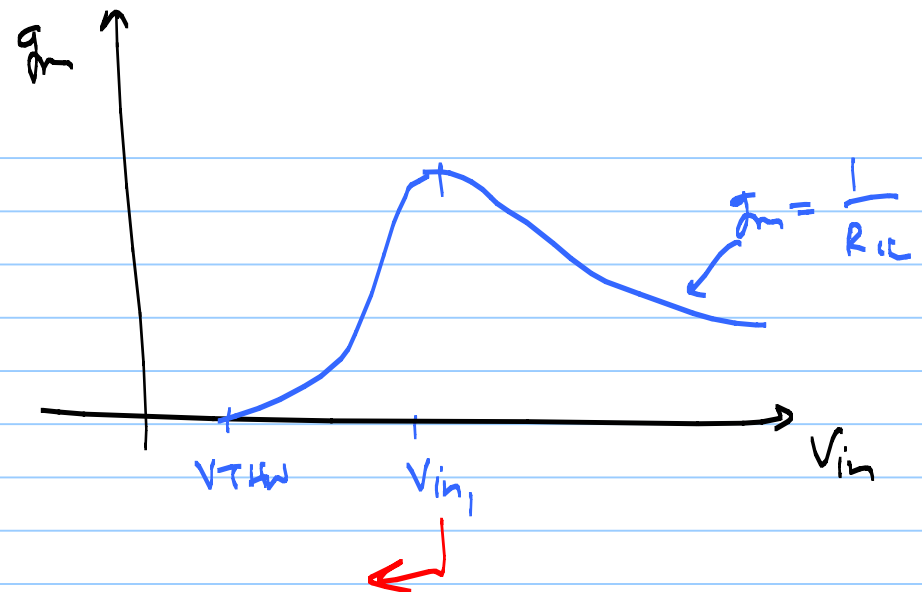
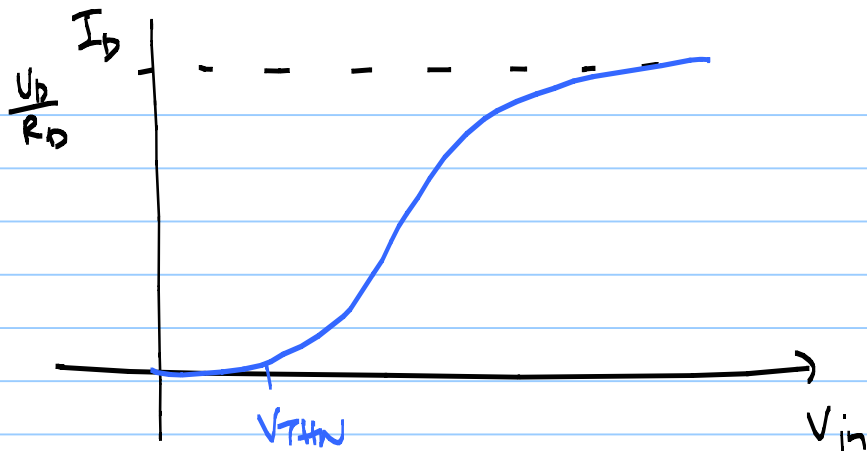
$$A_v = \frac{v_{out}}{v_{in}} = -g_m (r_o \parallel R_D)$$

$$\approx -g_m R_D$$

$$* A_v = -R_D \cdot \overbrace{K \mu_n \frac{W}{L}}^{g_m} (V_{in} - V_{THN})$$

* gain varies with large signal swing

$$* g_m = f(v_{in})$$



$$A_v = -\sqrt{2K_p \frac{W}{L} I_D} \cdot R_D$$

$$= -\sqrt{2K_p \frac{W}{L} \cdot I_D} \cdot \frac{V_{RD}}{I_D}$$

$$= -\sqrt{2K_p \frac{W}{L}} \cdot \frac{V_{RD}}{\sqrt{I_D}}$$

V_{RD} is the drop across R_D

|A_v|

$\left(\frac{W}{L}\right) \uparrow \Rightarrow$ larger device caps

$V_{DD} \uparrow \Rightarrow$ lower swing

$I_D \downarrow \Rightarrow$ lower speed.

$$f_T \propto \frac{V_{DD}}{L}, \quad A_v \propto \frac{L}{V_{DD}}$$