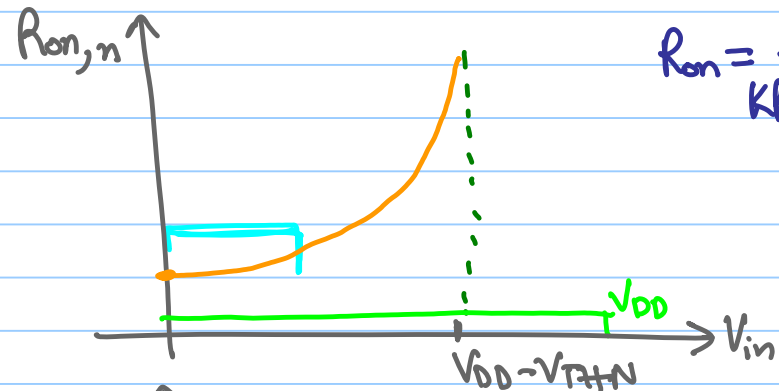
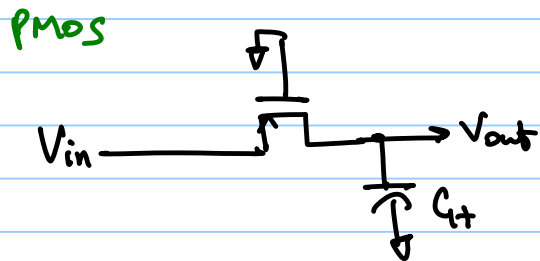
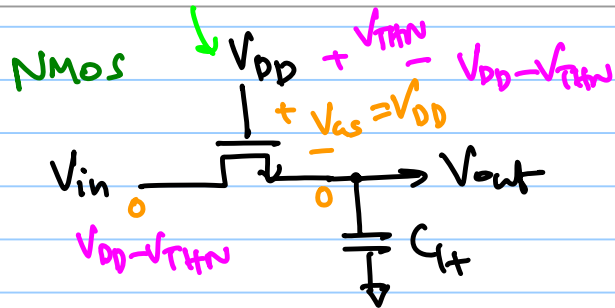


ECE 517 - Lecture 14

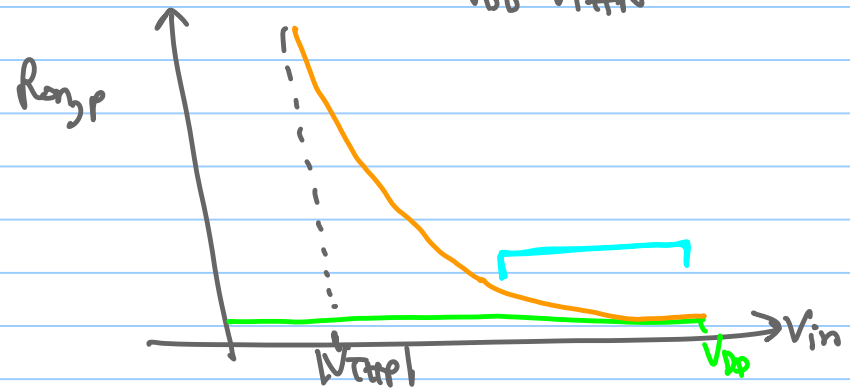
Razavi's Book

Note Title

3/2/2017



$$R_{on} = \frac{1}{K_n \frac{W}{L} (V_{DD} - V_{THN})}$$



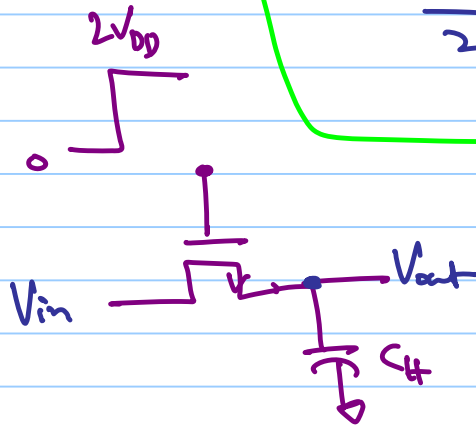
Restrict R_{on} to a range of 4:1

$$V_{in,max} = \frac{3}{4} (V_{DD} - V_{THN})$$

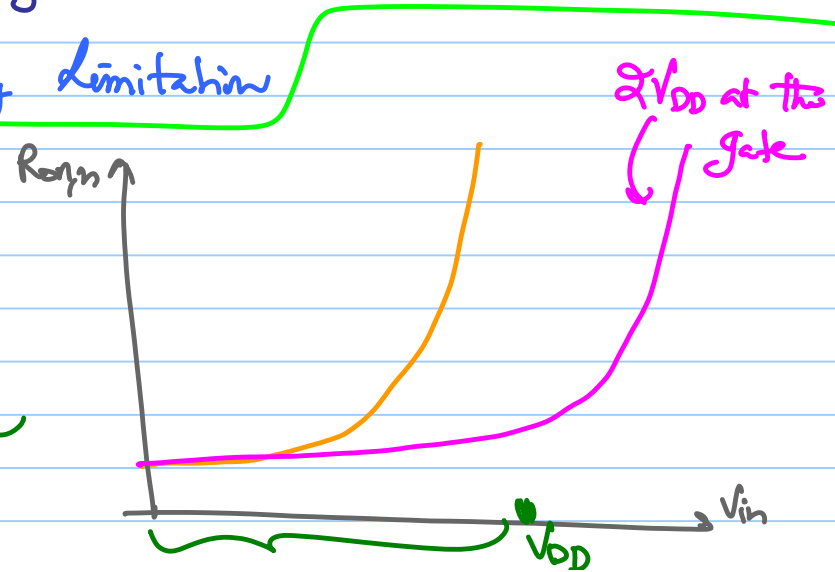
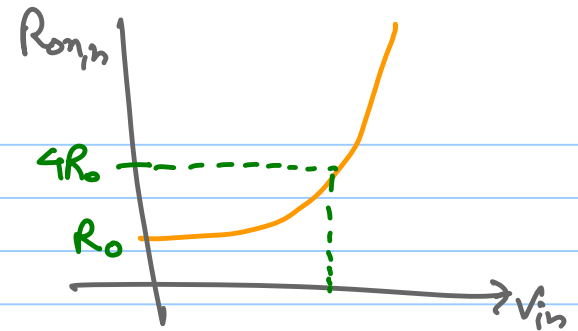
$\leq \frac{V_{DD}}{2}$ for some technologies

→ severe swing limitation

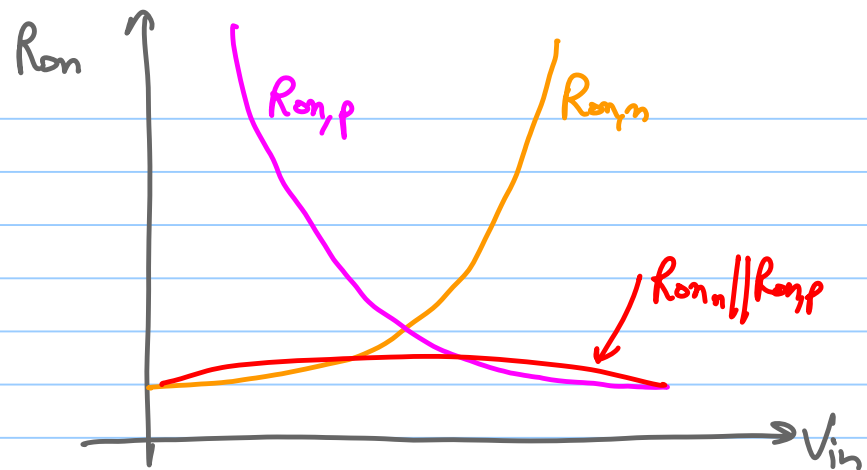
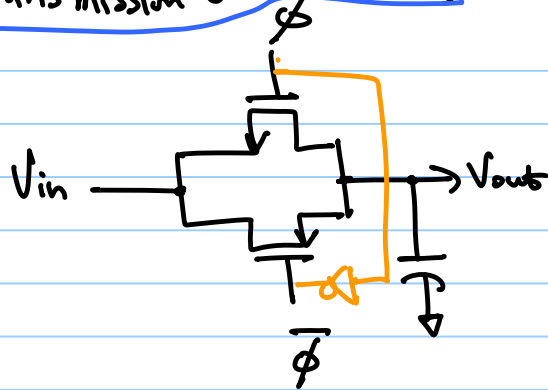
Bootstrapping

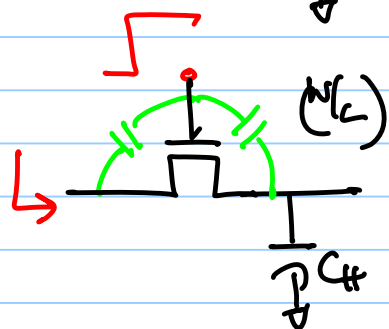
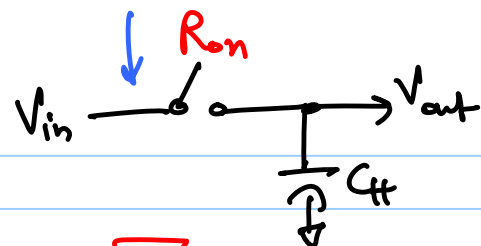


* charge pump
Voltage doubles



Transmission Gate (TG)





Large W/L
 $\hookrightarrow$ more capacitance

$$\tau = R_{on} C_{\#}$$

$$\begin{aligned} &\hookrightarrow R_{on} \downarrow \\ &\Rightarrow \left(\frac{W}{L}\right) \uparrow \end{aligned}$$

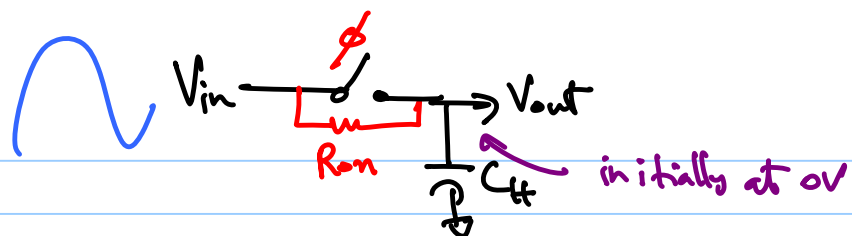
Noise sampled on the Capacitor:

$$V_{n,rms} = \sqrt{\frac{KT}{C_{\#}}}$$

$\uparrow$ SNR of the ADC

$$R_{on} \approx \frac{1}{K \mu_n \frac{W}{L} (V_{DD} - V_{THN})}$$

in Deep Triode



$$\tau = R_{on} \cdot C_{tt}$$

$$V_{out} = (1 - e^{-t/\tau}) V_{in}$$

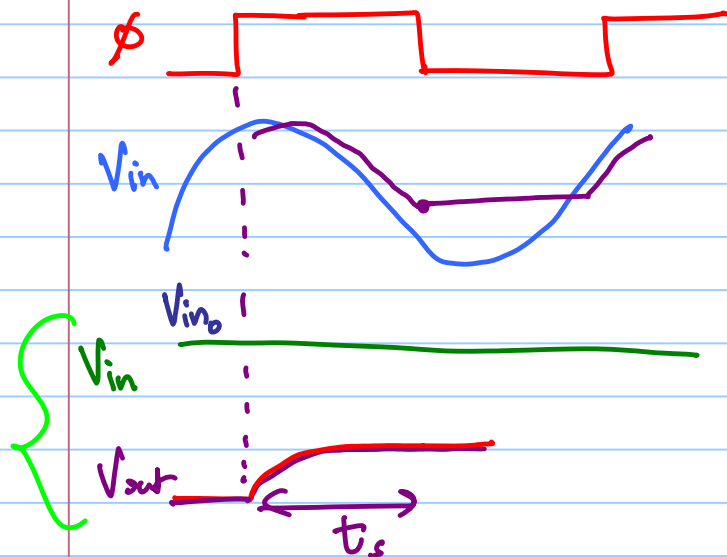
Clock rate $f_s \Rightarrow t_s \leftarrow T_s/2$
settling time

$$V_{out} = (1 - \epsilon) V_{in_0}$$

accuracy

$$1 - \epsilon = 1 - e^{-t_s/\tau}$$

$$\Rightarrow \frac{t_s}{\tau} = \ln(1/\epsilon)$$

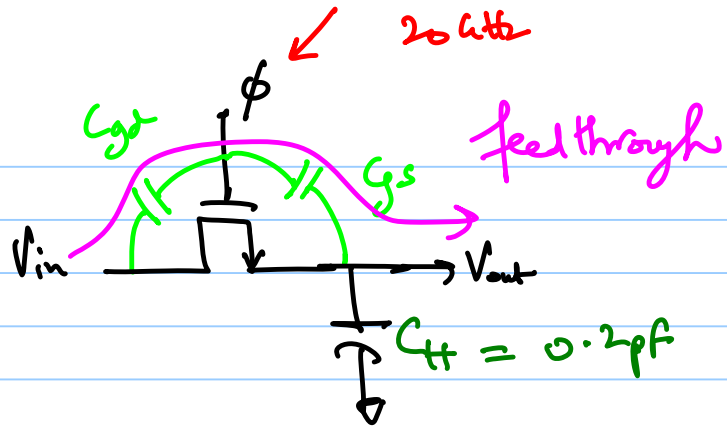


$$t_s = \frac{1}{\omega} \ln\left(\frac{1}{\epsilon}\right)$$

↓
Rout C_H
↑

Accuracy	ϵ	Switch $t_{s/2}$
10%	0.1	2.3
1%	0.01	4.6
0.1%	0.0001	6.9
0.01% ⏟	0.000001	9.21

10GHz

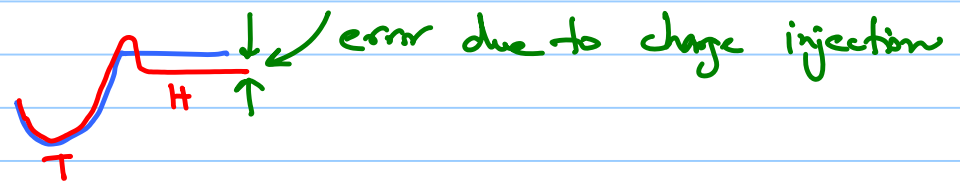
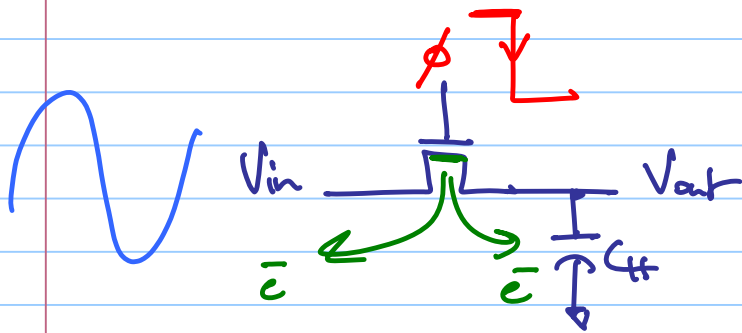


Issues?

→ Need better topologies at higher speeds to avoid capacitive feedthrough

Precision Considerations

① Channel "charge injection"

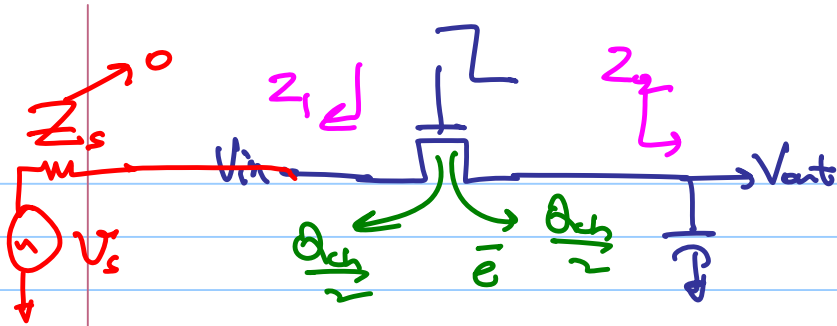


$$Q_{ch} \approx WL C'_{ox} (V_{DD} - V_{in} - \underbrace{V_{T+H}}_{\text{Assuming } V_{out} = V_{in}})$$

Non-linear dependence on the input

$$V_{T+H} \approx V_{T+H0} + \gamma \left(\sqrt{2\phi_B + V_{in}} - \sqrt{2\phi_B} \right)$$

"Body - Effect"



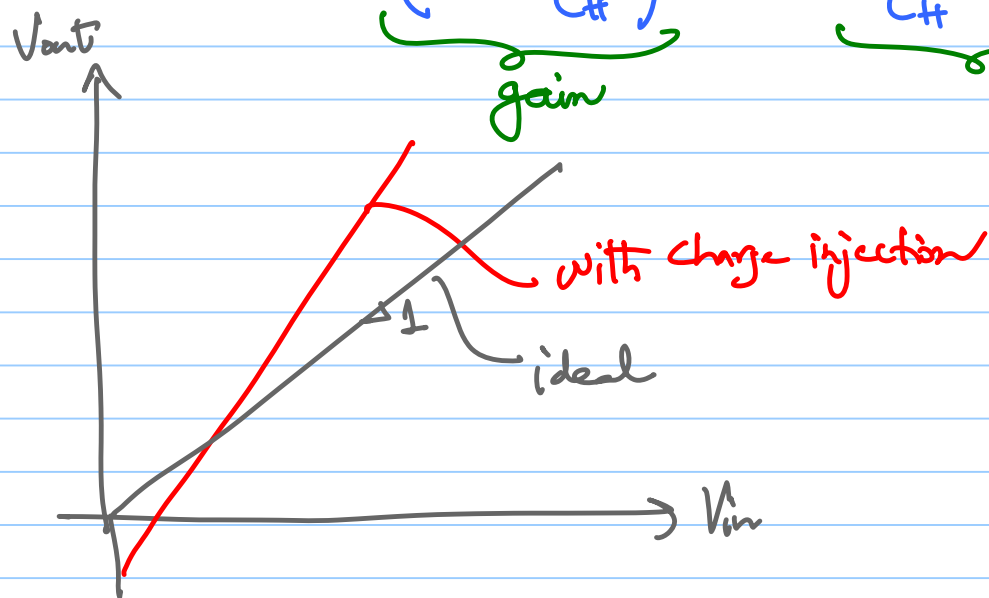
if $-\frac{Q_{ch}}{2}$ is injected into C_H

voltage error in the sampled voltage

$$\Delta V = \frac{-WL C_{ox} (V_{DD} - V_{in} - V_{THN})}{2 C_H} \quad (-ve)$$

$$V_{out} \approx V_{in} - \frac{WL C_{ox} (V_{DD} - V_{in} - \underline{V_{thn}})}{C_H} \quad \text{--- } f(V_{in}) : \text{Body effect}$$

$$= V_{in} \underbrace{\left(1 + \frac{WL C_{ox}}{C_H}\right)}_{\text{gain}} - \underbrace{\frac{WL C_{ox}}{C_H} (V_{DD} - V_{thn})}_{\text{offset}}$$



$$V_{out} = V_{in} \left(1 + \frac{W L C_{ox}}{C_H} \right) + \gamma \frac{W L C_{ox}}{C_H} \sqrt{2 \phi_B + V_{in}} - \frac{W L C_{ox}}{C_H} \left(V_{DD} - V_{Tn0} + \gamma \sqrt{2 \phi_B} \right)$$

✓ *gain*
 (The term $\gamma \frac{W L C_{ox}}{C_H} \sqrt{2 \phi_B + V_{in}}$ is circled in green and labeled *non-linearity* ✗)
offset ✓

↳ non-linearity cannot be tolerated