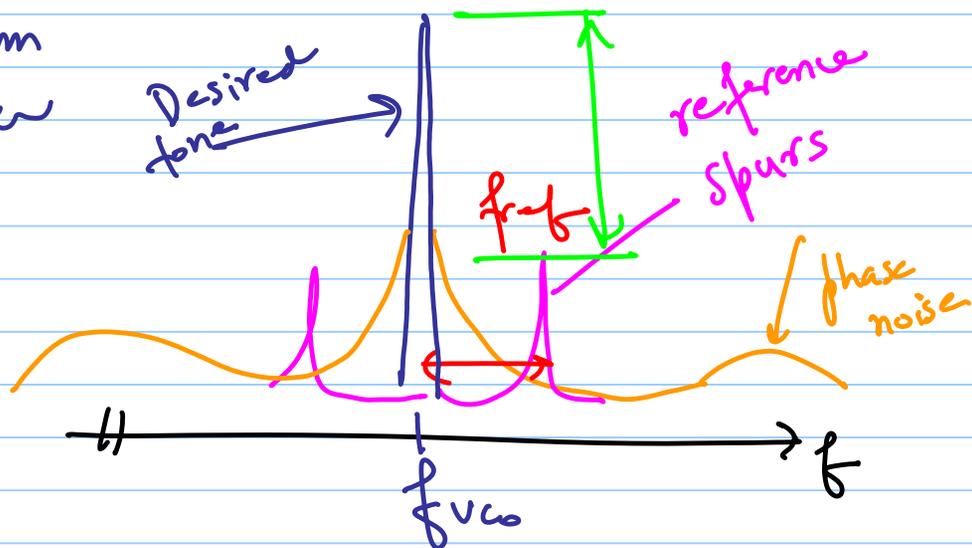


# ECE 504 - Lecture 7

Note Title

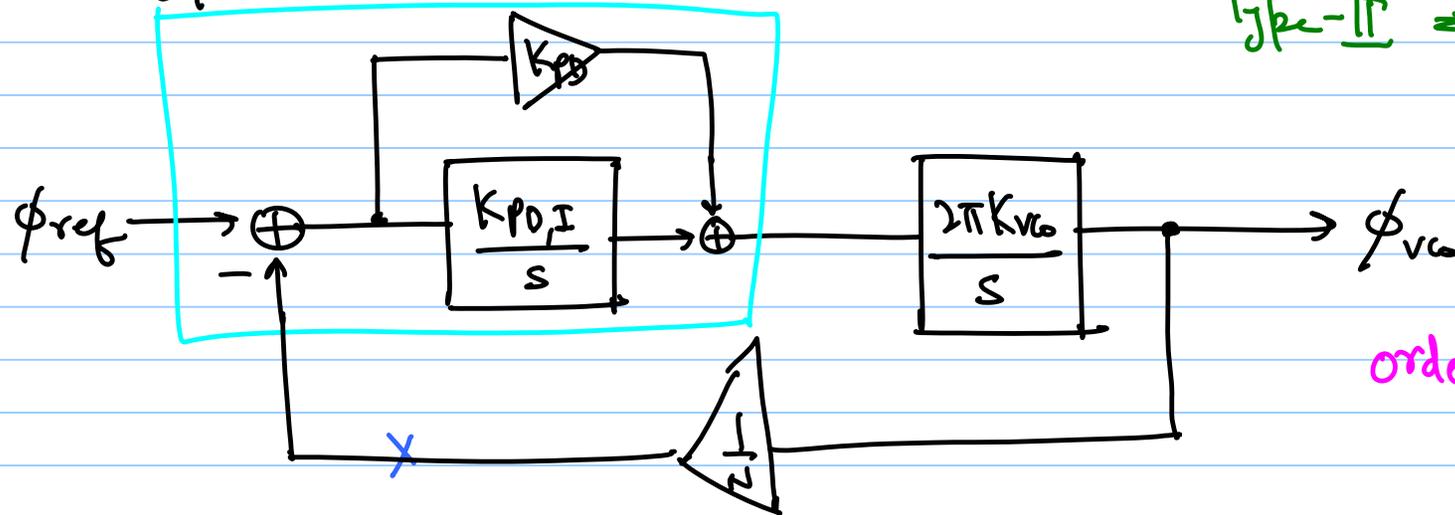
9/14/2016

Spectrum Analyzer



HW#2 is posted on the site!

# Type-II PLL



Type-II  $\Rightarrow$  2 poles at DC in the loop gain

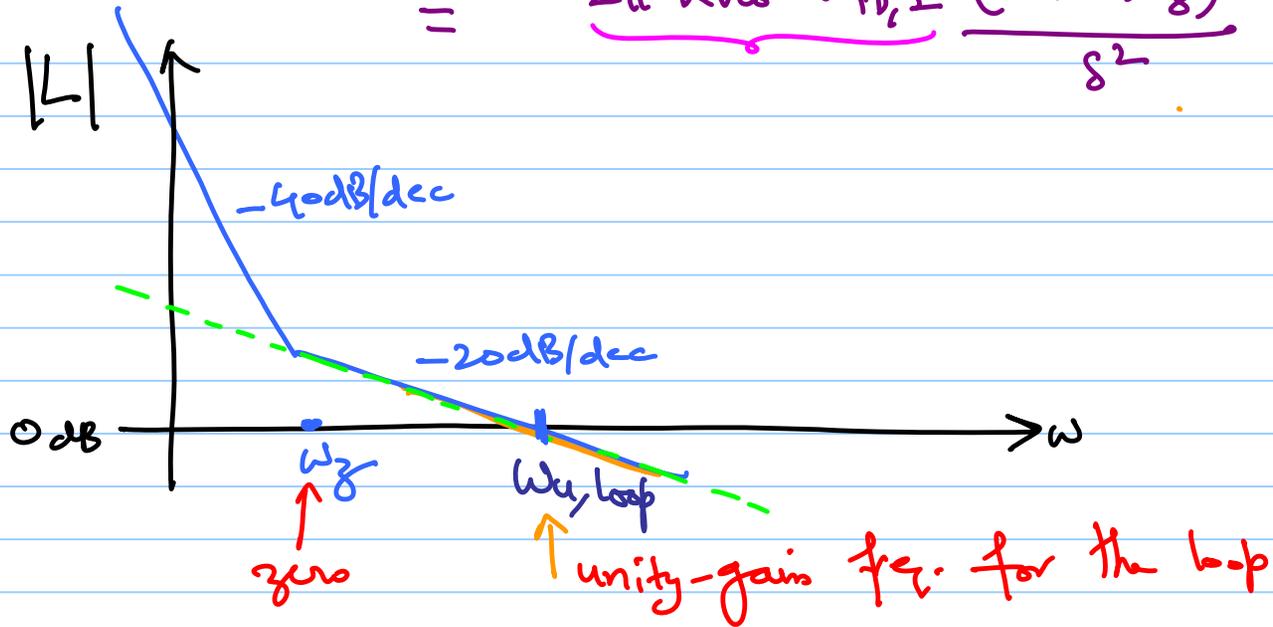
order  $\neq$  Type

$$\begin{aligned}
 L(s) &= \left( K_{PD} + \frac{K_{PD,I}}{s} \right) \cdot \frac{2\pi K_{VCO}}{s} \cdot \frac{1}{N \cdot s^2} \\
 &= \frac{2\pi K_{VCO} K_{PD,I}}{N \cdot s^2} \left( 1 + \frac{s K_{PD}}{K_{PD,I}} \right)
 \end{aligned}$$

$$= \underbrace{2\pi K_{vco} \cdot K_{PD,I}}_{\text{}} \frac{(1 + s/\omega_z)}{s^2}$$

$$\zeta = -\frac{K_{PD,I}}{K_{PD}}$$

$$\omega_z = \frac{K_{PD,I}}{K_{PD}}$$



Around  $\omega \approx \omega_{c, \text{loop}}$

$$\text{if } \frac{s}{\omega_z} \approx \frac{s}{\omega_p}, \quad \therefore \omega \gg \omega_z$$

$$L(s) \approx \frac{2\pi K_{vco} K_{p0, I} \cancel{s} \times \cancel{s}}{N \cancel{\omega_z}} = \frac{2\pi K_{vco} K_{p0}}{N} \cdot \frac{1}{s}$$

↳ approx as a first-order system

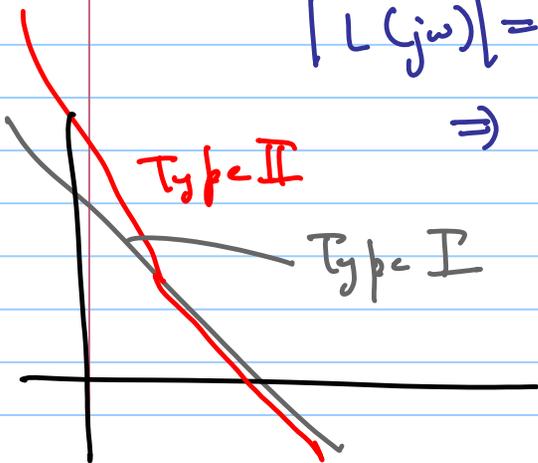
$$|L(j\omega)| = 1$$

⇒

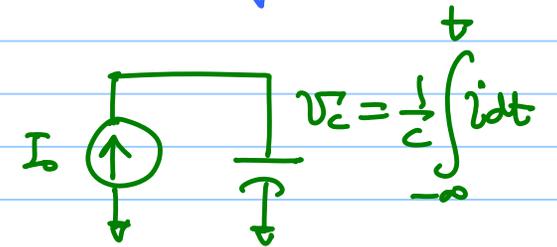
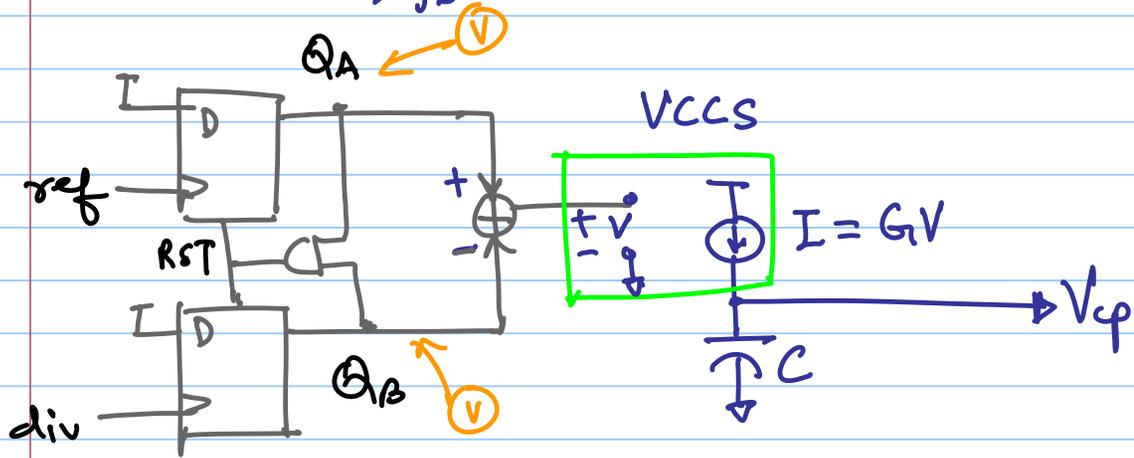
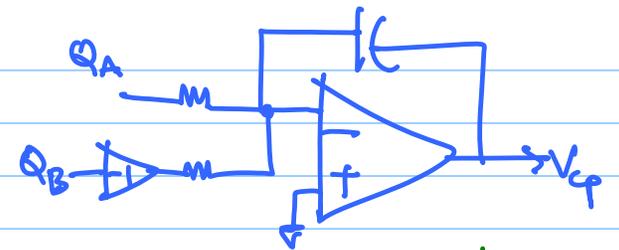
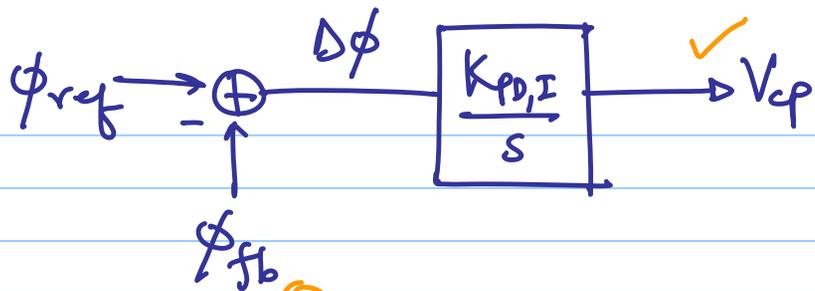
$$\omega_{c, \text{loop}} \approx \frac{2\pi K_{vco} K_{p0}}{N}$$

valid only for

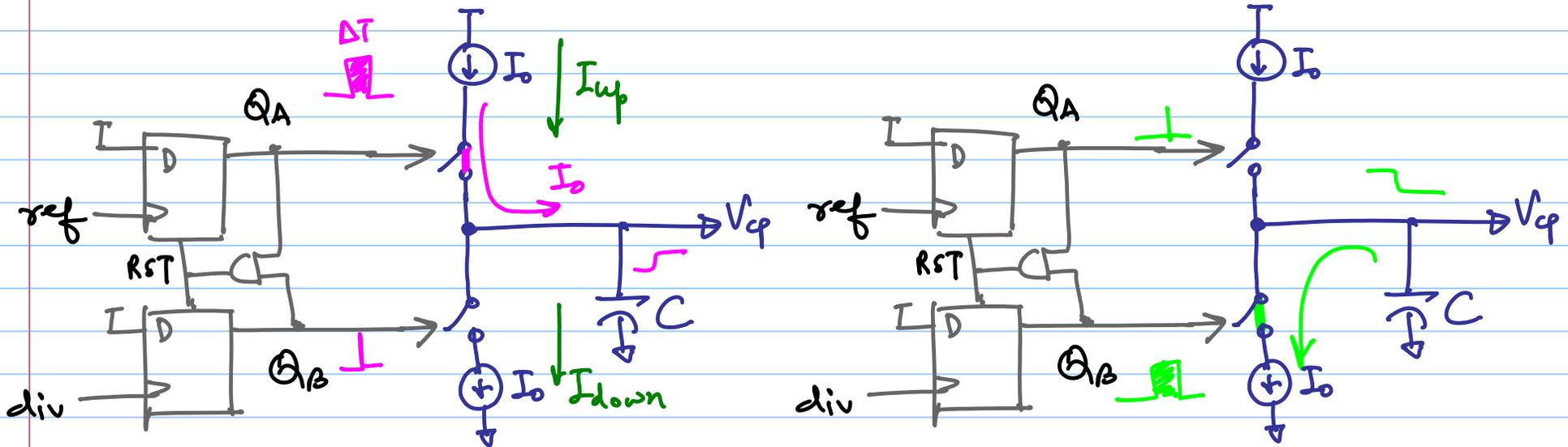
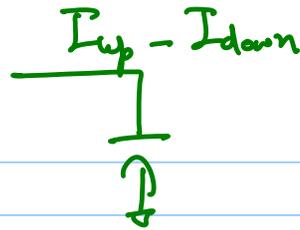
$$\omega_{c, \text{loop}} \gg \omega_z$$



↳ Same as the Type-I PLL  
↳ but more gain at DC ⇒  $\Delta\phi \rightarrow 0$

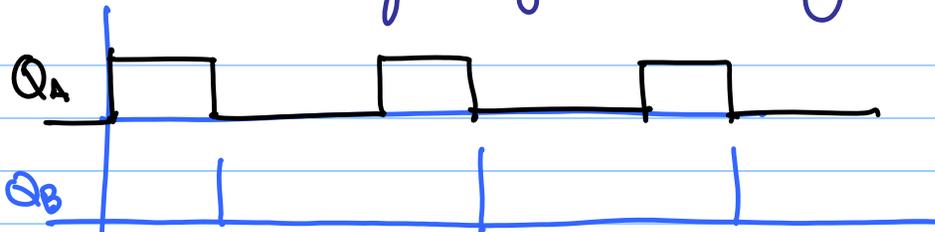


charge pump PLL



- \* push current when  $Q_A > 0$
- \* pull current when  $Q_B > 0$

Lets say ref is leading div in every cycle



Hybrid DT-CT systems  
↳ precise analysis is very challenging



looks like a sampled system

↳  $V_{cp}$  is not CT in nature

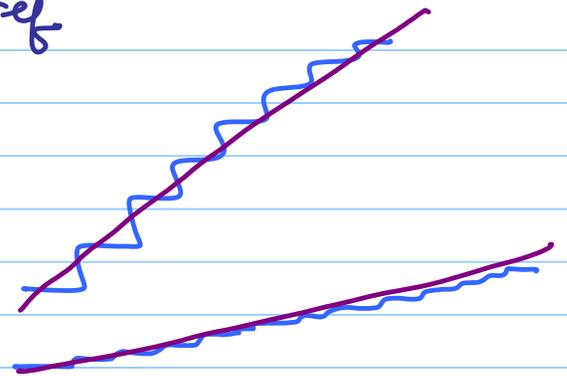
We can approximate this system as CT for analysis  
as long as  $\omega_{\text{loop}} \ll \omega_{\text{ref}}$

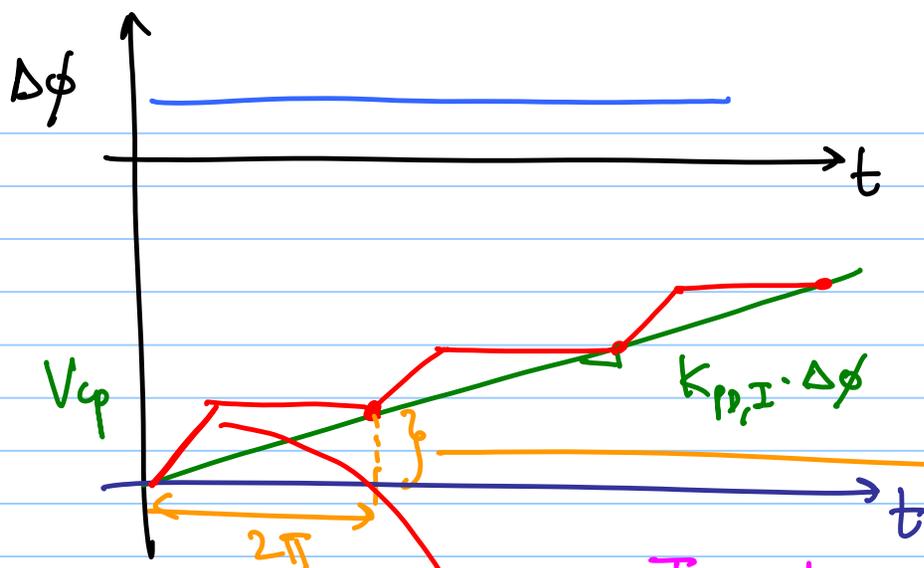
↳  $\omega_{\text{loop}} \leq \frac{\omega_{\text{ref}}}{10}$

Rule of thumb

so that PLL has approx CT dynamics

↳ PLL response is much slower than the frequency of  
phase detection ( $\omega_{\text{ref}}$ )



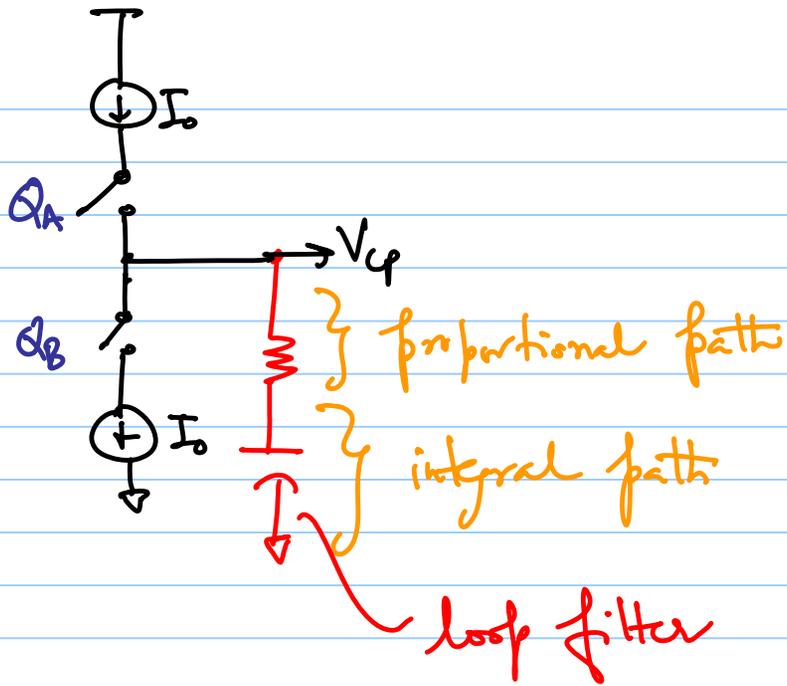


$$K_{pd,I} \Delta\phi 2\pi$$

$$\frac{I_0 \Delta\phi}{C}$$

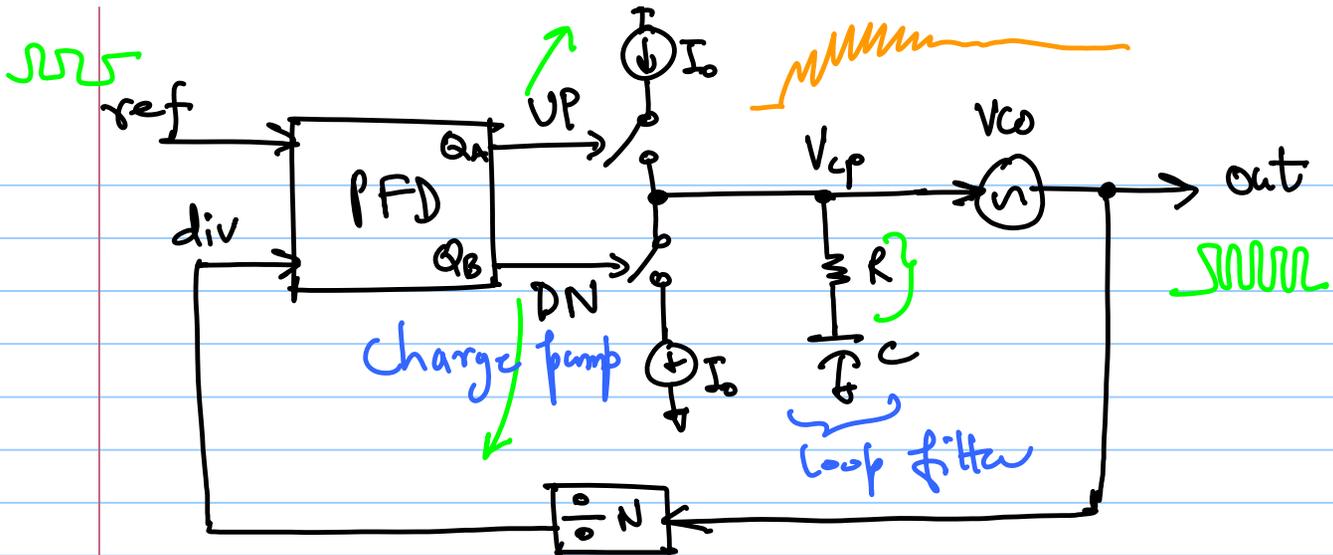
$$K_{pd,I} \cdot \cancel{\Delta\phi} \cdot 2\pi = \frac{I_0}{C} \cancel{\Delta\phi}$$

$$K_{pd,I} = \frac{I_0}{2\pi C}$$



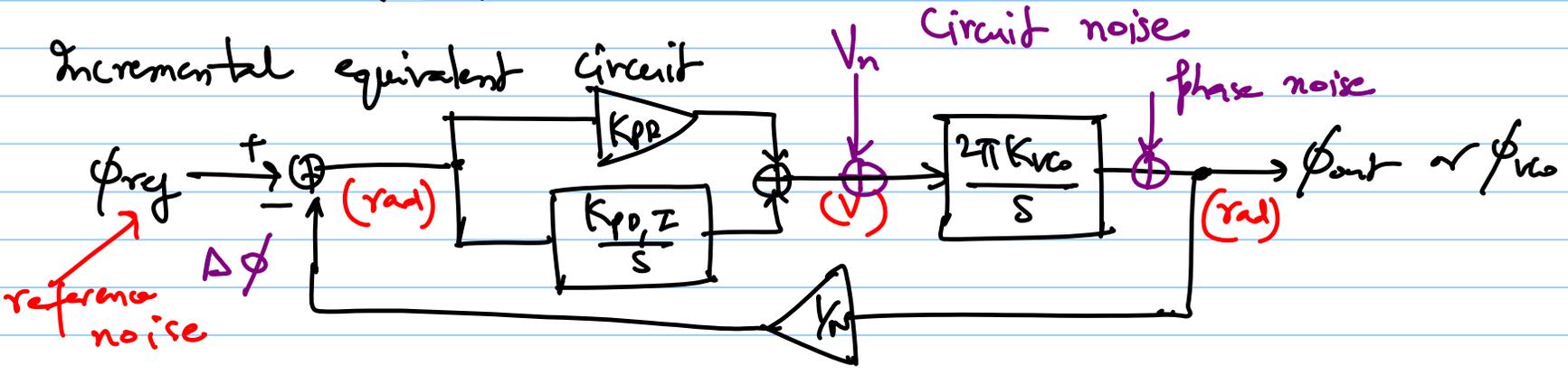
By the same logic as  $K_{PD,I} = \frac{I_0}{2\pi C}$

$$K_{PD} = \frac{I_0 R}{2\pi}$$



# Type-II PLL

UP  $\Rightarrow$  increment  $V_{CO}$  frequency  
 DN  $\Rightarrow$  decrement  $V_{CO}$  frequency



$$L(s) = \left( \frac{I_0 T}{2\pi} + \frac{I_0}{2\pi s C} \right) \frac{2\pi K_{vco}}{s}$$

$$\omega_z = \frac{1}{RC}$$

$$\omega_{n, loop} \approx \left( \frac{K_{vco} I_0 R}{N} \right)^{1/2},$$

$$\omega_{n, loop} \Rightarrow \omega_z$$