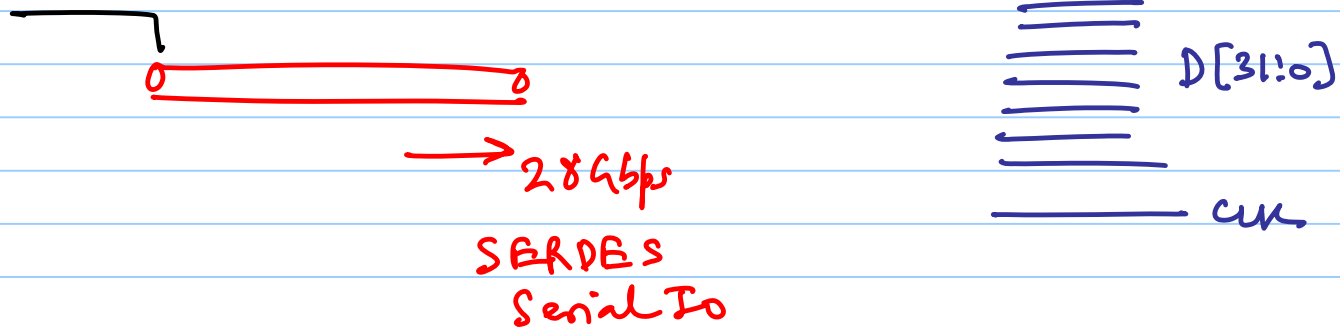
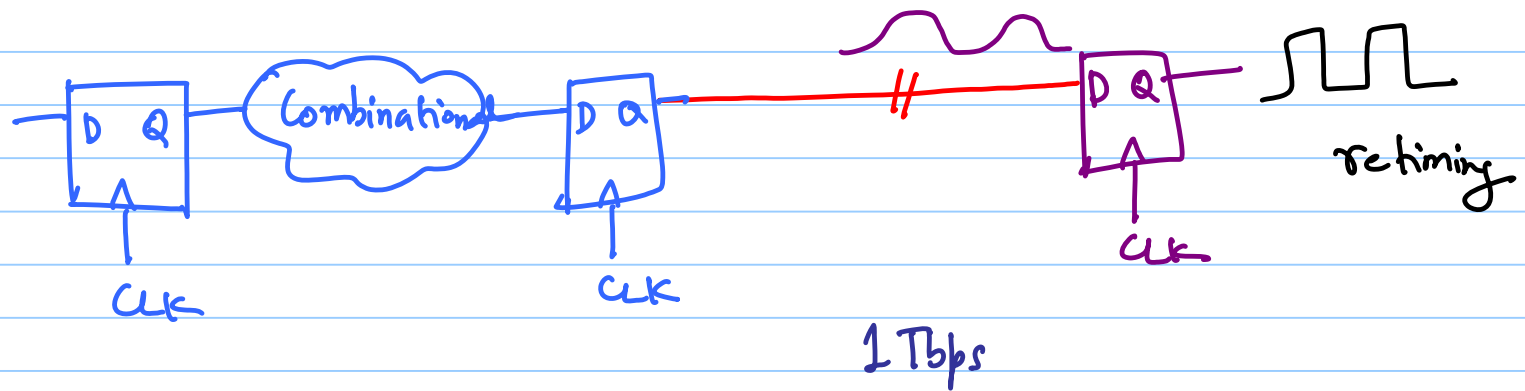
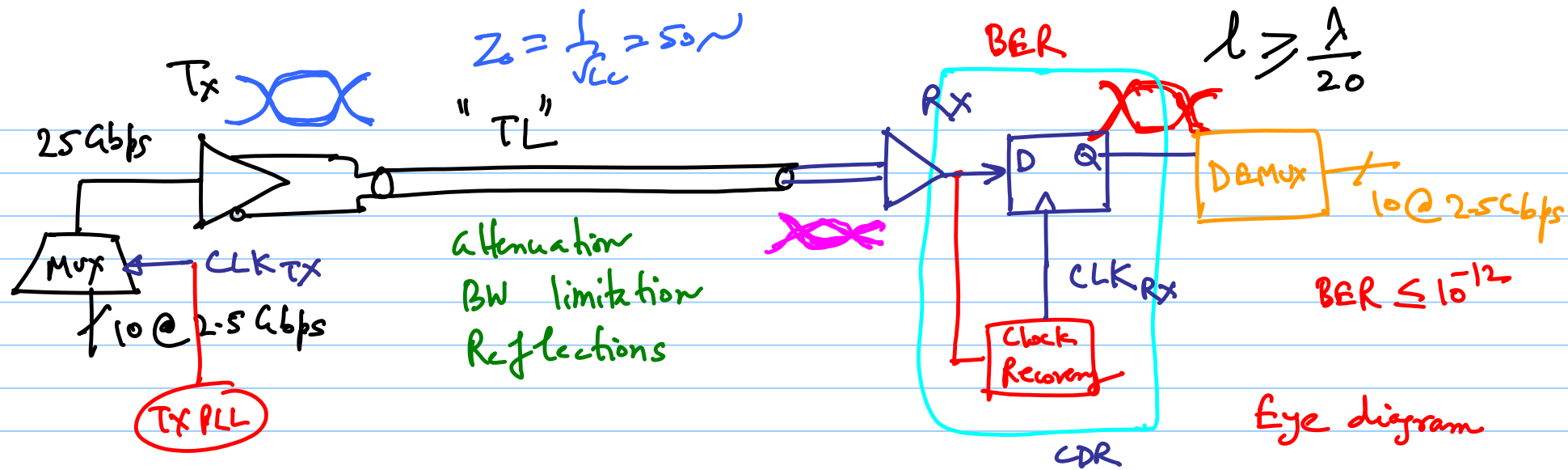


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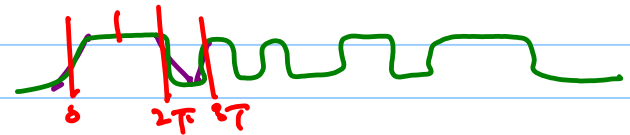
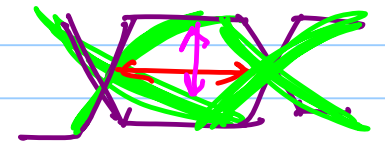
Note Title

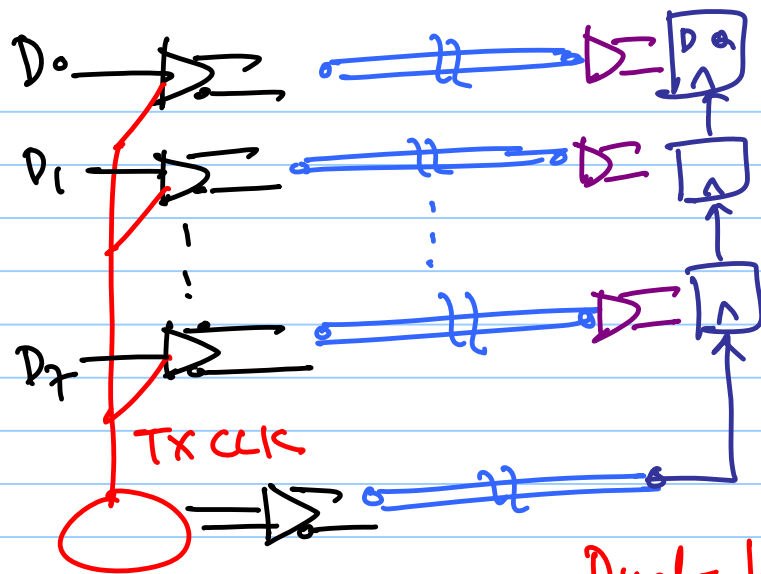
11/16/2016





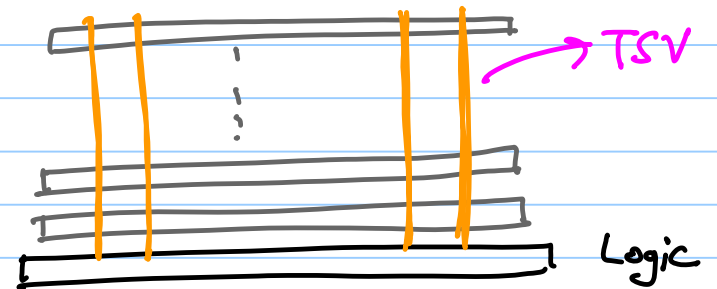
- ① CDR → recover clock & sample incoming data
- ② local PLL at Rx at known frequency
- ③ clock forwarding



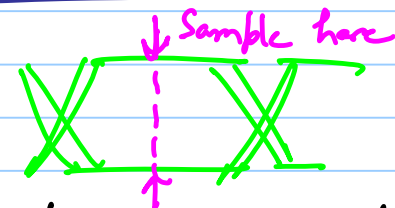
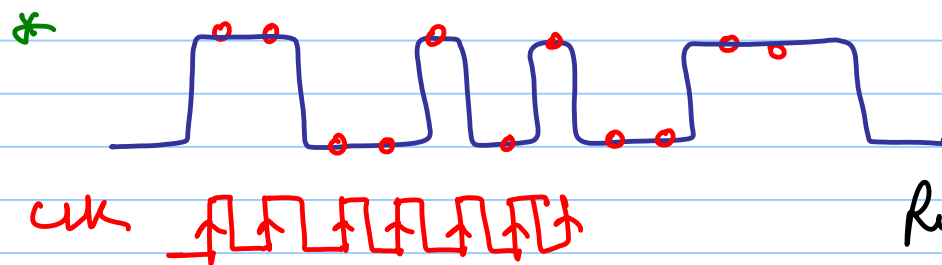
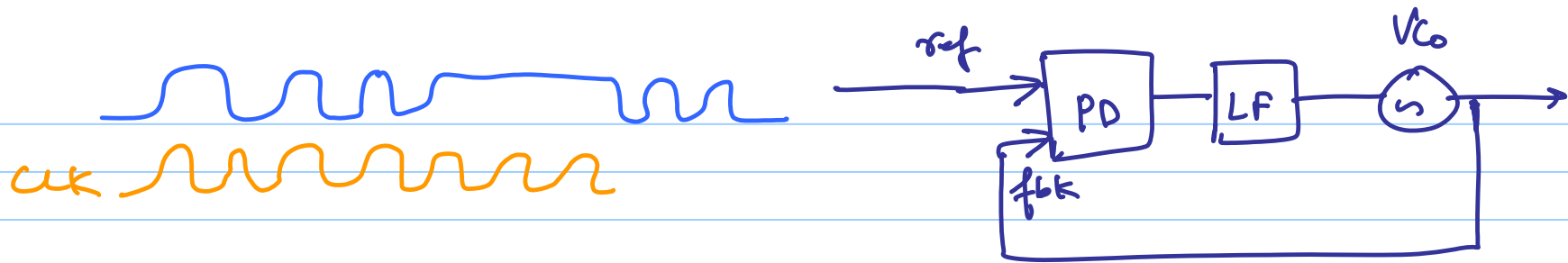


Dual-loop CDR
 ↳ separate

HMC / 3DIC



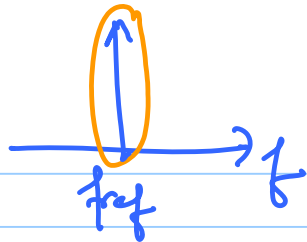
clock generation + phase alignment



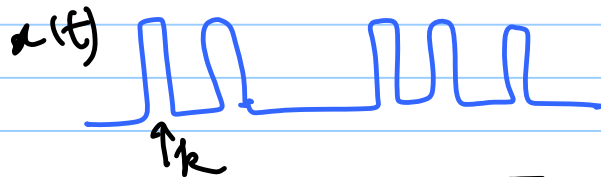
Rising edge of the recovered clock should align with the middle of the bit period (i.e. center of the data)

↳ provides maximum margin for jitter & other error

* the recovered clock should have low jitter

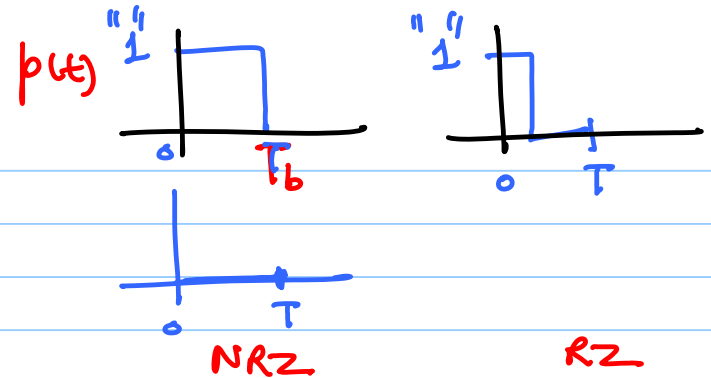


⇒ Random NRZ data

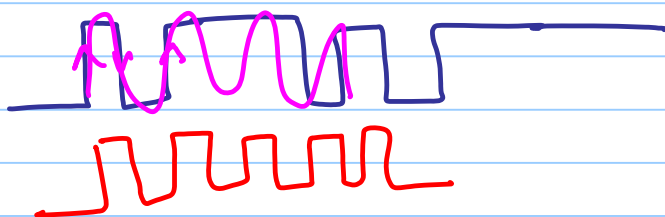
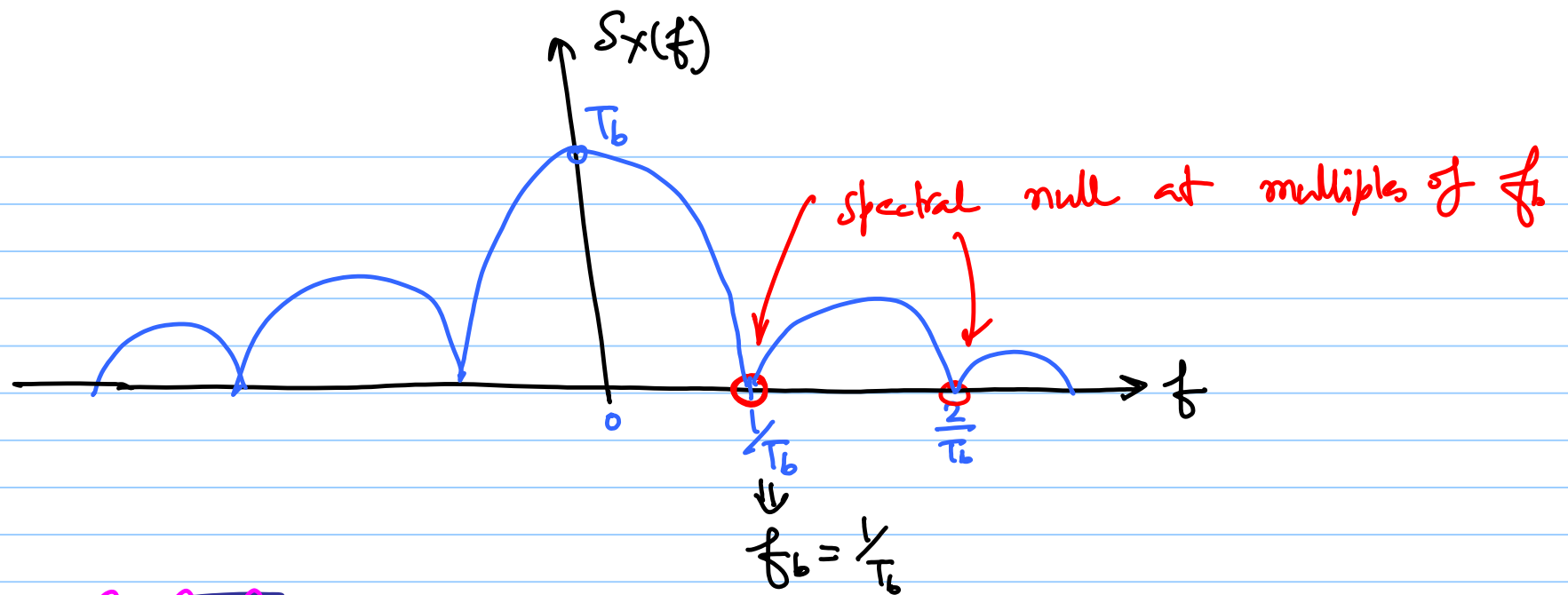


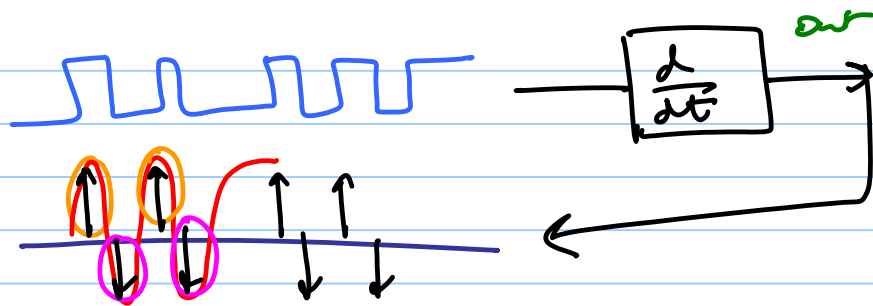
$$x(t) = \sum_k \underbrace{b_k}_{\text{random bit stream}} \underbrace{p(t - kT_b)}_{\text{NRZ}}$$

PSD: $S_x(f) = T_b \cdot \text{Sinc}^2(f \cdot T_b)$



$$\text{Sinc}(x) = \frac{\text{Sinc}(\pi x)}{\pi x}$$

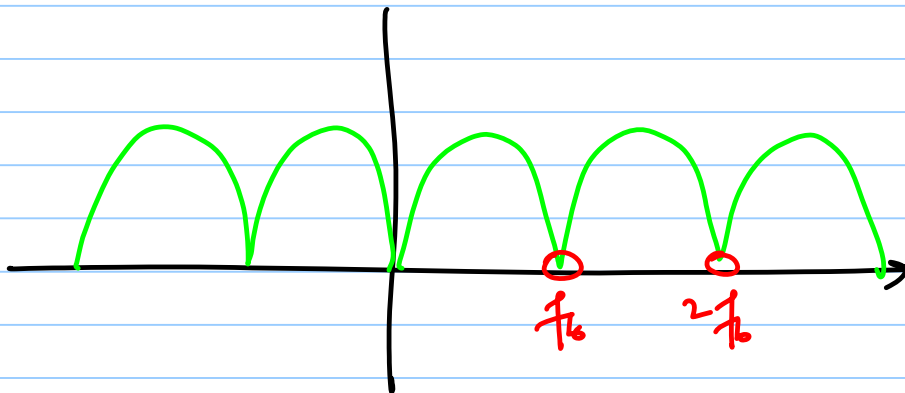




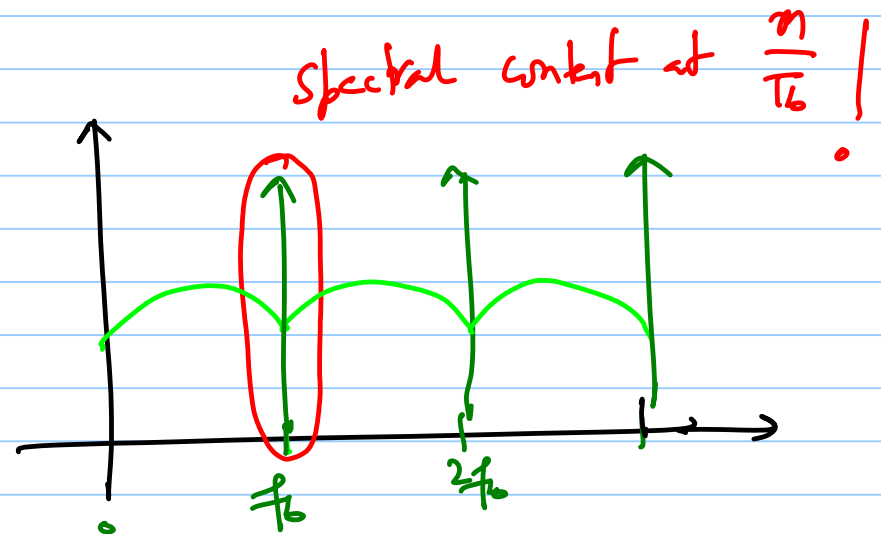
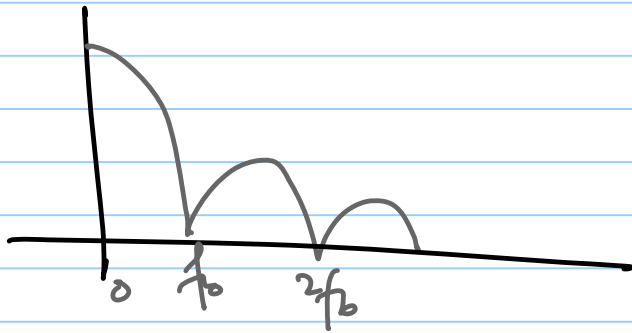
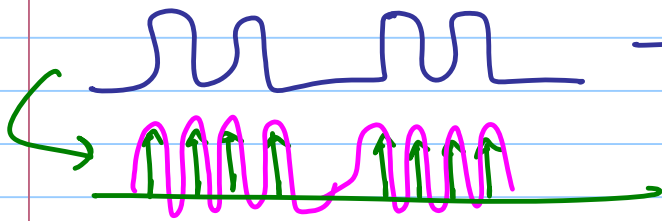
$$\frac{d}{dt} x(t) \xrightarrow{f} (2\pi f) X(f)$$

$$S_{\text{out}}(f) = (2\pi f)^2 \left(\frac{\sin(\pi f T_b)}{\pi f T_b} \right)^2$$

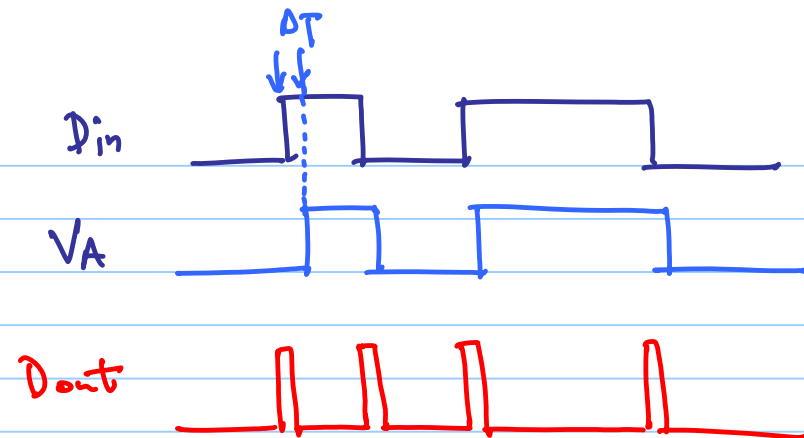
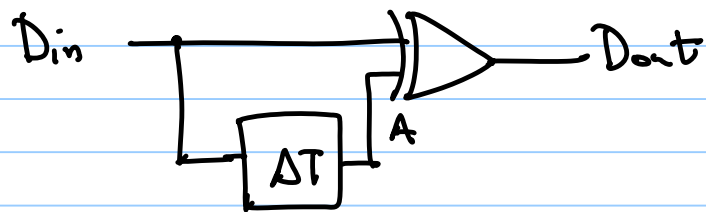
$$= \left[\frac{2 \sin(\pi f T_b)}{T_b} \right]^2$$



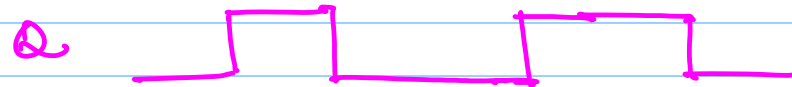
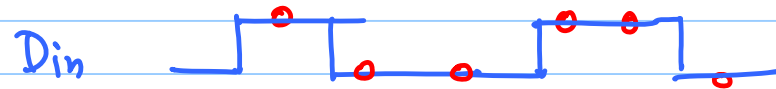
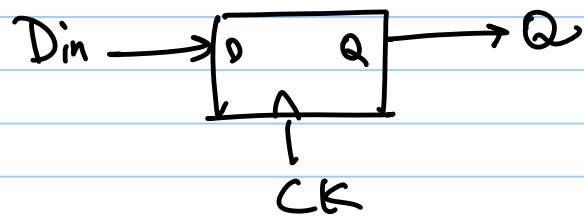
Edge detection
FW rectification



Edge Detector:



* How about DFF for phase detection?



① Hogge PD!

