



BLAST-A Model Checker for C

Developed by

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BLAST Installation

- Currently version 2.0 src files available.
- <http://mtc.epfl.ch/software-tools/blast/>
- Installation
 - Download Simplify theorem prover
<http://www.cs.virginia.edu/~weimer/615/hw.html>
 - Either build from src files or use Linux binaries.
 - A “working” example configuration for compiling Blast 2.0 is OCaml 3.08.3 and gcc (GCC) 3.4.4 20050721 (Red Hat 3.4.4-2).



Features

- 👉 “On the Fly” Abstraction
- 👉 Automatic abstraction
- 👉 Smarter predicate discovery
- 👉 Verify safety properties, assertion violations
- 👉 Finding reachable program locations
- 👉 Detecting dead code
- 👉 Reuse saved abstractions



Problems

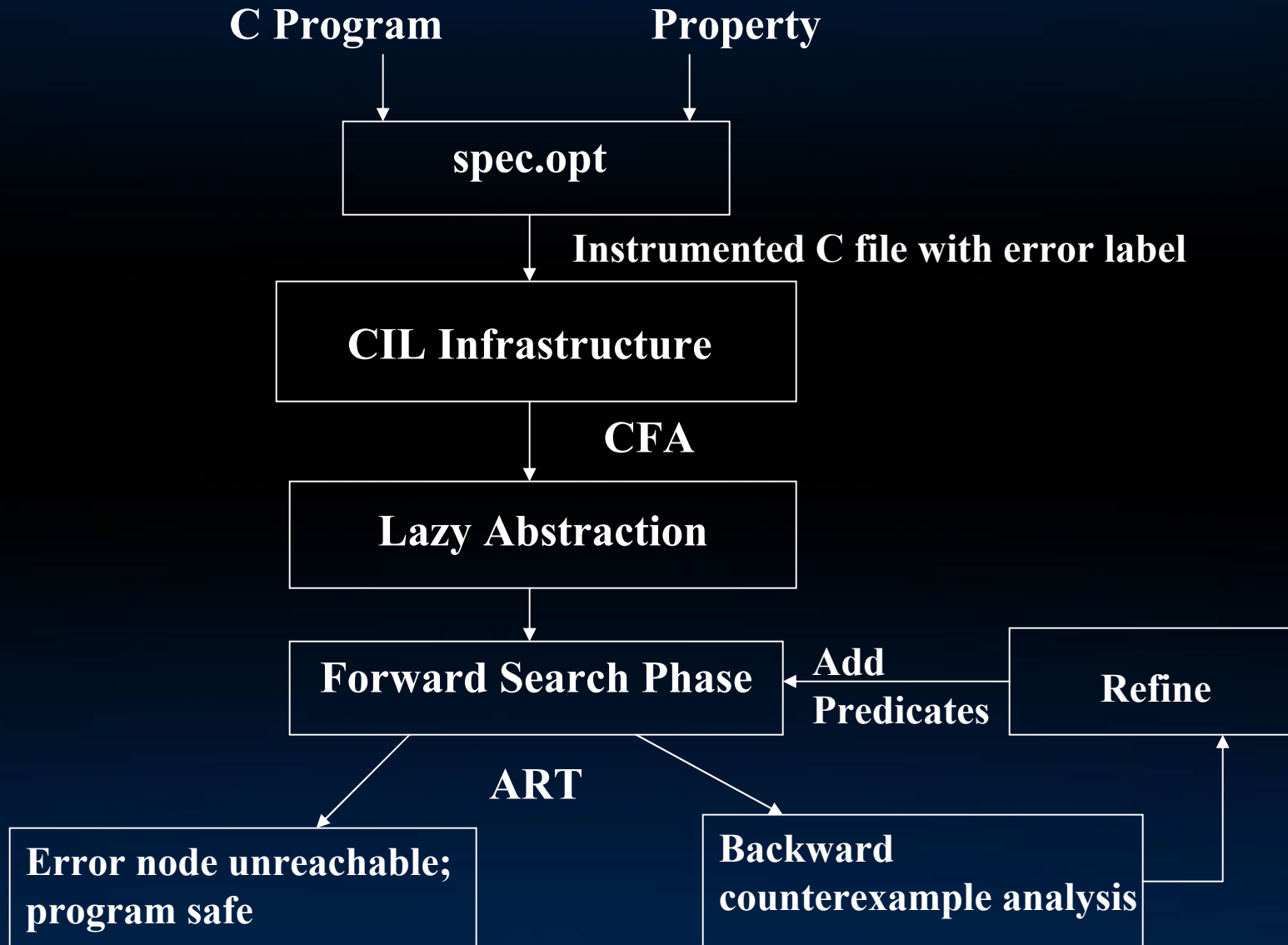
- ✎ Installing and making it work
- ✎ Predicate discovery not good enough.
- ✎ Checking concurrent programs
- ✎ Eclipse plugin
- ✎ Checking recursive functions



BLAST working

- Build an abstract model using predicate abstraction.
- Check for reachability of a specified label using the abstract model.
- If no path to ERR node-system safe.
- If path is feasible, output error trace.
- Else use infeasibility of path to refine abstract model.

BLAST working





Problem: Abstraction is expensive

- # of abstract states = $2^{\# \text{ of predicates}}$
- Solution 1: Only abstract reachable states
- Solution 2: Don't refine any error free states
- Advantages:
 - State space only refined as much as required.
 - Reuse previously defined error free states.

Lazy Abstraction

- Integrate the following
 - Abstraction
 - Verification
 - Counterexample-driven refinement
- Find pivot state.
- Construct, verify and refine abstract model “on the fly” from pivot state on.
- Forward Search Phase and Backward Counterexample analysis.
- Stop when either real counterexample found or system found safe

Locking example

```
Example() {
1:  if (*){
7:    do {
        got_lock = 0;
8:      if (*){
9:        lock();
        got_lock++;
        }
10:     if (got_lock){
11:       unlock();
        }
12:   } while (*)
    }
2:  do {
        lock();
        old = new;
3:    if (*){
4:      unlock();
        new++;
        }
5:  } while (new != old);
6:  unlock();
    return;
}
```

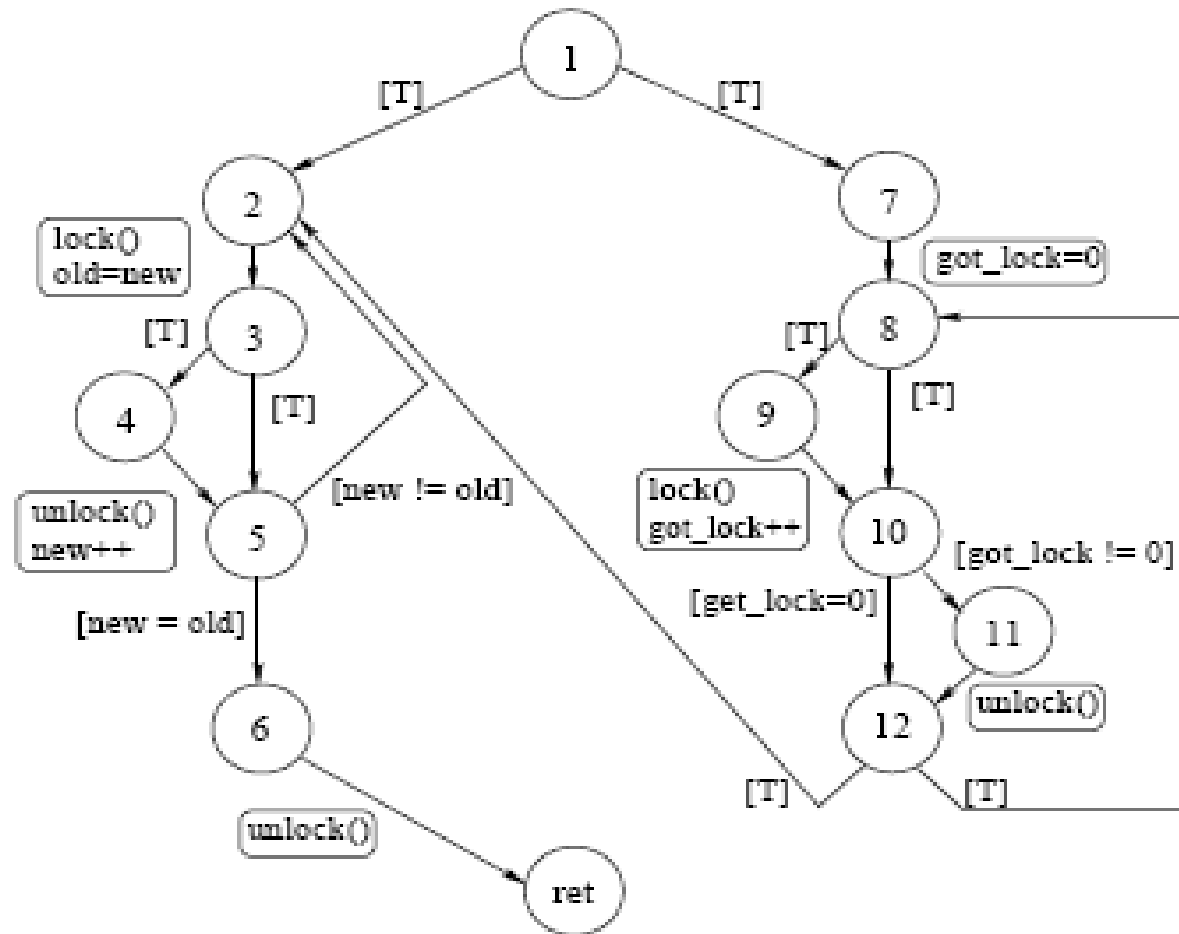
```
lock(){
    if (LOCK == 0){
        LOCK = 1;
    } else {
        ERROR
    }
}

unlock(){
    if (LOCK == 1){
        LOCK = 0;
    } else {
        ERROR
    }
}
```

Control Flow Automaton

- Local and global variables of C program
- Vertices: control locations of a function.
- Labeled directed edges
 - Basic block of instructions.
 - Assume predicate for branch condition.
- Formally, CFA is a tuple $\langle Q, q_0, X, Ops, \rightarrow \rangle$
 - Q - finite set of control locations
 - q_0 -initial control location
 - X - set of variables
 - Ops - set of operations on X ($lval = exp$ or $[p]$)
 - $\rightarrow (Q \times Ops \times Q)$

Control Flow Automaton

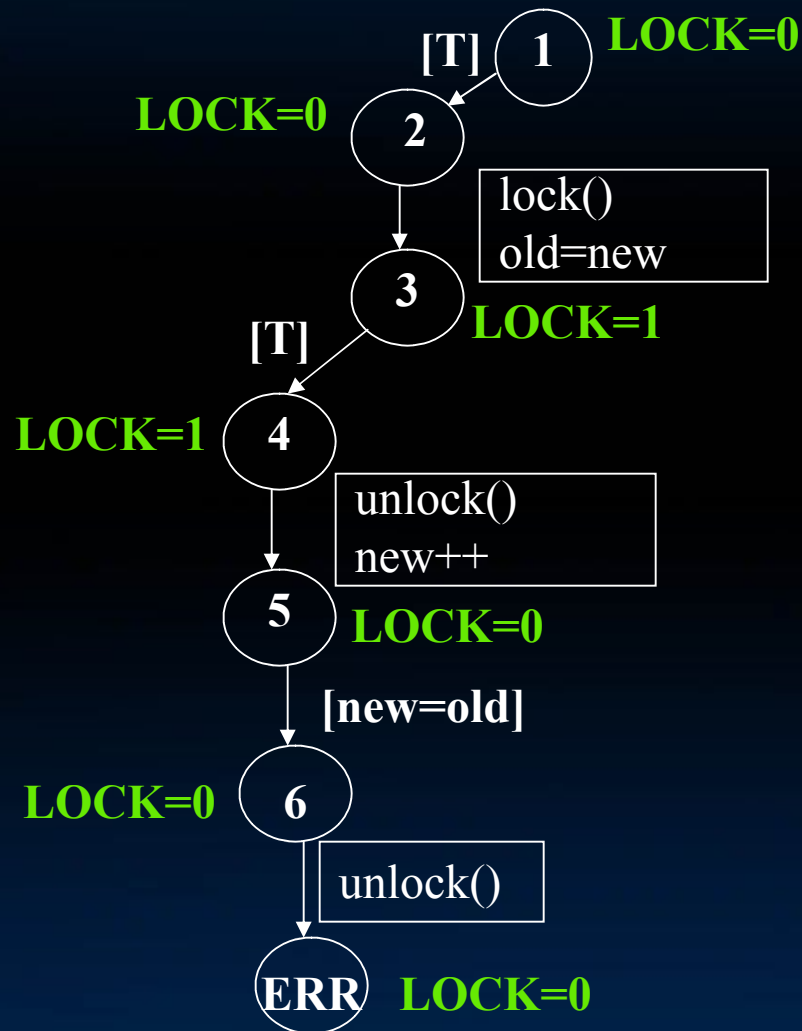




Forward Search Phase

- Abstract reachability tree in dfs order.
- Constructed from CFA.
- Vertices in CFA are nodes in ART.
- Labels of nodes are reachable regions.
- Reachable region obtained from parent's reachable region and instructions on the edge between them.
- Finite set of predicates per node.
- Reachable region is a boolean combination of set of predicates

Forward Search for locking example



Is this a valid counterexample??

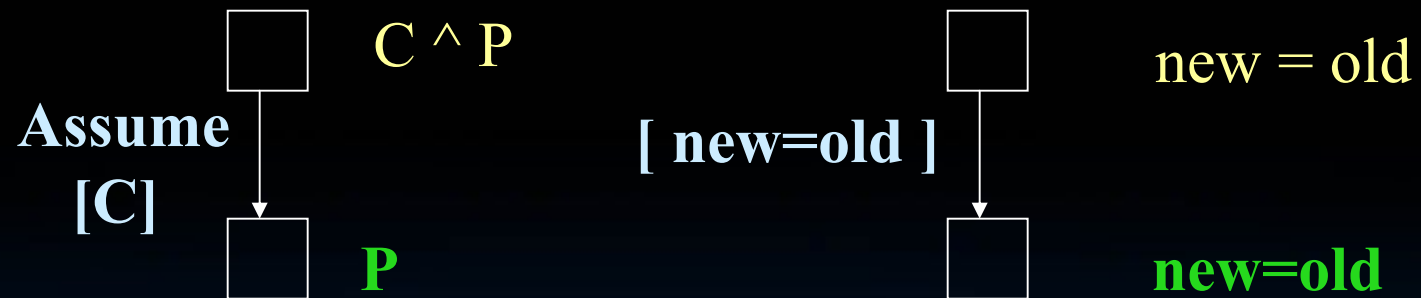
Weakest Precondition

- $WP(P, Op)$ –weakest formula P' s.t. if P' is T before Op , then P is T after Op



Weakest Precondition

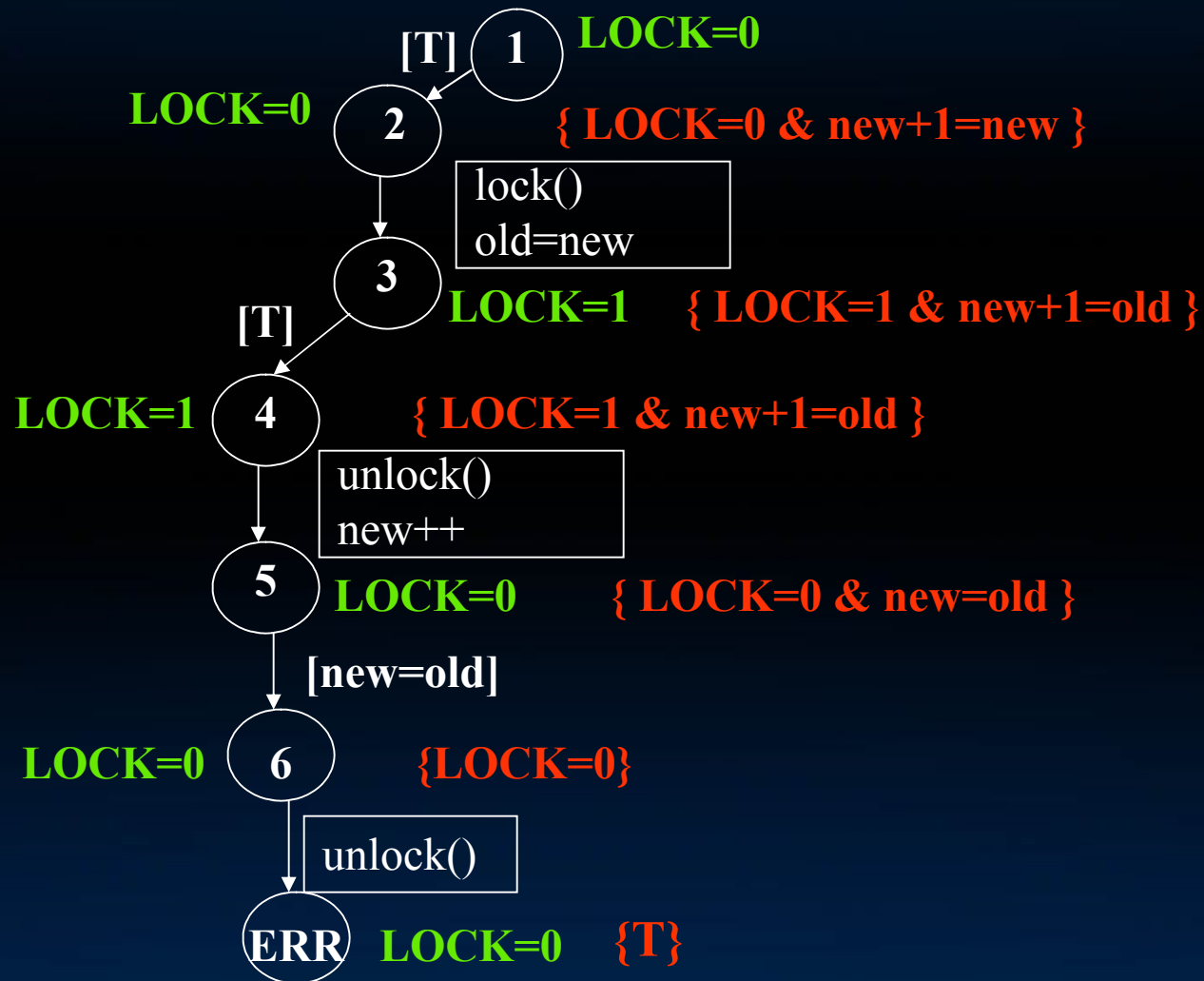
- $WP(P, Op)$ –weakest formula P' s.t. if P' is T before Op , then P is T after Op



Backward Counterexample Analysis

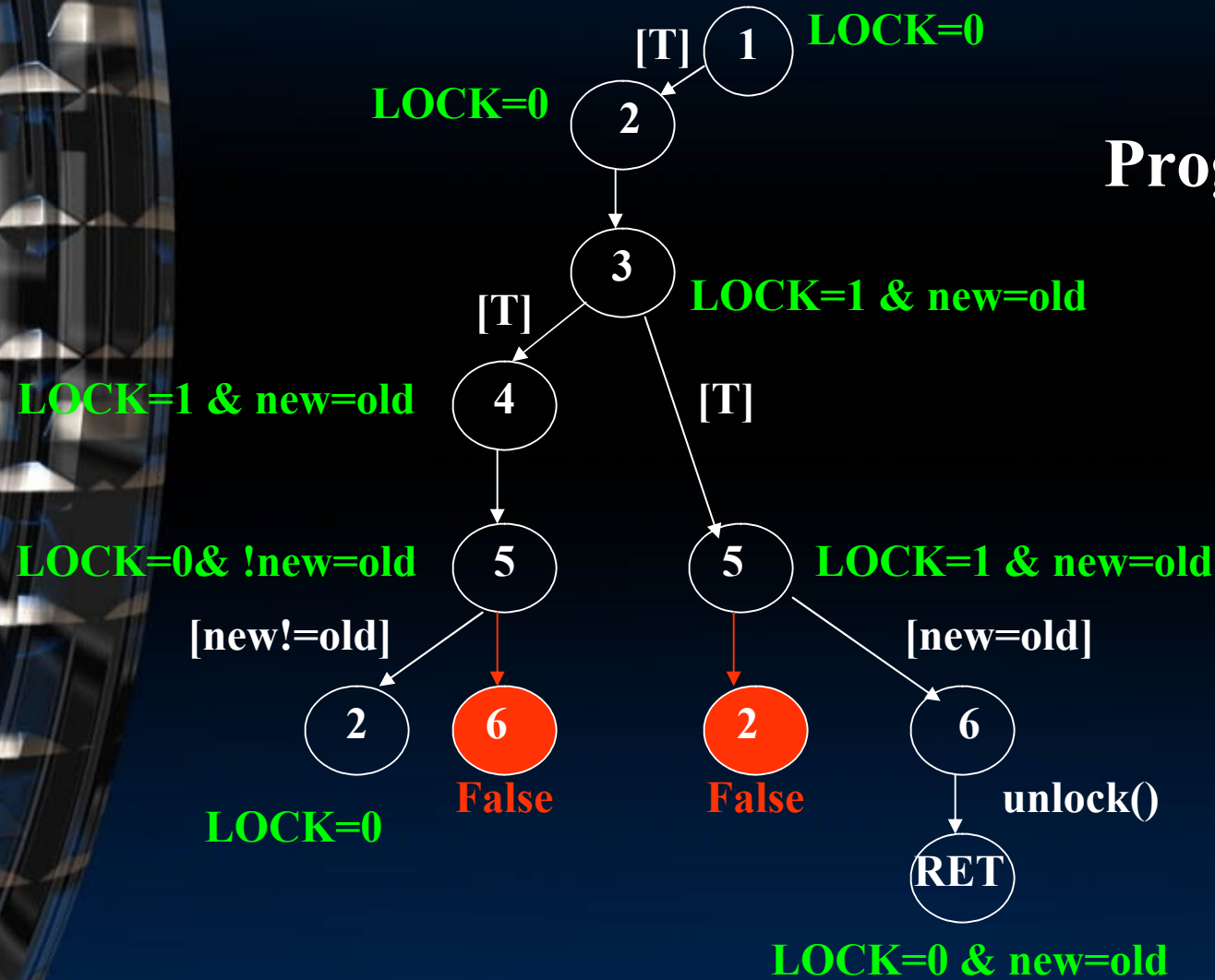
- For each tree node, find a bad region.
- Bad region of ERR node = T
- Other nodes = WP of bad region of child w.r.t instructions on edge between the 2.
- Start from ERR node
- Pivot node - First node in the tree where Bad region \cap Reachable region = \emptyset
- Refine abstraction from pivot node onwards

Counter example analysis for locking program



Searching with new predicate new=old

Program Safe!!



Finding Predicates

- Problem: How many predicates to find?
of predicates grows with program size

```
while(*){  
1:   if (p1) lock ();  
     if (p1) unlock ();  
     ...  
2:   if (p2) lock ();  
     if (p2) unlock ();  
     ...  
n:   if (pn) lock ();  
     if (pn) unlock ();  
}
```

p1 {
p2 {
pn {

Solution: Use
predicates **only where
needed**

2^n abstract states!!

$2n$ abstract states

Counter example Traces

Theorem: Trace formula is satisfiable iff trace is
Trace formula is a conjunction of constraints, one
per instruction in the trace.

```
1: x=ctr;  
2: ctr=ctr+1;  
3: y=ctr;  
4: if (x=i-1) {  
5:   if (y!=i){  
        ERROR;  
      }  
}
```

Sample program

```
1: x=ctr;  
2: ctr=ctr+1;  
3: y=ctr;  
4: assume (x=i-1)  
5: assume (y!=i)
```

Counter example
trace

```
1:  $x_1 = ctr_0$   
2:  $ctr_1 = ctr_0 + 1$   
3:  $y_1 = ctr_1$   
4:  $x_1 = i_0 - 1$   
5:  $y_1 \neq i_0$ 
```

Trace Formula φ

Steps in Refine Stage

Counter example
trace



Trace formula



Theorem Prover



Proof of
Unsatisfiability




Interpolate



Predicate Map

Finding what predicates are needed

Trace	Trace Formula	What predicate is needed for trace to become infeasible
1: $x=ctr$; 2: $ctr=ctr+1$; 3: $y=ctr$;	1: $x_1=ctr_0$ 2: $ctr_1=ctr_0+1$ 3: $y_1=ctr_1$	
4: assume ($x=i-1$) 5: assume ($y!=i$)	4: $x_1=i_0-1$ 5: $y_1!=i_0$	

Given an infeasible trace t , find a set of predicates P , such that t is abstractly infeasible w.r.t P .

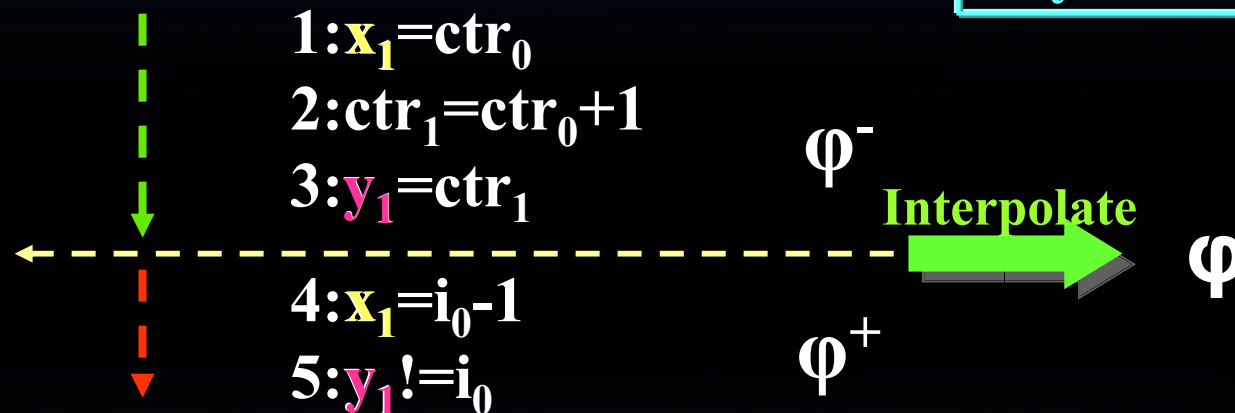
Finding what predicates are needed

- Partition ϕ into ϕ^- (trace prefix) and ϕ^+ (trace suffix)
- Find an interpolant Ψ s.t.
 - ϕ^- implies Ψ
 - $\Psi \wedge \phi^+$ is unsatisfiable.
 - The variables of Ψ are common to both ϕ^- and ϕ^+
- Use interpolant to construct predicate map.

Interpolant = Predicate

Trace Formula

Predicate at 4:
 $y=x+1$



Predicate is

..implied by Trace formula
prefix

..on common variables

..makes Trace Formula
suffix unfeasible

Finding predicate map

- Partition at each point
- Interpolate at each partition
- Construct predicate map $pc_i \mapsto$ Interpolant from partition i

Trace
1: $x=ctr$;
2: $ctr=ctr+1$;
3: $y=ctr$;
4: $assume(x=i-1)$
5: $assume(y!=i)$

Trace Formula

1: $x_1=ctr_0$ φ^-
2: $ctr_1=ctr_0+1$ φ^+
3: $y_1=ctr_1$
4: $x_1=i_0-1$
5: $y_1!=i_0$

Interpolate

$x_1=ctr_0$

Predicate Map
2: $x_1=ctr_0$

Finding predicate map

- Partition at each point
- Interpolate at each partition
- Construct predicate map $pc_i \mapsto$ Interpolant from partition i

Trace

1: $x=ctr$;
2: $ctr=ctr+1$;
 ←-----
3: $y=ctr$;
4: assume ($x=i-1$)
5: assume ($y!=i$)

Trace Formula

1: $x_1=ctr_0$
2: $ctr_1=ctr_0+1$ φ^-
 -----→ **Interpolate** $x_1=ctr_1-1$
 φ^+
3: $y_1=ctr_1$
4: $x_1=i_0-1$
5: $y_1!=i_0$

Predicate Map

2: $x_1=ctr_0$
3: $x_1=ctr_1-1$

Finding predicate map

- Partition at each point
- Interpolate at each partition
- Construct predicate map $pc_i \mapsto$ Interpolant from partition i

Trace

1: $x=ctr$;
2: $ctr=ctr+1$;
3: $y=ctr$;
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4: assume ($x=i-1$)
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Trace Formula

1: $x_1=ctr_0$
2: $ctr_1=ctr_0+1$
3: $y_1=ctr_1$

4: $x_1=i_0-1$
5: $y_1!=i_0$

φ^-
 -----> **Interpolate** $y_1=x_1+1$
 φ^+

Predicate Map

2: $x_1=ctr_0$
3: $x_1=ctr_1-1$
4: $y_1=x_1+1$

Finding predicate map

- Partition at each point
- Interpolate at each partition
- Construct predicate map $pc_i \mapsto$ Interpolant from partition i

Trace

1: $x=ctr$;
2: $ctr=ctr+1$;
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←-----
5: assume ($y!=i$)

Trace Formula

1: $x_1=ctr_0$
2: $ctr_1=ctr_0+1$
3: $y_1=ctr_1$
4: $x_1=i_0-1$
5: $y_1!=i_0$

φ^-
-----> **Interpolate** $y_1=i_0$
 φ^+

Predicate Map

2: $x_1=ctr_0$
3: $x_1=ctr_1-1$
4: $y_1=x_1+1$
5: $y_1=i_0$



BLAST Specification language

- Include directives
- Global variables
- Shadowed types
- Events
 - Pattern
 - Guard
 - Action/Repair
 - Before/After



References

- “Abstractions from Proofs”-Thomas .H et al.
- “The Blast query language for software verification”- Dirk Beyer et al.
- “Lazy Abstraction”-Gregoire Sutre et al.