### Summary of Memory Layout

- Most details abstracted away by IR format.
- · Remember:
  - Parameters start at fp + 4 and grow upward.
  - Locals start at fp 8 and grow downward.
  - Globals start at **gp** + **0** and grow upward.
- You will need to write code to assign variables to these locations.

## Data Representations

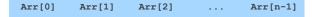
- What do different types look like in memory?
- Machine typically supports only limited types:
  - Fixed-width integers: 8-bit, 16-bit- 32-bit, signed, unsigned, etc.
  - Floating point values: 32-bit, 64-bit, 80-bit IEEE 754.
- How do we encode our object types using these types?

### **Encoding Primitive Types**

- Primitive integral types (byte, char, short, int, long, unsigned, uint16\_t, etc.) typically map directly to the underlying machine type.
- Primitive real-valued types (float, double, long double) typically map directly to underlying machine type.
- Pointers typically implemented as integers holding memory addresses.
  - Size of integer depends on machine architecture; hence 32-bit compatibility mode on 64-bit machines.

## Encoding Arrays

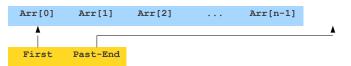
· C-style arrays: Elements laid out consecutively in memory.



• Java-style arrays: Elements laid out consecutively in memory with size information prepended.



• D-style arrays: Elements laid out consecutively in memory; array variables store pointers to first and past-the-end elements.



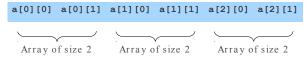
· (Which of these works well for Decaf?)

### Encoding Multidimensional Arrays

- Often represented as an array of arrays.
- · Shape depends on the array type used.
- C-style arrays:

  int a[3][2];

  How do you know where to look for an element in an array like this?



## Encoding Multidimensional Arrays

- Often represented as an array of arrays.
- \* Shape depends on the array type used.
- Java-style arrays:



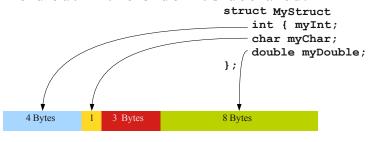
# Implementing Objects

## Objects are Hard

- It is difficult to build an expressive and efficient object-oriented language.
- Certain concepts are difficult to implement efficiently:
  - Dynamic dispatch (virtual functions)
  - Interfaces
  - · Multiple Inheritance
  - Dynamic type checking (i.e. instanceof)
- Interfaces are so tricky to get right we won't ask you to implement them in PP4.

### Encoding C-Style structs

- A **struct** is a type containing a collection of named values.
- Most common approach: lay each field out in the order it's declared.



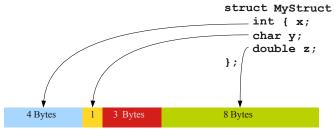
## Accessing Fields

- Once an object is laid out in memory, it's just a series of bytes.
- How do we know where to look to find a particular field?



- Idea: Keep an internal table inside the compiler containing the offsets of each field.
- To look up a field, start at the base address of the object and advance forward by the appropriate offset.

# Field Lookup



```
MyStruct* ms = new MyStruct;

ms->x = 137; store 137 0 bytes after ms

ms->y = 'A'; store 'A' 4 bytes after ms

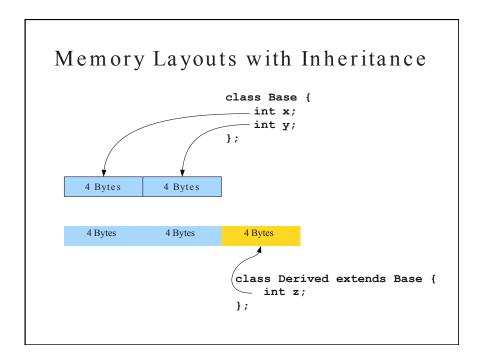
ms->z = 2.71 store 2.71 8 bytes after ms
```

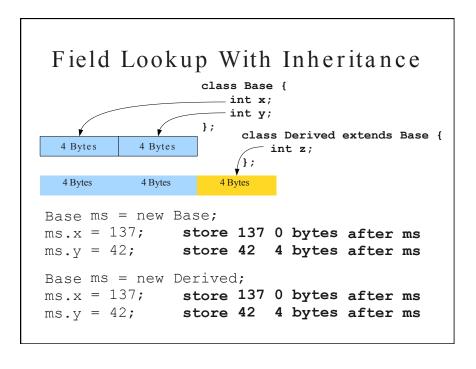
### OOP without Methods

```
    Consider the following Decaf code:
    class Base {
```

```
int x;
int y;
}
class Derived extends Base {
  int z;
}
```

• What will **Derived** look like in memory?





### Single Inheritance in Decaf

- The memory layout for a class D that extends B is given by the memory layout for B followed by the memory layout for the members of D.
  - Actually a bit more complex; we'll see why later.
- Rationale: A pointer of type B pointing at a D object still sees the B object at the beginning.
- Operations done on a D object through the B reference guaranteed to be safe; no need to check what B points at dynamically.

### What About Member Functions?

- Member functions are mostly like regular functions, but with two complications:
  - How do we know what receiver object to use?
  - How do we know which function to call at runtime (dynamic dispatch)?

## this is Tricky

- Inside a member function, the name this refers to the current receiver object.
- This information (pun intended) needs to be communicated into the function.
- Idea: Treat this as an implicit first parameter.
- Every n-argument member function is really an (n+1)-argument member function whose first parameter is the **this** pointer.

### this is Clever

```
class MyClass {
    int x;
    void myFunction(int arg) {
        this.x = arg;
    }
}
MyClass m = new MyClass;
m.myFunction(137);
```

### this is Clever

```
class MyClass {
    int x;
}
void MyClass_myFunction(MyClass this, int arg) {
    this.x = arg;
}
MyClass m = new MyClass;
m.myFunction(137);
```

### this is Clever

```
class MyClass {
    int x;
}
void MyClass_myFunction(MyClass this, int arg) {
    this.x = arg;
}
MyClass m = new MyClass;
MyClass_myFunction(m, 137);
```

#### this Rules

- •When generating code to call a member function, remember to pass some object as the **this** parameter representing the receiver object.
- Inside of a member function, treat **this** as just another parameter to the member function.
- •When implicitly referring to a field of **this**, use this extra parameter as the object in which the field should be looked up.

### Implementing Dynamic Dispatch

- Dynamic dispatch means calling a function at runtime based on the dynamic type of an object, rather than its static type.
- How do we set up our runtime environment so that we can efficiently support this?

### An Initial Idea

- At compile-time, get a list of every defined class.
- To compile a dynamic dispatch, emit IR code for the following logic:

if (the object has type A)
 call A's version of the function
else if (the object has type B)
 call B's version of the function

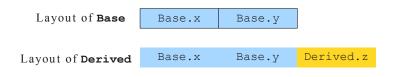
else if (the object has type N) call N's version of the function.

## Analyzing our Approach

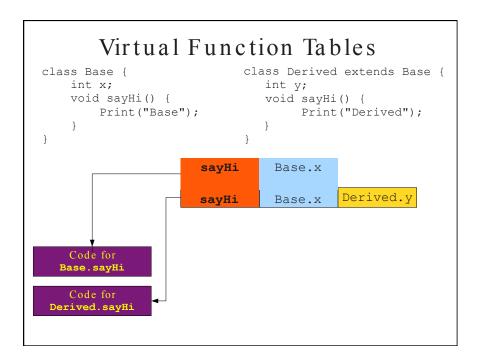
- This previous idea has several serious problems.
- · What are they?
- · It's slow.
  - Number of checks is O(C), where C is the number of classes the dispatch might refer to.
  - Gets slower the more classes there are.
- · It's infeasible in most languages.
  - · What if we link across multiple source files?
  - · What if we support dynamic class loading?

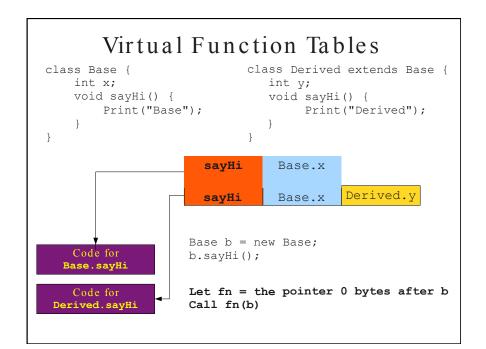
### An Observation

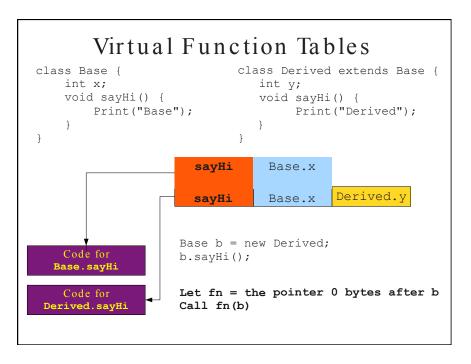
- When laying out fields in an object, we gave every field an offset.
- Derived classes have the base class fields in the same order at the beginning.



• Can we do something similar with functions?







### More Virtual Function Tables

#### More Virtual Function Tables class Base { class Derived extends Base int x; { int y; void sayHi() { Print("Hi Mom!"); Base clone() { Derived clone() { return new Base; return new Derived; Code for sayHi Base.sayHi clone Code for Base.clone Base.x Code for Derived.clone

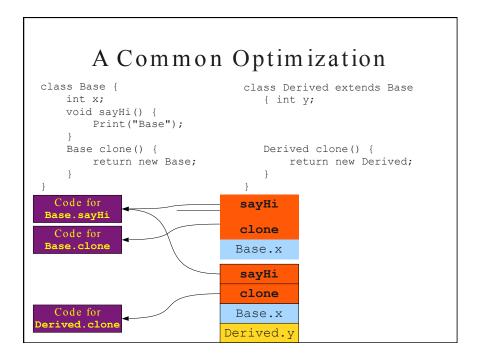
#### More Virtual Function Tables class Base { class Derived extends Base int x; { int y; void sayHi() { Print("Hi Mom!"); Base clone() { Derived clone() { return new Base; return new Derived; Code for sayHi Base.sayHi clone Code for Base.clone Base.x sayHi clone Code for Base.x Derived.clone Derived.y

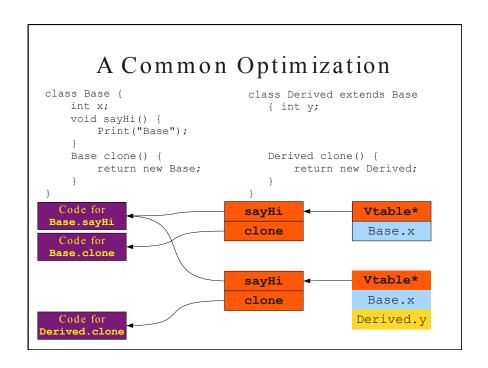
### Virtual Function Tables

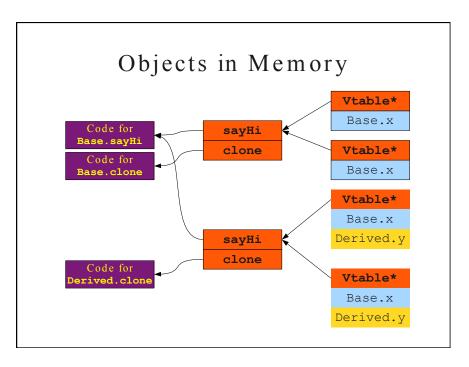
- A virtual function table (or vtable) is an array of pointers to the member function implementations for a particular class.
- To invoke a member function:
  - Determine (statically) its index in the vtable.
  - Follow the pointer at that index in the object's vtable to the code for the function.
  - · Invoke that function.

## Analyzing our Approach

- · Advantages:
  - Time to determine function to call is O(1).
  - (and a good O(1) too!)
- What are the disadvantages?
- · Object sizes are larger.
  - Each object needs to have space for  $\mathrm{O}(M)$  pointers.
- · Object creation is slower.
  - Each new object needs to have O(M) pointers set, where M is the number of member functions.







### Dynamic Dispatch in O(1)

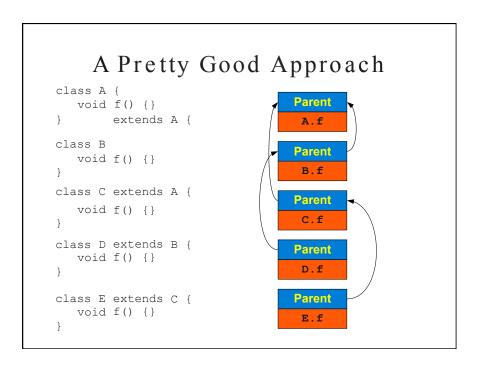
- Create a single instance of the vtable for each class.
- Have each object store a pointer to the vtable.
- Can follow the pointer to the table in O(1).
- Can index into the table in O(1).
- Can set the vtable pointer of a new object in O(1).
- Increases the size of each object by O(1).
- This is the solution used in most C++ and Java implementations.

### Vtable Requirements

- We've made implicit assumptions about our language that allow vtables to work correctly.
- What are they?
- · Method calls known statically.
  - We can determine at compile-time which methods are intended at each call (even if we're not sure which method is ultimately invoked).
- · Single inheritance.
  - Don't need to worry about building a single vtable for multiple different classes.

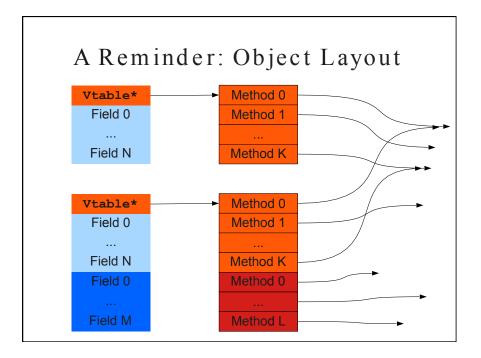
## Dynamic Type Checks

- Many languages require some sort of dynamic type checking.
  - Java's instanceof, C++'s dynamic\_cast, any dynamically-typed language.
- May want to determine whether the dynamic type is *convertible* to some other type, not whether the type is *equal*.
- · How can we implement this?



## Simple Dynamic Type Checking

- Have each object's vtable store a pointer to its base class.
- To check if an object is convertible to type S at runtime, follow the pointers embedded in the object's vtable upward until we find S or reach a type with no parent.
- Runtime is O(d), where d is the depth of the class in the hierarchy.



## TAC for Objects, Part I

```
class A {
    void fn(int x) {
        int y;
        y = x;
    }
}
int main()
    { A a;
    a.fn(137);
}
```

```
_A.fn:
BeginFunc 4;
y = x;
EndFunc;

main:
BeginFunc 8;
_t0 = 137;
PushParam _t0;
PushParam a;
LCall _A.fn;
PopParams 8;
EndFunc;
```

## TAC for Objects, Part II

```
class A {
    int y;
    int z;
    void fn(int x) {
        y = x;
        x = z;
    }
}
int main()
    { A a;
    a.fn(137);
}
```

```
_A.fn:

BeginFunc 4;

*(this + 4) = x;

x = *(this + 8);

EndFunc;

main:

BeginFunc 8;

_t0 = 137;

PushParam _t0;

PushParam a;

LCall _A.fn;

PopParams 8;

EndFunc;
```

## Memory Access in TAC

- Extend our simple assignments with memory accesses:
  - $var = *var_2$ • var = + constant) •  $var * (var_2)$ •  $var_1 * (var_2)$ •  $var_2 * (var_2)$
- var<sub>2</sub>

You will need to translate field accesses into relative memory accesses.

## TAC for Objects, Part III

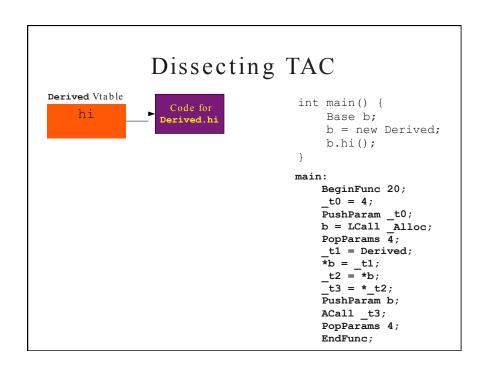
```
class Base
  void { hi()
     Print("Base");
}

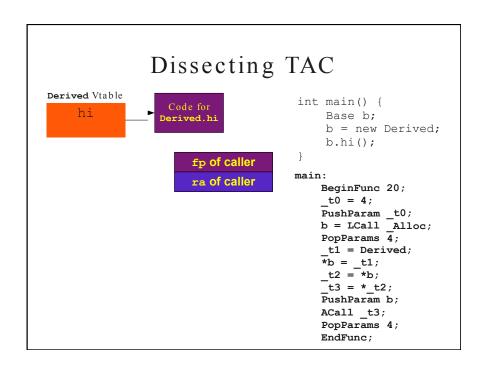
class Derived extends Base{
  void hi() {
     Print("Derived");
  }
}

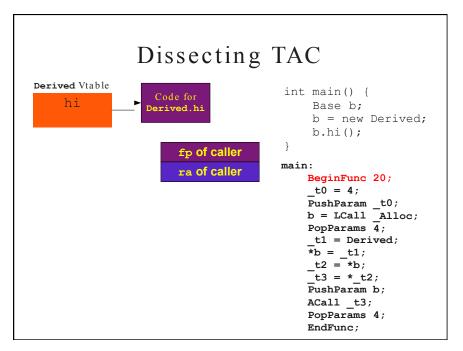
int main() {
     Base b;
     b = new Derived;
     b.hi();
}
```

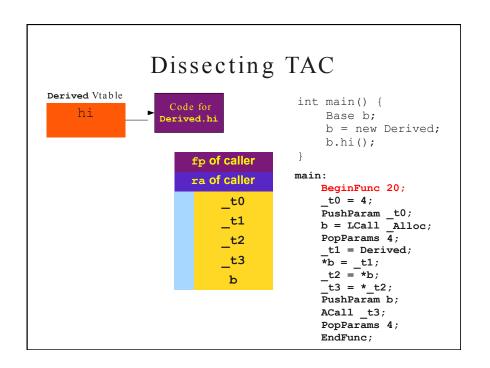
```
_Base.hi:
   BeginFunc 4;
    t0 = "Base";
    PushParam _t0;
   LCall PrintString;
   PopParams 4;
   EndFunc;
Vtable Base = _Base.hi,
Derived.hi:
   BeginFunc 4;
    t0 = "Derived";
   PushParam _t0;
   LCall PrintString;
   PopParams 4;
   EndFunc:
Vtable Derived = Derived.hi,
```

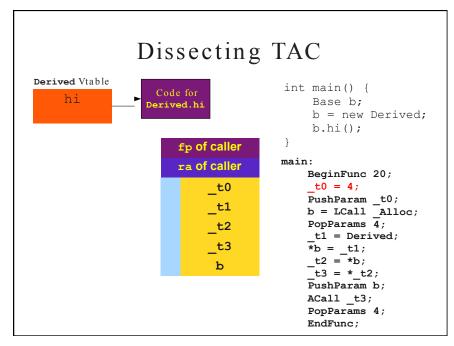
#### TAC for Objects, Part III main: class Base BeginFunc 20; void { hi() t0 = 4;Print("Base"); PushParam \_t0; b = LCall Alloc; PopParams 4; \_t1 = Derived; \*b = \_t1; class Derived extends Base{ void hi() { \_t2 = \*b; \_t3 = \*\_t2; Print("Derived"); PushParam b; ACall t3; } PopParams 4; EndFunc; int main() { Base b; What's going b = new Derived; b.hi(); on here? }

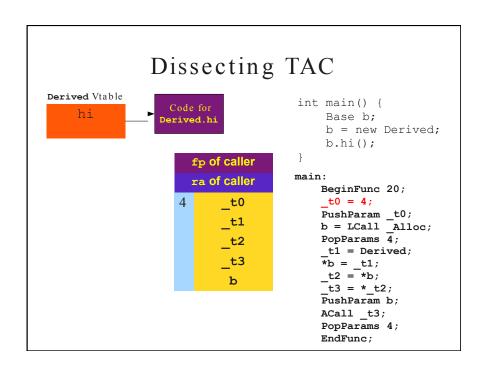


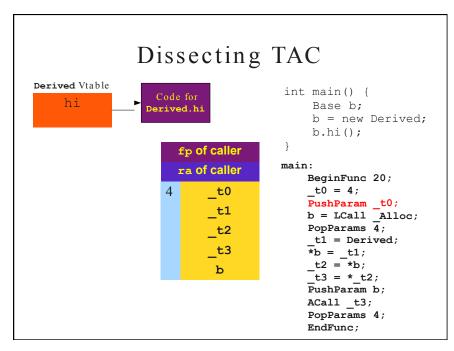


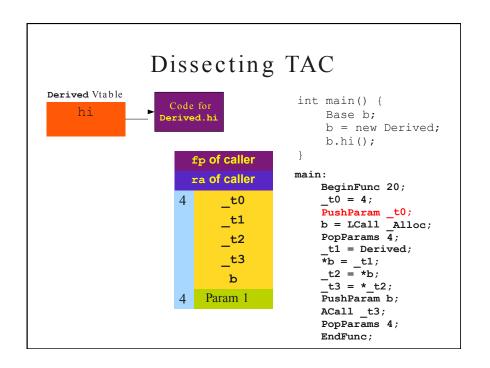


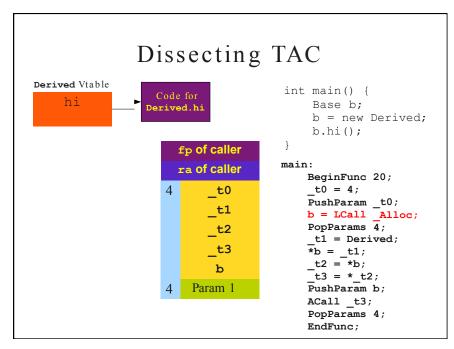


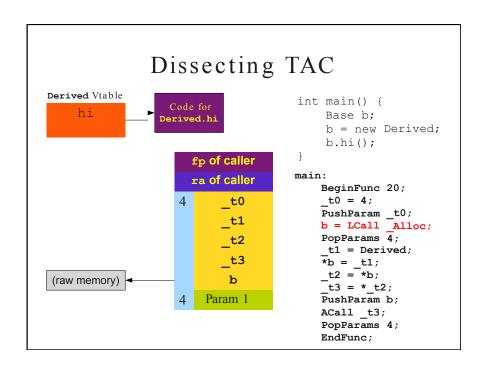


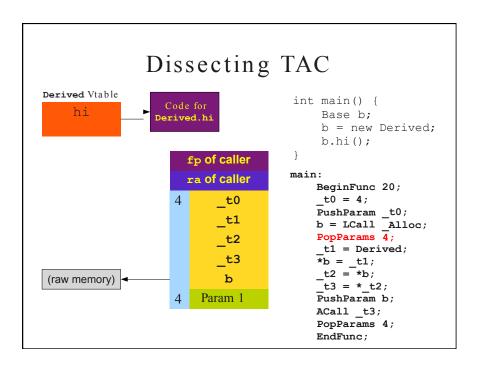


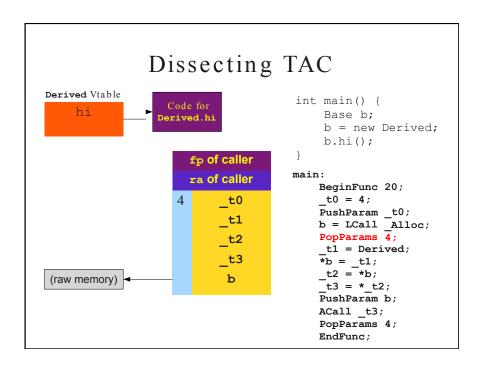


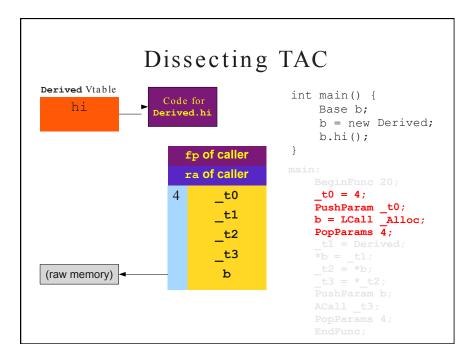


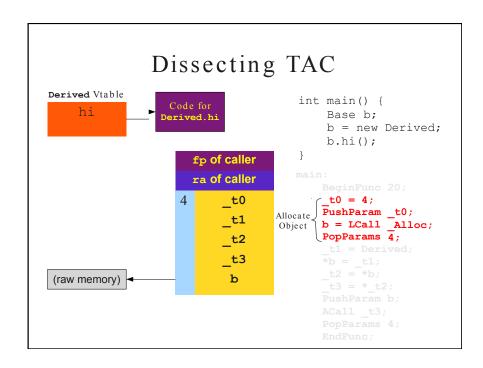


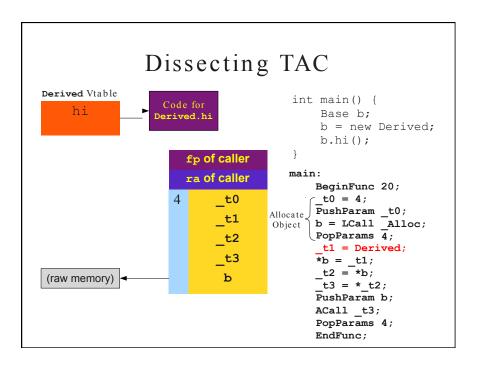


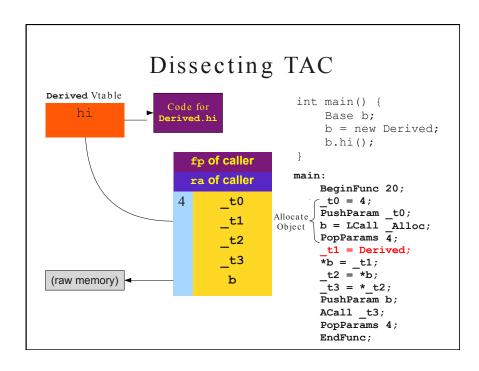


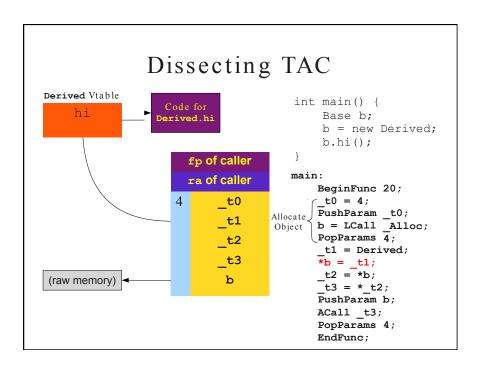


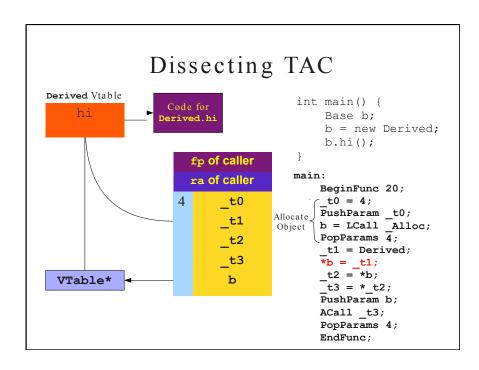


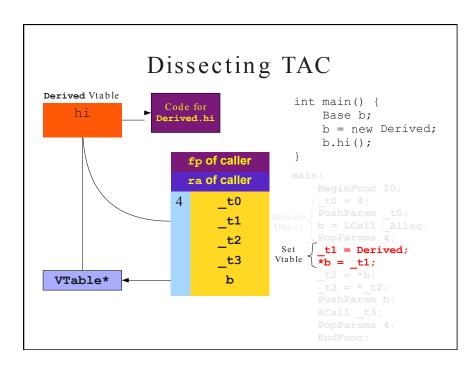


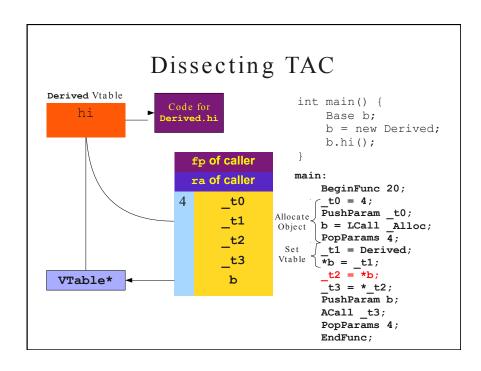


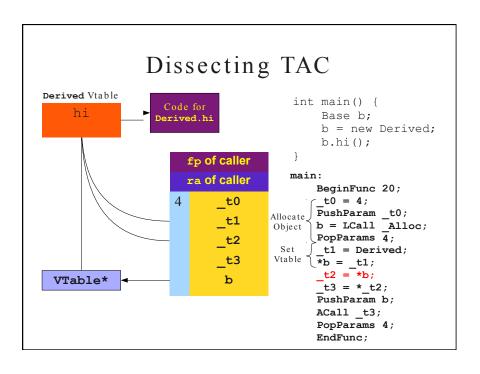


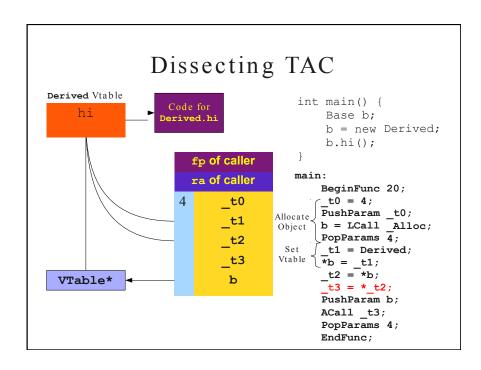


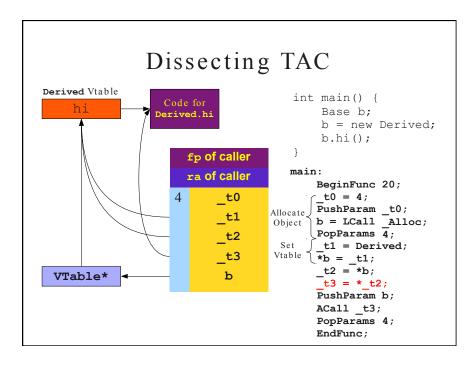


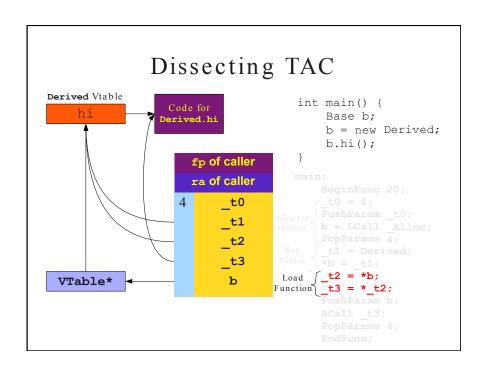


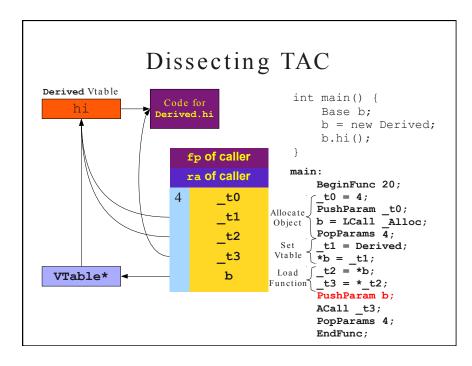


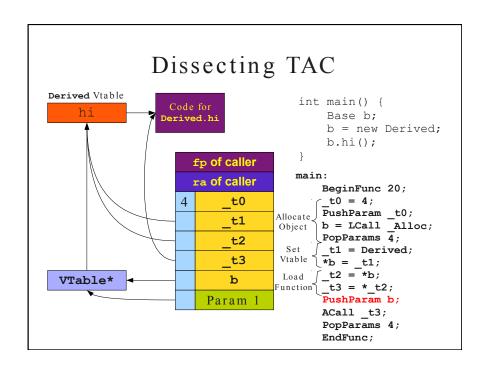


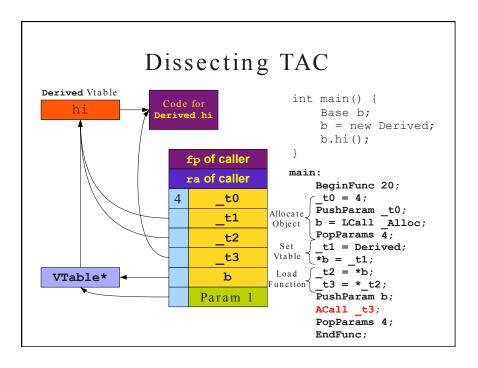


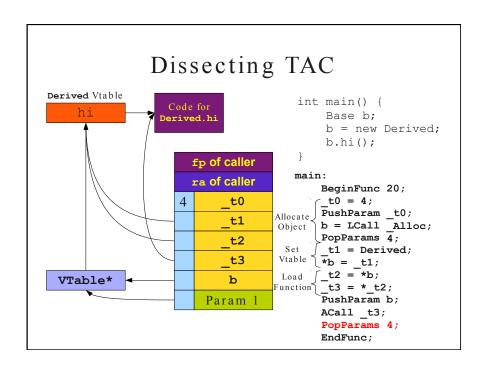


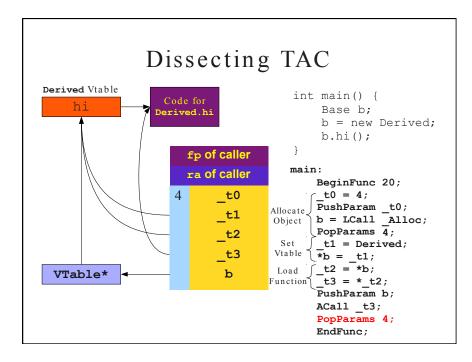


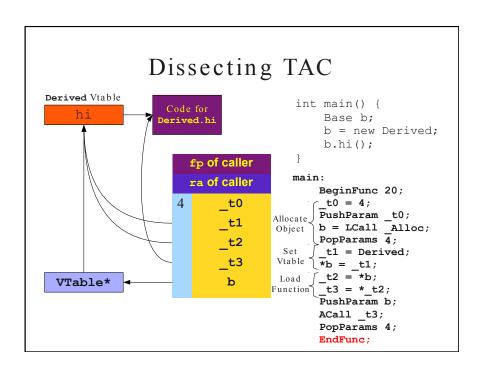












### OOP in TAC

- The address of an object's vtable can be referenced via the name assigned to the vtable (usually the object name).
  - e.g. t0 = Base;
- When creating objects, you must remember to set the object's vtable pointer or any method call will cause a crash at runtime.
- The ACall instruction can be used to call a method given a pointer to the first instruction.