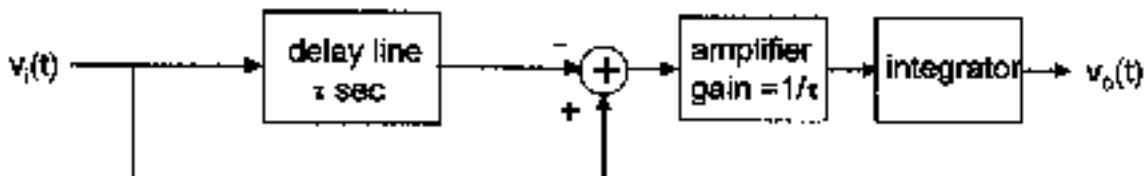


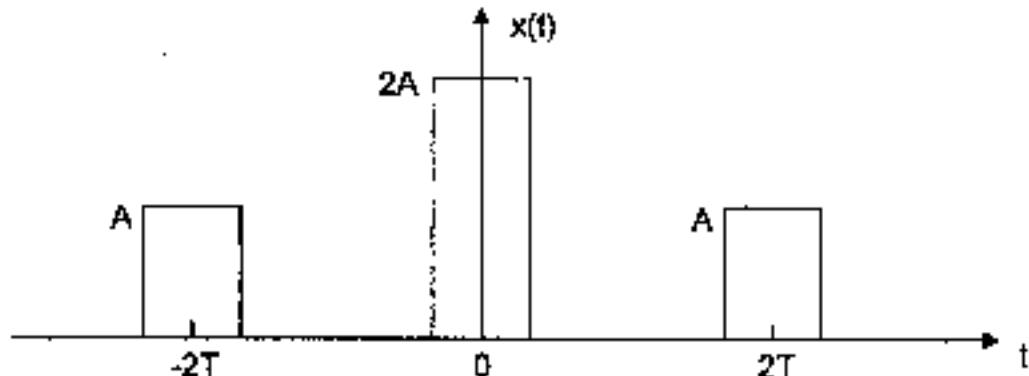
ELEG403 COMMUNICATIONS SYSTEMS ENGINEERING

ASSIGNMENT #2 due Monday September 22

1. A delay line and integrating circuit as shown below are one example of a "holding circuit" that was commonly used in radar work, sampled-data servo systems, and pulse-modulation systems.
 - a) Tracing through the circuit step-by-step, determine the transfer function $H(f) = V_o(f)/V_i(f)$.
 - b) Let $v_i(t)$ be a rectangular pulse of width τ seconds, determine the output $v_o(t)$.



2. Using the superposition (linearity) and time-shift theorems for Fourier transforms, find the transform of the signal shown below. The width of each of the rectangles is τ .

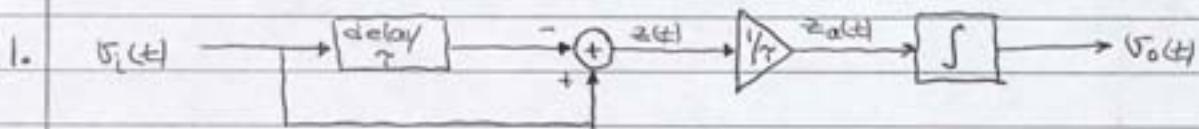


3. Given the energy signal, $x(t) = e^{-\alpha t} u(t)$, $\alpha > 0$, compute the Fourier transform of the following expression (* denotes convolution)

$$y(t) = \beta_1 x(t-t_0) + \beta_2 x(t)^* x(t) + \delta(t-t_0).$$

4. Haykin Problem P2.3 #7

SOLUTIONS TO ASSIGNMENT #1



$$a.) z(t) = V_i(t) - V_i(t-\tau) ; z_a(t) = \frac{1}{\tau} z(t)$$

$$V_o(t) = \int z_a(t) dt = \frac{1}{\tau} \int [V_i(t) - V_i(t-\tau)] dt$$

$$\therefore Z(f) = V_i(f) - V_i(f)e^{-j2\pi f\tau}$$

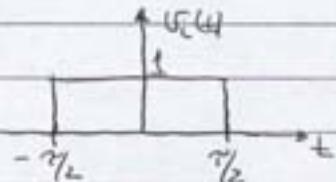
$$Z_a(f) = \frac{1}{\tau} V_i(f) [1 - e^{-j2\pi f\tau}]$$

$$V_o(f) = \frac{1}{j2\pi f} Z_a(f) = V_i(f) \frac{1 - e^{-j2\pi f\tau}}{j2\pi f\tau}$$

$$\therefore H(f) = \frac{V_o(f)}{V_i(f)} = e^{-j2\pi f\tau/2} \left[\frac{e^{j2\pi f\tau/2} - e^{-j2\pi f\tau/2}}{2j(\pi f\tau)} \right]$$

$$= e^{-j\pi f\tau} \frac{\sin \pi f\tau}{\pi f\tau}$$

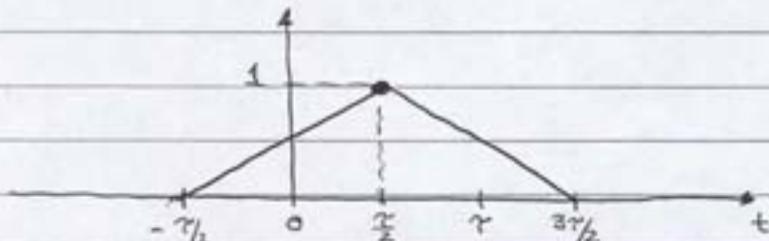
b.) $V_i(t)$ = rectangular pulse
of width τ seconds



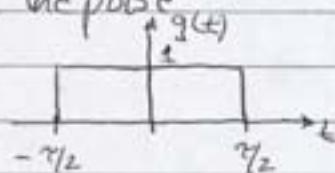
$$V_i(f) = \int_{-\tau/2}^{\tau/2} 1 \cdot e^{-j2\pi ft} dt = \tau \frac{\sin \pi f\tau}{\pi f\tau}$$

$$V_o(f) = H(f)V_i(f) = \tau e^{-j\pi f\tau} \left[\frac{\sin \pi f\tau}{\pi f\tau} \right]^2$$

$V_o(t) = \mathcal{F}^{-1}[V_o(f)] \rightarrow$ triangle of amplitude 1, shifted by $\tau/2$, duration 2τ



2. Define $g(t)$ as the pulse



$$G(f) = \mathcal{F}[g(t)]$$

$$= \frac{\sin \pi f \tau}{\pi f \tau}$$

Then,

$$X(t) = 2A g(t) + A g(t - 2T) + A g(t + 2T)$$

$$X(f) = \mathcal{F}[X(t)]$$

$$= 2A \mathcal{F}[g(t)] + A \mathcal{F}[g(t - 2T)] + A \mathcal{F}[g(t + 2T)] \text{ (linearity)}$$

$$= 2A G(f) + A e^{-j2\pi f 2T} G(f) + A e^{j2\pi f 2T} G(f)$$

$$= 2A \left[1 + e^{-j2\pi f 2T} + e^{j2\pi f (-2T)} \right] G(f) \quad \text{time-shift property}$$

$$= 2A (1 + \cos 4\pi f T) G(f)$$

$$X(f) = 2A \tau (1 + \cos 4\pi f T) \frac{\sin \pi f \tau}{\pi f \tau}$$

3. $X(t) = e^{-\alpha t} u(t)$

$$X(f) = \mathcal{F}[X(t)] = \int_0^\infty e^{-\alpha t} e^{-j2\pi f t} dt = \frac{1}{\alpha + j2\pi f}$$

$$y(t) = \beta_1 X(t - t_0) + \beta_2 X(t) * X(t) + \delta(t - t_0)$$

$$Y(f) = \beta_1 \mathcal{F}[X(t - t_0)] + \beta_2 \mathcal{F}[X(t) * X(t)] + \mathcal{F}[\delta(t - t_0)]$$

$$= \beta_1 e^{-j2\pi f t_0} X(f) + \beta_2 \cancel{X^2(f)} + e^{-j2\pi f t_0}$$

$$= e^{-j2\pi f t_0} \left[1 + \frac{\beta_1}{\alpha + j2\pi f} \right] + \beta_2 \left[\frac{1}{\alpha + j2\pi f} \right]^2$$

4. Haykin Chapter 2 #7

$$a.) \mathcal{F}[X(t)] = X(f)$$

$$G_1(f) = \mathcal{F}[q_1(t)] = \mathcal{F}[X(\frac{t}{5})]$$

$$= 5X(5f) \quad \text{time scaling property}$$

$$G_2(f) = \mathcal{F}[q_2(t)] = \mathcal{F}[X(5t)]$$

$$= \frac{1}{5}X(\frac{f}{5})$$

b.) $q_1(t) \rightarrow$ time expansion

$q_2(t) \rightarrow$ time compression

$$a.) ① y(t) = aq_1(t) = aX(\frac{t}{5})$$

$$Y(f) = 5aX(5f)$$

$$\text{For } Y(0) = X(0), 5a = 1 \Rightarrow a = 1/5$$

$$② y(t) = aq_2(t) = aX(5t)$$

$$Y(f) = \frac{a}{5}X(\frac{f}{5})$$

$$\text{For } Y(0) = X(0), \frac{a}{5} = 1 \Rightarrow a = 5$$

4. Haykin Chapter 2 #7

a.) $\mathcal{F}[x(t)] = X(f)$

$$G_1(f) = \mathcal{F}[q_1(t)] = \mathcal{F}[x(\frac{t}{5})]$$

$= 5 X(5f)$ time scaling property

$$G_2(f) = \mathcal{F}[q_2(t)] = \mathcal{F}[x(5t)]$$

$$= \frac{1}{5} X(\frac{f}{5})$$

b.) $q_1(t) \rightarrow$ time expansion

$q_2(t) \rightarrow$ time compression

c.) ① $y(t) = a q_1(t) = a x(\frac{t}{5})$

$$Y(f) = 5a X(5f)$$

$$\text{For } Y(0) = X(0), 5a = 1 \Rightarrow a = 1/5$$

② $y(t) = a q_2(t) = a x(5t)$

$$Y(f) = \frac{a}{5} X(\frac{f}{5})$$

$$\text{For } Y(0) = X(0), \frac{a}{5} = 1 \Rightarrow a = 5$$