

# CISC 436/636 Computational Biology & Bioinformatics (Fall 2016)

## Protein Structure Prediction 3-Dimensional Structure

## Foundation

- Anfinsen Hypothesis: A native state of protein corresponds to a free energy minimum. (This hypothesis was by Anfinsen based on some experimental findings for smaller molecules, 1973)
- Levinthal paradox: how can a protein fold to a native conformation so rapidly when the number of possible conformations is so huge?
  - Experimental observation: proteins fold into native conformations in a few seconds
  - If a local move by diffusion takes  $10^{-11}$  seconds, it would take  $10^{57}$  seconds to try  $\sim 5^{100}$  possible conformations for a protein of 100 AAs.
- NP-completeness

## Computational Methods for 3-D structures

- Comparative (find homologous proteins)
- Threading (recognize folds)
- *Ab initio* (Molecular dynamics)

## Root Mean Square Deviation (RMSD)

$$\sqrt{\frac{\sum_{i=1, N} (\vec{x}_i - \vec{y}_i)^2}{N}}$$

Where  $x_i$  are the coordinates from molecule 1 and  $y_i$  are the *equivalent*\* coordinates from molecule 2.

\*Which atoms are *equivalent* is based on an **alignment**.

Credit: Chris Bystroff @ RPI

# Comparative (homology based) modeling

- Identification of structurally conserved regions (using multiple alignment)
- Backbone construction
- Loop construction
- Side-chain restoration
- Structure verification and evaluation
- Structure refinement (energy minimization)

# Least squares superposition

Problem: find the rotation matrix,  $\underline{M}$ , and a vector,  $\underline{v}$ , that minimize the following quantity:

$$\sum_i \left| \underline{M} \vec{x}_i + \vec{v} - \vec{y}_i \right|^2$$

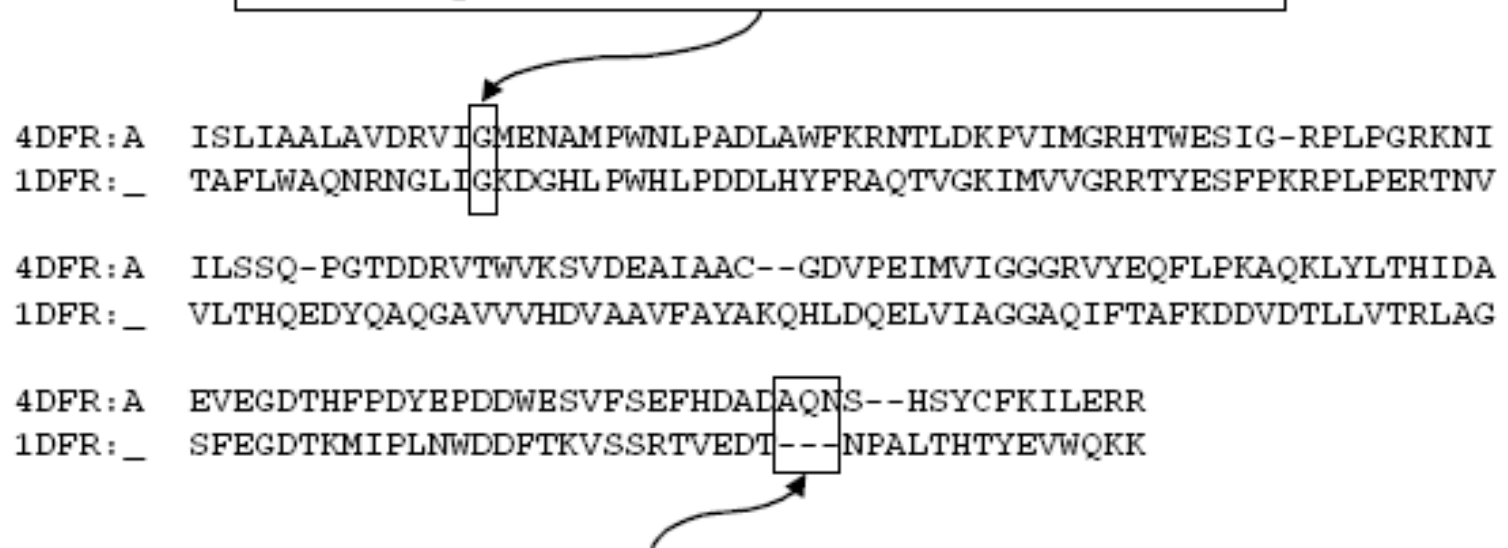
Where  $x_i$  are the coordinates from one molecule and  $y_i$  are the *equivalent*\* coordinates from another molecule.

\**equivalent* based on alignment

Credit: Chris Bystroff @ RPI

# Mapping structural equivalence = aligning the sequence

Any position that is aligned is included in the  
sum of squares.



4DFR: A ISLIAALAVDRVIGMENAMPWNLPADLAWFKRNTLDKPVIMGRHTWESIG-RPLPGRKNI  
1DFR: \_ TAFLWAQNRNGLIGKDGHL PWHL PDDLHYFRAQTVGKIMVVGRRTYESFPKRPLPERTNV

4DFR: A ILSSQ-PGTDDRVTWVKSVD EAIAC--GDVPEIMVIGGGRVYEQFLPKAQKLYLTHIDA  
1DFR: \_ VLTHQEDYQAQGAVVVDVA AVFAYAKQHLDQELVIAGGAQIFTAFKDDVD TLLVTRLAG

4DFR: A EVEGDTHFPDYEPDDWESVFSEFHDADAQNS--HSYCFKILERR  
1DFR: \_ SFEGDTKMIPLNWDDFTKVSSRTVEDT---NPALHTHTYEVWQKK

Unaligned positions are not.

Credit: Chris Bystroff @ RPI

# least-squares superimposed molecules

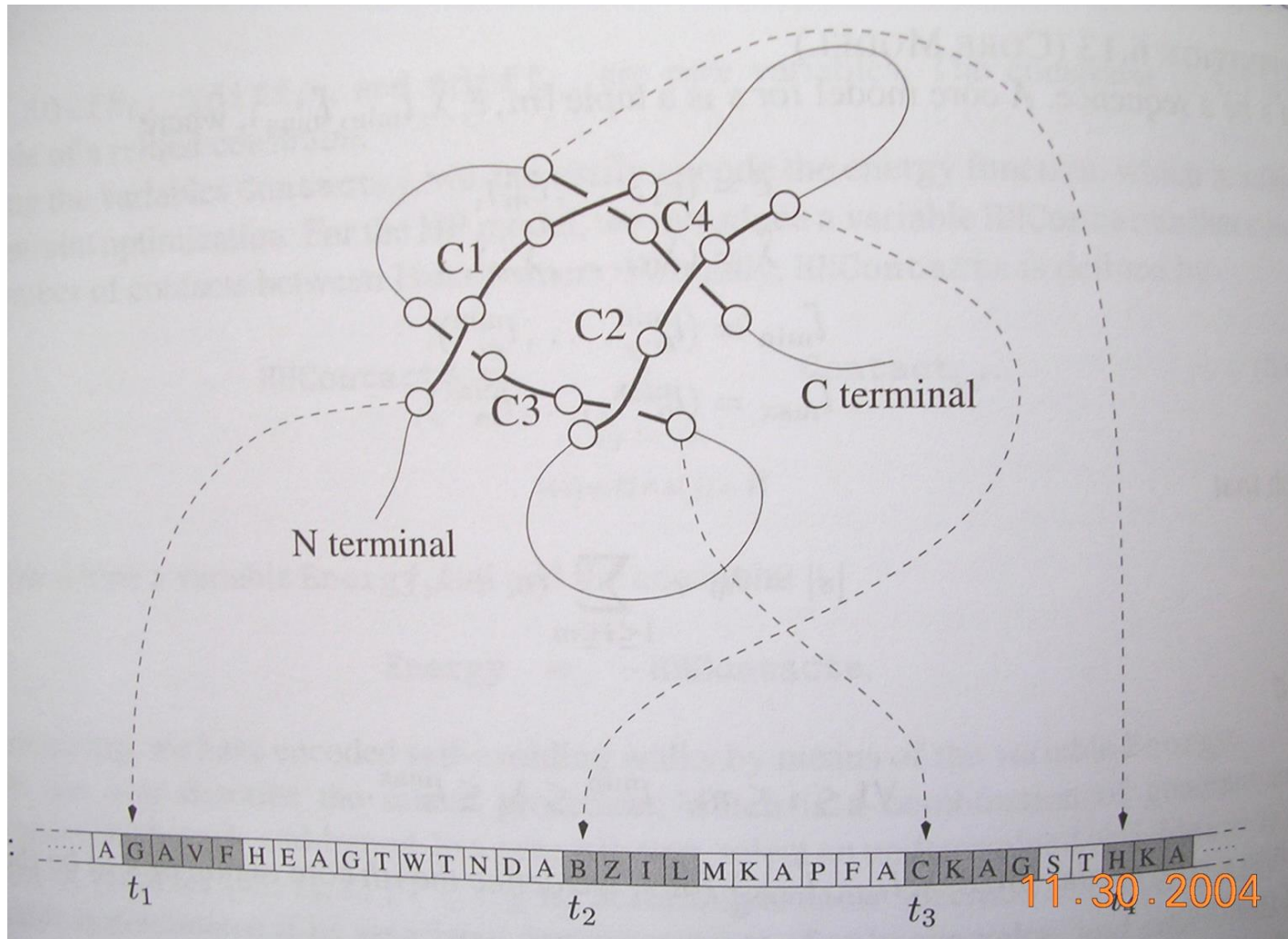


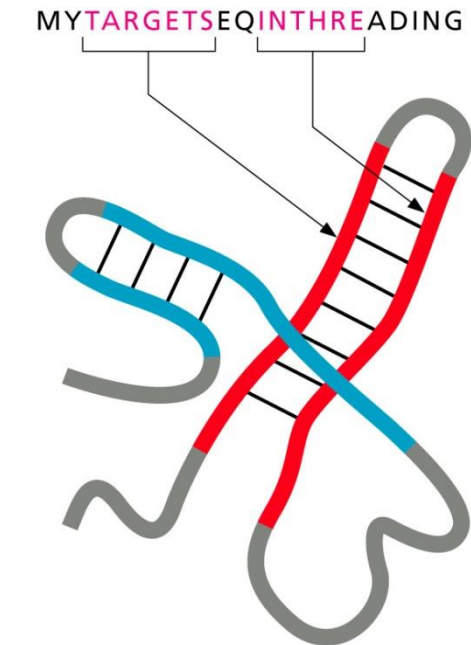
Credit: Chris Bystroff @ RPI

# Protein Threading

- When two homologous proteins do not have high sequence similarity
- Structure of one protein, P1, is known
- The goal is to predict the structure for the other protein P2
- Identify core regions for P1
- Scoring a given alignment with a known structure (Contact potentials)

# Threading: A schematic view

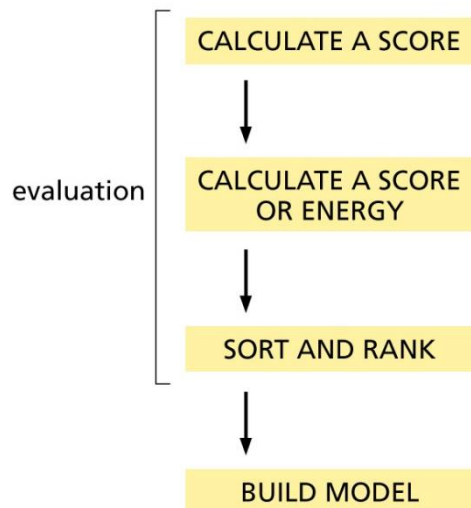




First, segments of sequence are structurally aligned (threaded) on to a fold and a score/energy is obtained for each alignment.

A dynamic programming technique is used to find the alignment that has the best score.

This is done for each fold in the fold library, and the results are ranked. The folds giving the best score are then selected for use in modeling the query sequence.



# Lattice Models

## Simplifications

- All residues have the same size
- Bond length is uniform
- Positions of residues are restricted to positions in a regular lattice (or grid).

## HP model

- Energy function  $B_{i,j}$  for a pair of residues  $w_i$  and  $w_j$ 
  - = 0 when the two residues
    - do not have contact (i.e. not topological neighbors), or
    - one residue is polar/hydrophilic and the other is hydrophobic, or
    - both are polar/hydrophilic
  - = -1 when two residues
    - are topological neighbors, and
    - both are hydrophobic.

Note: Despite these simplifications, it is still NP complete to find an optimal conformation

- 2-dimensional and 3-dimensional lattice
- Two residues  $w_i$  and  $w_j$  are *connected neighbors* when  $j = i+1$  or  $i-1$ .
- Two residues  $w_i$  and  $w_j$  are *topological neighbors* when  $j \neq i+1$  or  $i-1$ , and

$$\| w_i - w_j \| = 1$$

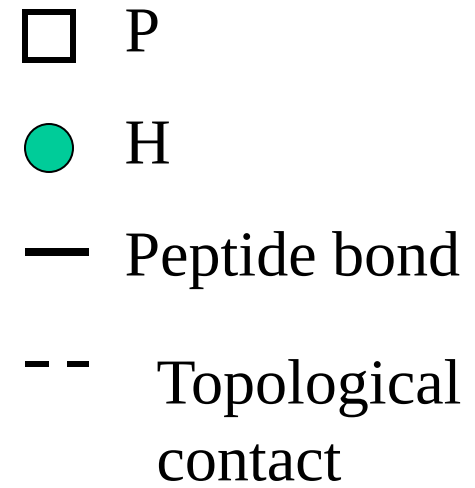
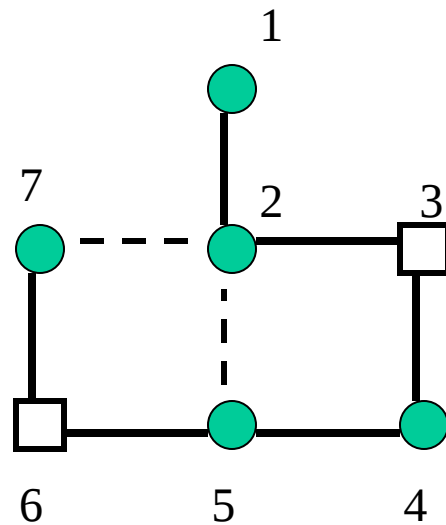
- A native state is a conformation that has the minimum contact energy

$$E = \sum_{1 \leq i+1 < j \leq n} B_{i,j} \delta(w_i, w_j)$$

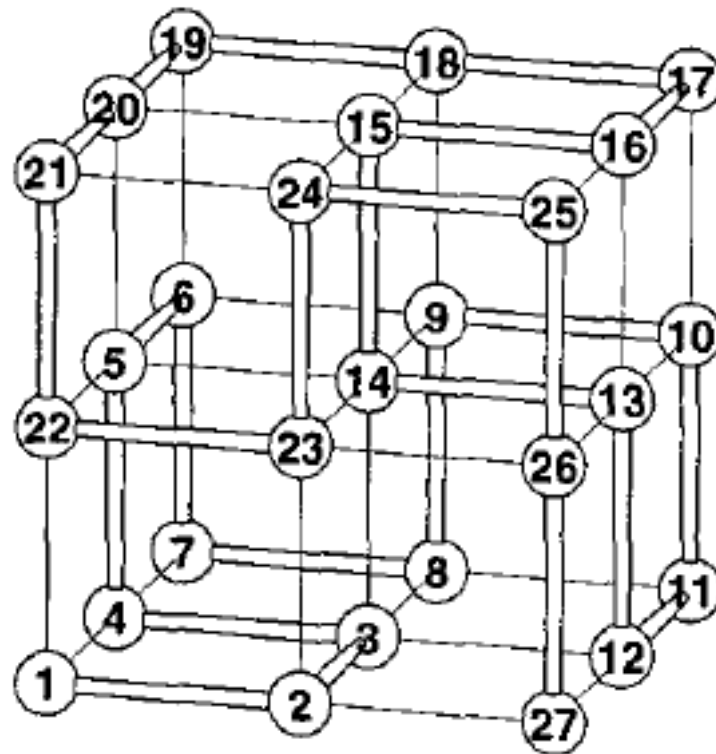
where  $\delta(w_i, w_j) = 1$  when  $w_i$  and  $w_j$  are *topological neighbor*, and  $=0$  otherwise.

- The HP model approximates the hydrophobic force, which is not really a force, but rather an aggregate tendency for nonpolar residues to minimize their contact with the solvent.

- Example HP model

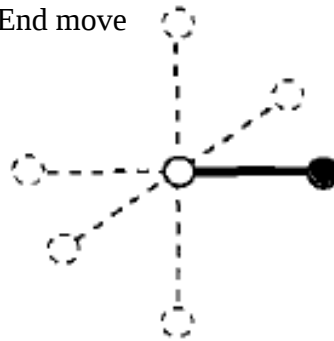


- The HP model by SSK (Sali, Shakhnovich, and Karplus, 1994)
  - A 27-bead heteropolymer in a 3-d lattice.
  - Contact energy normally distributed
  - Possible conformation:  $5^{26} \sim 10^{18}$
  - Compact conformation: in a 3x3x3 cube there are 103346 distinct conformations
  - Folding time  $t_0$  is short if energy gap is large
  - Solved Levinthal paradox

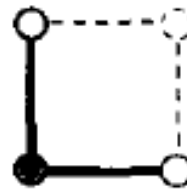


# Local moves

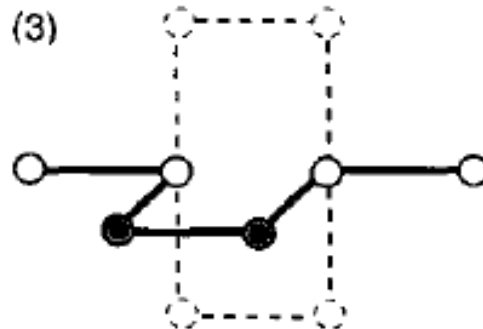
(1) End move



(2) Corner move



(3)



Crankshaft move

(4)

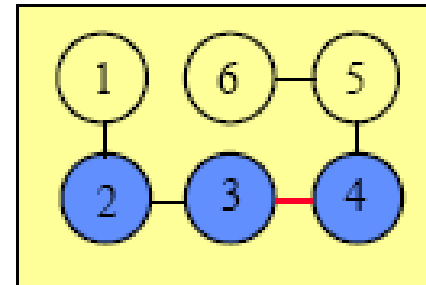
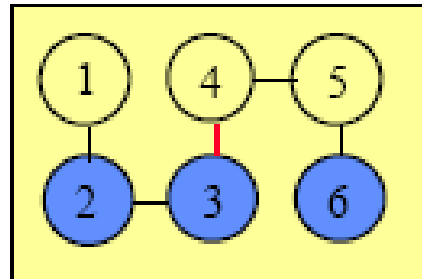


Impossible move

# Crossover to create new conformations

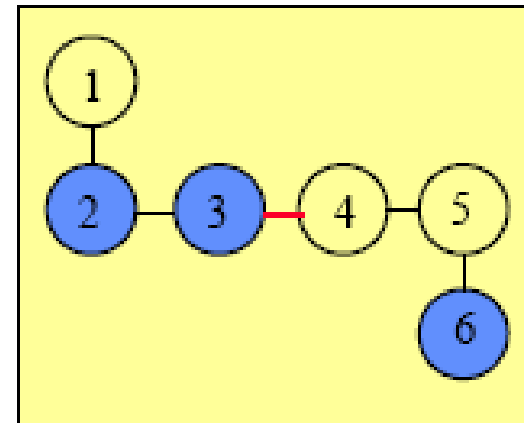
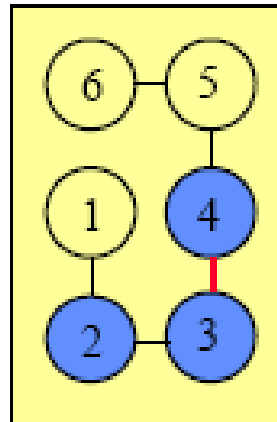
Parents

10 00 **01** 00 10  
10 00 **00** 01 11

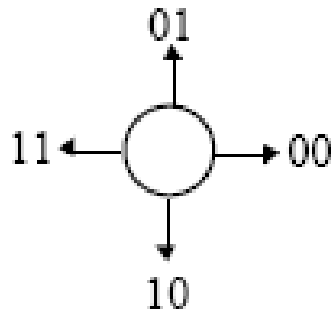


Children

10 00 **01** 01 11  
10 00 **00** 00 10



Encoding:



Credit: Iosif Vaisman @ GAU

# Genetic algorithm

Input

- P, the population,
- r: the fraction of population to be replaced,
- f, a fitness,
- ft, the fitness\_threshold,
- m: the rate for mutation.

Initialize population (randomly)

Evaluate: for each h in P, compute Fitness(h)

While [ $\text{Max}_h f(h)$ ] < ft

do

1. Select
2. Crossover
3. Mutate
4. Update P with the new generation Ps
5. Evaluate: f(h) for all h  $\in$  P

Return the h in P that has the best fitness

# Unger-Moult hybrid genetic algorithm

```
initialize population P(t) of random coils
best = argmax {F(x) | x in P(t)}
repeat {
    pointwise mutation
    n = 0
    while (n < P) { // genetic algorithm part
        select 2 chromosomes m, f
        produce child c by crossover of m, f
        ave = average( F(m), F(f))
        if(F(c) >= ave) {
            place c in next generation; n++
        } else { // Metropolis part
            z = random(0,1)
            if (z < e-(ave - F(c))/T ) {
                place c in next generation; n++
            }
        }
    }
    } // end while
    update best
    check if stopping criterion is met
}
```

# Ab initio approaches

## Potential Energy Function

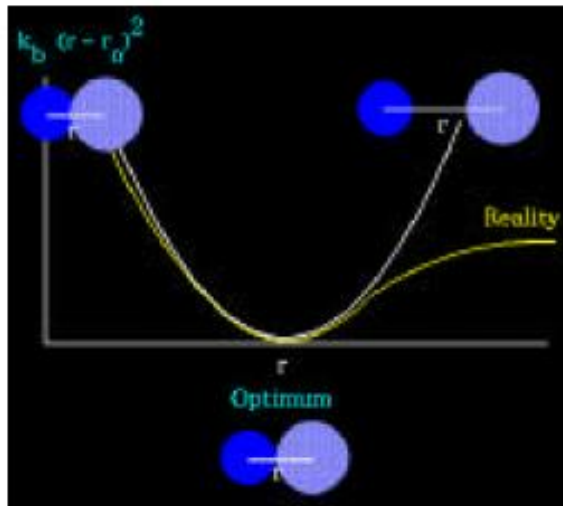
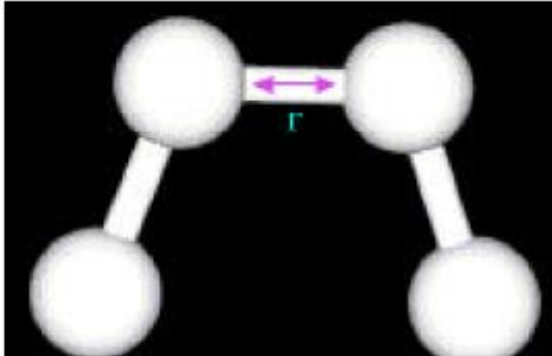
$$\begin{aligned} \text{PEF}(R) = & \sum_{\text{bonds}} K_b \{b(R) - b_{eq}\}^2 + \sum_{\text{angles}} K_\theta \{\theta(R) - \theta_{eq}\}^2 + \\ & \sum_{\text{dihedrals}} \frac{K_\phi}{2} \{1 + \cos[n\phi(R) - \gamma]\} + \\ & \sum_{\text{non-bonded atom pairs } ij} \left[ \frac{A_{ij}}{r_{ij}(R)^{12}} - \frac{B_{ij}}{r_{ij}(R)^6} + \frac{q_i q_j}{\epsilon_r \epsilon_0 r_{ij}(R)} \right] \quad (1) \end{aligned}$$

Forcefields: [AMBER](#), [CHARMM](#), [CVF](#), [ECEPP](#), [GROMOS](#)

Credit: Iosif Vaisman @ GMU

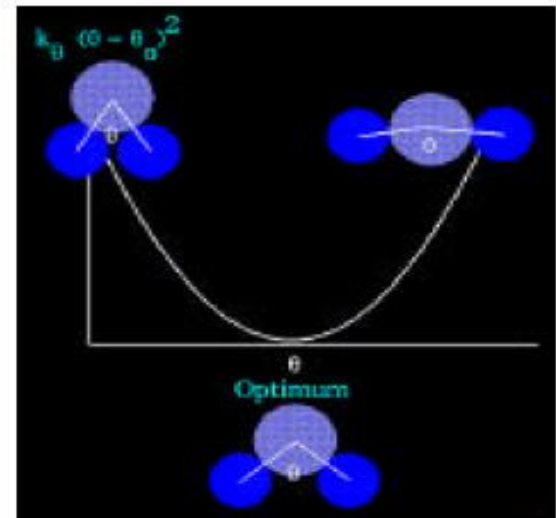
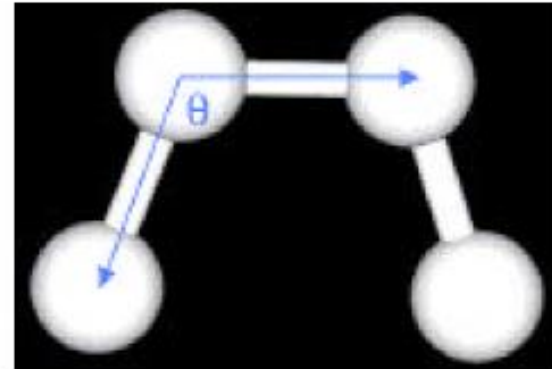
## Bond length

$$E = \sum_{\text{bonds}} k_b (r - r_o)^2$$

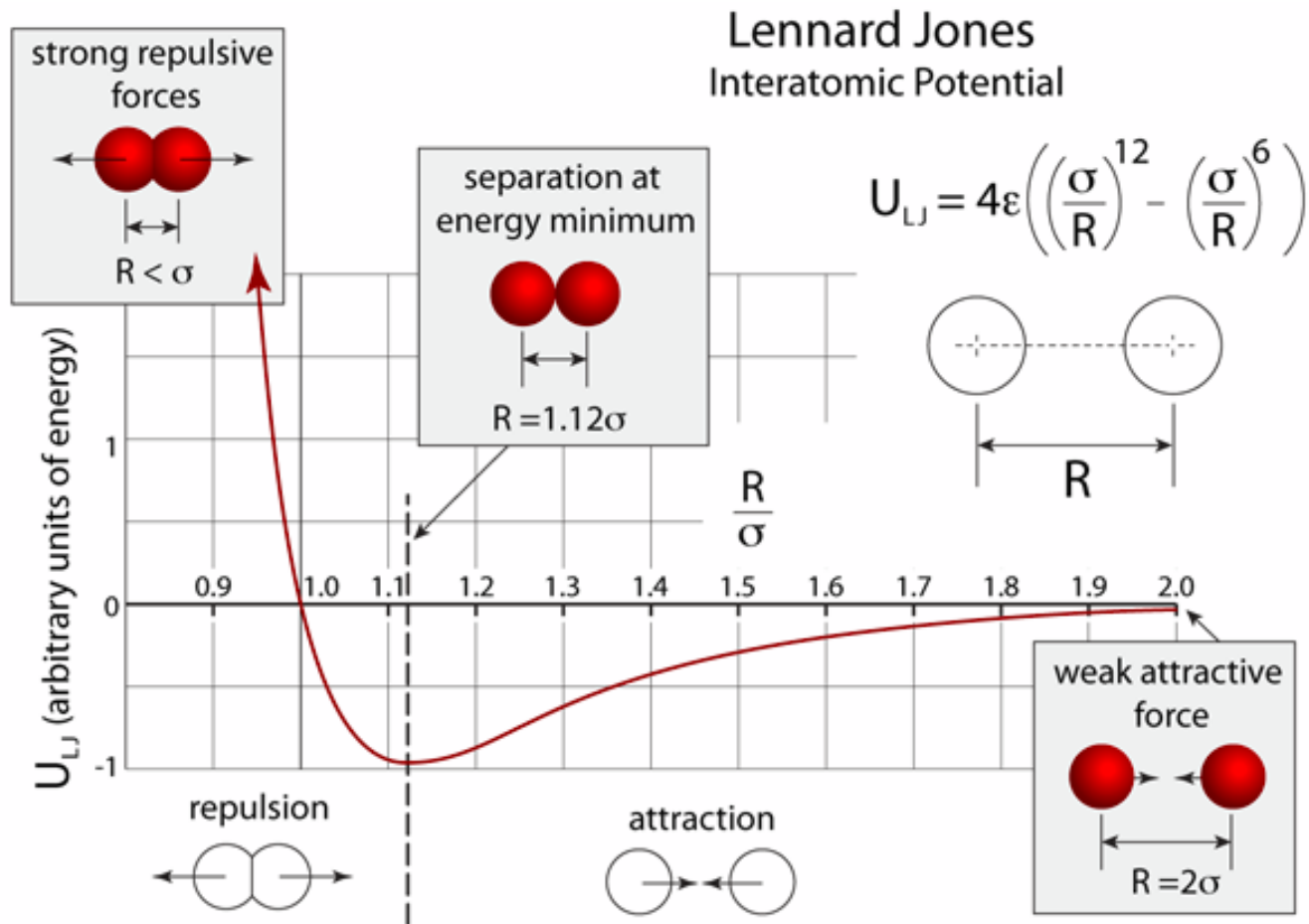


## Bond angle

$$E = \sum_{\text{angles}} k_\theta (\theta - \theta_o)^2$$



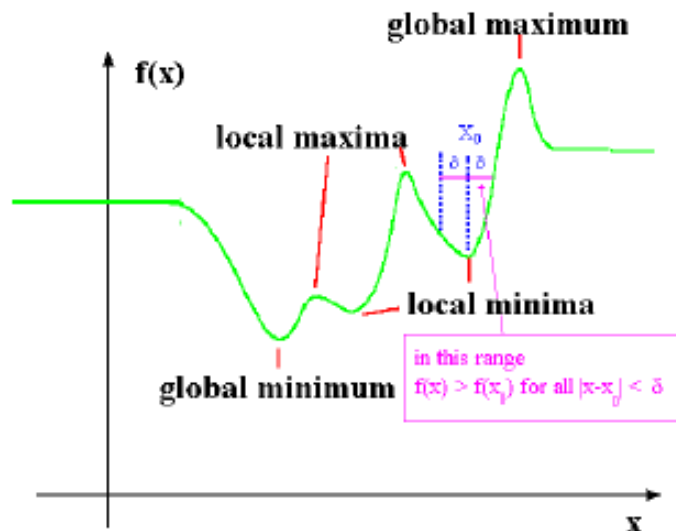
Credit: Iosif Vaisman @ GMU



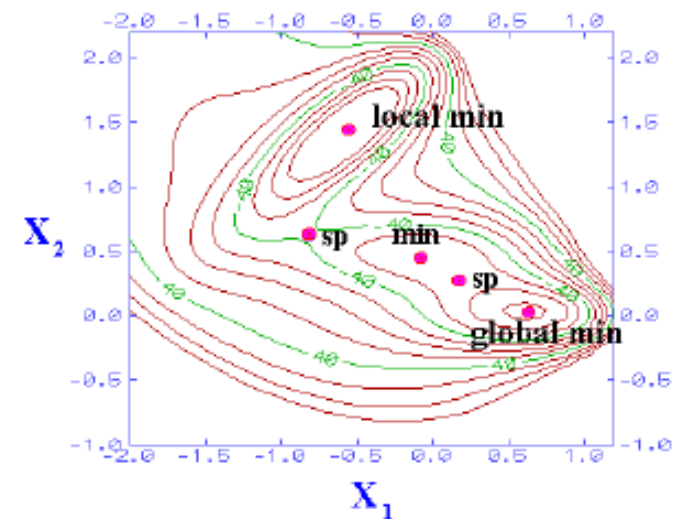
**Lennard Jones Potential.** The graph above plots the Lennard–Jones potential function, and indicates regions of attraction and repulsion. Atoms try to minimize their potential energy and at the lowest temperatures are sitting at the bottom of the potential curve. When the atomic separations are to the left of the minimum the atoms repel, otherwise they attract one another.

Credit: atomsinmotion.com

## Energy Minimazation

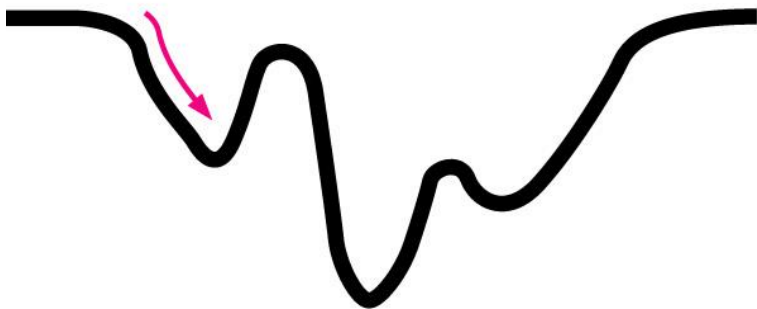


## Energy Minimazation

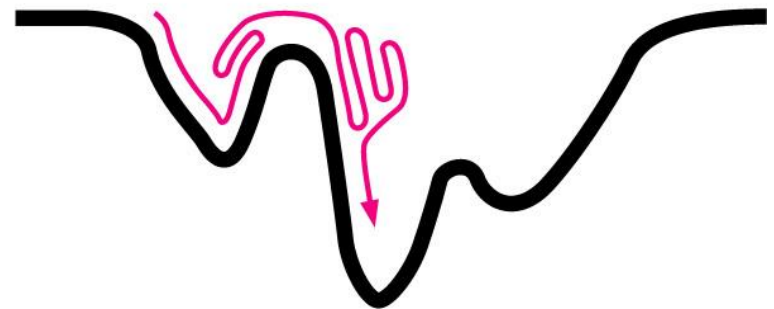


Credit: Iosif Vaisman @ GMU

(A)



(B)



# Molecular Dynamics

$$\mathbf{F}_i = m_i \mathbf{a}_i$$

$$\mathbf{a}_i = d\mathbf{v}_i / dt$$

$$\mathbf{v}_i = d\mathbf{r}_i / dt$$

$$- dE / d\mathbf{r}_i = \mathbf{F}_i$$

$$- dE / d\mathbf{r}_i = m_i d^2\mathbf{r}_i / dt^2$$

Credit: Iosif Vaisman @ GMU

# Resources

## Homology modeling programs

<http://www.expasy.ch/swissmod>

## Threading:

<http://www.ncbi.nlm.nih.gov/Structure/RESEARCH/threading.shtml>