

Code Shape I Expressions & Arrays

Code Shape



$$X + Y + Z$$

$$x + y \rightarrow t1$$

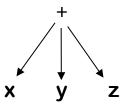
$$x + z \rightarrow t1$$

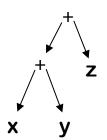
$$y + z \rightarrow t1$$

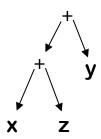
$$t1+z \rightarrow t2$$

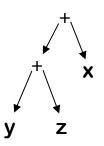
$$t1+y \rightarrow t2$$

$$t1+z \rightarrow t2$$









- What if x is 2 and z is 3?
- What if y+z is evaluated earlier?

Addition is commutative & associative for integers

The "best" shape for x+y+z depends on contextual knowledge

→ There may be several conflicting options





Another example -- the case statement

- Implement it as cascaded if-then-else statements
 - → Cost depends on where your case actually occurs
 - \rightarrow O(number of cases)
- Implement it as a binary search
 - → Need a dense set of conditions to search
 - → Uniform (log n) cost
- Implement it as a jump table
 - → Lookup address in a table & jump to it
 - → Uniform (constant) cost

Compiler must choose best implementation strategy
No amount of massaging or transforming will convert one into
another





The key code quality issue is holding values in registers

- When can a value be safely allocated to a register?
 - → When only 1 name can reference its value
 - → Pointers, parameters, aggregates & arrays all cause trouble
- When should a value be allocated to a register?
 - → When it is both <u>safe</u> & <u>profitable</u>

Encoding this knowledge into the IR

- Use code shape to make it known to every later phase
- Assign a virtual register to anything that can go into one
- Load or store the others at each reference

Relies on a strong register allocator





```
expr(node) {
  int result, t1, t2;
  switch (type(node)) {
      case \times, \div, +, -:
          t1 \leftarrow expr(left child(node));
          t2← expr(right child(node));
          result ← NextRegister();
          emit (op(node), t1, t2, result);
          break:
      case IDENTIFIER:
          t1 \leftarrow base(node);
          t2 \leftarrow offset(node);
          result \leftarrow NextRegister();
          emit (loadAO, t1, t2, result);
          break;
      case NUMBER:
          result \leftarrow NextRegister();
          emit (loadl, val(node), none, result);
          break;
       return result:
```

The concept

- Use a simple treewalk evaluator
- Bury complexity in routines it calls
 - > base(), offset(), & val()
- Implements expected behavior
 - > Visits & evaluates children
 - > Emits code for the op itself
 - > Returns register with result
- Works for simple expressions
- Easily extended to other operators
- Does not handle control flow





```
expr(node) {
  int result, t1, t2;
  switch (type(node)) {
      case \times, \div, +, -:
          t1 \leftarrow expr(left child(node));
          t2← expr(right child(node));
          result ← NextRegister();
          emit (op(node), t1, t2, result);
          break:
      case IDENTIFIER:
          t1 \leftarrow base(node);
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          result \leftarrow NextRegister();
          emit (loadAO, t1, t2, result);
          break:
      case NUMBER:
          result \leftarrow NextRegister();
          emit (loadl, val(node), none, result);
          break;
       return result:
```

Example:

Produces:

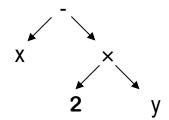
```
expr("x") \rightarrow
loadl @x \Rightarrow r1
loadAO r0, r1 \Rightarrow r2
expr("y") \rightarrow
loadl @y \Rightarrow r3
loadAO r0, r3 \Rightarrow r4
expr("+") \rightarrow
NextRegister() \rightarrow r5
emit(add,r2,r4,r5) \rightarrow
add r2, r4 \Rightarrow r5
```





```
expr(node) {
  int result, t1, t2;
  switch (type(node)) {
      case \times, \div, +, -1
         t1 \leftarrow expr(left child(node));
         t2← expr(right child(node));
         result ← NextRegister();
         emit (op(node), t1, t2, result);
         break;
      case IDENTIFIER:
         t1← base(node);
         t2 \leftarrow offset(node);
         result ← NextRegister();
         emit (loadAO, t1, t2, result);
         break;
      case NUMBER:
         result \leftarrow NextRegister();
         emit (loadl, val(node), none, result);
         break;
      return result:
```

Example:



Generates:

loadl	@x	⇒ r1
loadAO	r0, r1	⇒ r2
loadl	2	⇒ r3
loadl	@у	⇒ r4
loadAO	r0,r4	⇒ r5
mult	r3, r5	⇒ r6
sub	r2, r6	⇒ r7



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More complex cases for IDENTIFIER

- What about values in registers?
 - → Modify the IDENTIFIER case
 - \rightarrow Already in a register \Rightarrow return the register name
 - → Not in a register ⇒ load it as before, but record the fact
 - → Choose names to avoid creating false dependences
- What about parameter values?
 - → Many linkages pass the first several values in registers
 - → Call-by-value ⇒ just a local variable with "funny" offset
 - → Call-by-reference ⇒ needs an extra indirection
- What about function calls in expressions?
 - → Generate the calling sequence & load the return value
 - → Severely limits compiler's ability to reorder operations





Adding other operators

- Evaluate the operands, then perform the operation
- Complex operations may turn into library calls
- Handle assignment as an operator

Mixed-type expressions

- Insert conversions as needed from conversion table
- Most languages have symmetric & rational conversion tables

Typical Addition Table

+	Integer	Real	Double	Complex
Integer	Integer	Real	Double	Complex
Real	Real	Real	Double	Complex
Double	Double	Double	Double	Complex
Complex	Complex	Complex	Complex	Complex

Handling Assignment

(just another operator)



 $lhs \leftarrow rhs$

Strategy

- Evaluate rhs to a value
- Evaluate Ihs to a location
 - \rightarrow Ivalue is a register \Rightarrow move rhs
 - \rightarrow Ivalue is an address \Rightarrow store rhs
- If rvalue & Ivalue have different types
 - → Evaluate rvalue to its "natural" type
 - → Convert that value to the type of */value

Unambiguous scalars go into registers

Ambiguous scalars or aggregates go into memory

(an rvalue)
(an lvalue)

Let hardware sort out the addresses!





What if the compiler cannot determine the rhs's type?

- This is a property of the language & the specific program
- If type-safety is desired, compiler must insert a <u>run-time</u> check
- Add a tag field to the data items to hold type information

Code for assignment becomes more complex

```
evaluate rhs
if type(lhs) ≠ rhs.tag
    then
        convert rhs to type(lhs) or
        signal a run-time error

lhs ← rhs
This is much more complex than if it knew the types
```





Compile-time type-checking

- Goal is to eliminate both the check & the tag
- Determine, at compile time, the type of each subexpression
- Use compile-time types to determine if a run-time check is needed

Optimization strategy

- If compiler knows the type, move the check to compile-time
- Unless tags are needed for garbage collection, eliminate them
- If check is needed, try to overlap it with other computation

Can design the language so all checks are static





First, must agree on a storage scheme

Row-major order

Lay out as a sequence of consecutive rows

Rightmost subscript varies fastest

A[1,1], A[1,2], A[1,3], A[2,1], A[2,2], A[2,3]

Column-major order

Lay out as a sequence of columns

Leftmost subscript varies fastest

A[1,1], A[2,1], A[1,2], A[2,2], A[1,3], A[2,3]

Indirection vectors

Vector of pointers to pointers to ... to values

Takes much more space, trades indirection for arithmetic

Not amenable to analysis

(most languages)

(Fortran)

(Java)

Laying Out Arrays



The Concept

These have distinct & different cache behavior

Row-major order

Column-major order

Indirection vectors

Computing an Array Address



A[i]

- @A + (i low) x sizeof(A[1])
- In general: base(A) + (i low) x sizeof(A[1])





A[i]

- @A + (i low) x sizeof(A[1])
- In general: base(A) + (i low) x sizeof(A[1])

int $A[1:10] \Rightarrow low is 1$ Make low 0 for faster access (saves a -) Almost always a power of 2, known at compile-time ⇒ use a shift for speed

Computing an Array Address



A[i]

- @A + (i low) x sizeof(A[1])
- In general: base(A) + (i low) x sizeof(A[1])

What about $A[i_1,i_2]$?

This stuff looks expensive! Lots of implicit +, -, x ops

Row-major order, two dimensions

$$@A + ((i_1 - low_1) \times (high_2 - low_2 + 1) + i_2 - low_2) \times sizeof(A[1])$$

Column-major order, two dimensions

$$@A + ((i_2 - low_2) \times (high_1 - low_1 + 1) + i_1 - low_1) \times sizeof(A[1])$$

Indirection vectors, two dimensions

```
*(A[i_1])[i_2] — where A[i_1] is, itself, a 1-d array reference
```



Optimizing Address Calculation for A[i,j]

```
where w = sizeof(A[1,1])
In row-major order
     @A + (i-low_1)(high_2-low_2+1) \times w + (j-low_2) \times w
Which can be factored into
     @A + i \times (high_2 - low_2 + 1) \times w + j \times w
        - (low_1 \times (high_2 - low_2 + 1) \times w) + (low_2 \times w)
If low, high, and w are known, the last term is a constant
Define @A_0 as
    @A - (low_1 \times (high_2 - low_2 + 1) \times w) + (low_2 \times w)
And len<sub>2</sub> as (high<sub>2</sub>-low<sub>2</sub>+1)
Then, the address expression becomes
    @A_0 + (i \times len_2 + j) \times w
```

Compile-time constants

Array References



What about arrays as actual parameters?

Whole arrays, as call-by-reference parameters

- Need dimension information ⇒ build a dope vector
- Store the values in the calling sequence
- Pass the address of the dope vector in the parameter slot
- Generate complete address polynomial at each reference

What about call-by-value?

- Most c-b-v languages pass arrays by reference
- This is a language design issue

@A low₁

high₁

high₂





What about A[12] as an actual parameter?

If corresponding parameter is a scalar, it's easy

- Pass the address or value, as needed
- Must know about both formal & actual parameter
- Language definition must force this interpretation

What if corresponding parameter is an array?

- Must know about both formal & actual parameter
- Meaning must be well-defined and understood
- Cross-procedural checking of conformability
- ⇒ Again, we're treading on language design issues





Naïve: Perform the address calculation twice

```
DO J = 1, N

R1 = @A_0 + (J × len<sub>1</sub> + I ) × floatsize

R2 = @B_0 + (J × len<sub>1</sub> + I ) × floatsize

MEM(R1) = MEM(R1) + MEM(R2)

END DO
```





Sophisticated: Move comon calculations out of loop

```
R1 = I \times floatsize

c = len_1 \times floatsize ! Compile-time constant

R2 = @A_0 + R1

R3 = @B_0 + R1

DO J = 1, N

a = J \times c

R4 = R2 + a

R5 = R3 + a

MEM(R4) = MEM(R4) + MEM(R5)

END DO
```