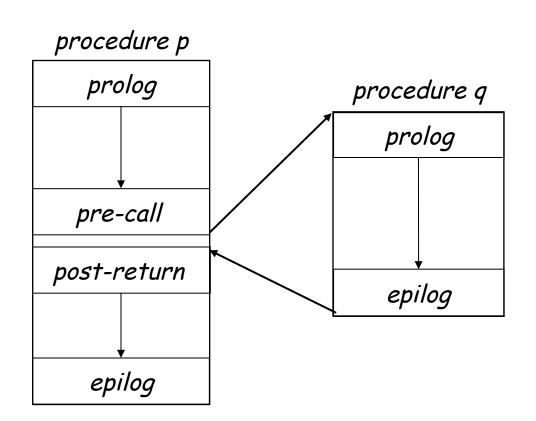


Code Shape Procedure Calls, Dispatch, Booleans, Relationals, & Control flow





Standard procedure linkage



Procedure has

- standard prolog
- standard epilog

Each call involves a

- pre-call sequence
- post-return sequence

These are completely predictable from the call site \Rightarrow depend on the number & type of the actual parameters

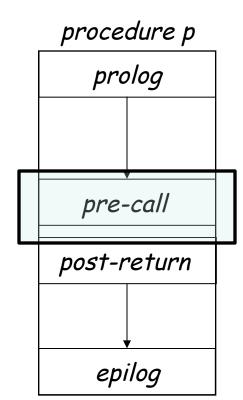




Pre-call Sequence

- Sets up callee's basic AR
- Helps preserve its own environment

- Allocate space for the callee's AR
 - → except space for local variables
- Evaluates each parameter & stores value or address
- Saves return address, caller's ARP into callee's AR
- Save any caller-save registers
 - → Save into space in caller's AR
- Jump to address of callee's prolog code



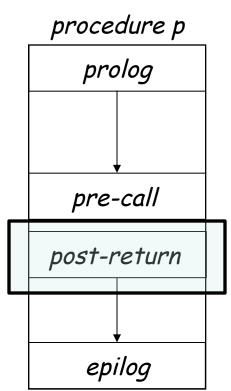




Post-return Sequence

- Finish restoring caller's environment
- Place any value back where it belongs

- Copy return value from callee's AR, if necessary
- Free the callee's AR
- Restore any caller-save registers
- Restore any call-by-reference parameters to registers, if needed
 - → Also copy back call-by-value/result parameters
- Continue execution after the call



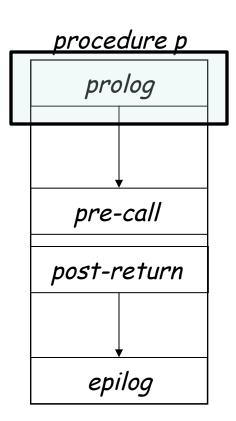




Prolog Code

- Finish setting up the callee's environment
- Preserve parts of the caller's environment that will be disturbed

- Preserve any callee-save registers
- Allocate space for local data
 - → Easiest scenario is to extend the AR
- Find any static data areas referenced in the callee
- Handle any local variable initializations



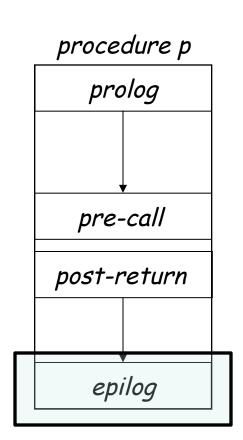
Procedure Linkages



Epilog Code

- Wind up the business of the callee
- Start restoring the caller's environment

- Store return value? No, this happens on the return statement
- Restore callee-save registers
- Free space for local data, if necessary (on the heap)
- Load return address from AR
- Restore caller's ARP
- Jump to the return address







If p calls q, one of them must

- Preserve register values (caller-saves versus callee saves)
 - \rightarrow Caller-saves registers stored/restored by p in p 's AR
 - \rightarrow Callee-saves registers stored/restored by q in q 's AR
- Allocate the AR
 - → Heap allocation ⇒ callee allocates its own AR
 - → Stack allocation ⇒ caller & callee cooperate to allocate AR

Space tradeoff

- Pre-call & post-return occur on every call
- Prolog & epilog occur once per procedure
- More calls than procedures
 - → Moving operations into prolog/epilog saves space





Evaluating parameters

- Call by reference ⇒ evaluate parameter to an Ivalue
- Call by value ⇒ evaluate parameter to an rvalue & store it

Aggregates (structs), arrays, & strings are usually c-b-r

- Language definition issues
- Alternatives
 - → Small structures can be passed in registers
 - → Can pass large c-b-v objects c-b-r and copy on modification

Procedure-valued parameters

Must pass starting address of procedure



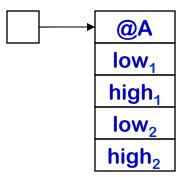


What about arrays as actual parameters?

Whole arrays, as call-by-reference parameters

- Callee needs dimension information
 - → Builds a descriptor called a *dope vector*
- Store the values in the calling sequence
- Pass the address of the dope vector in the parameter slot
- Generate complete address polynomial at each reference

dope vector







What about A[12] as an actual parameter?

If corresponding parameter is a scalar, it's easy

Pass the address or value, as needed

What if corresponding parameter is an array?

See previous slide





What about a string-valued argument?

- Call by reference ⇒ pass a pointer to the start of the string
 - → Works with either length/contents or null-terminated string
- Call by value ⇒ copy the string & pass it
 - → Can store it in caller's AR or callee's AR
 - → Can pass by reference & have callee copy it if necessary ...

Pointer of string serves as "descriptor" for the string, stored in the appropriate location (register or slot in the AR)

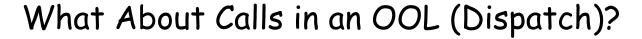




What about a structure-valued parameter?

- Again, pass a handle
- Call by reference ⇒ descriptor (pointer) refers to original
- Call by value ⇒ create copy & pass its descriptor
 - → Can allocate it in either caller's AR or callee's AR
 - → Can pass by reference & have callee copy it if necessary ...

If it is actually an array of structures, then use a dope vector

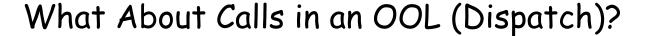




In an OOL, most calls are indirect calls

- Compiled code does not contain address of callee
 - → Finds it by indirection through class' method table
 - → Required to make subclass calls find right methods
 - \rightarrow Code compiled in class C cannot know of subclass methods that override methods in C and C 's superclasses
- In the general case, need dynamic dispatch
 - → Map method name to a search key
 - → Perform a run-time search through hierarchy
 - ◆ Start with object's class, search for 1st occurrence of key
 - This can be expensive
 - → Use a method cache to speed search
 - Cache holds < key, class, method pointer >

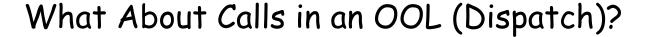
How big?
Bigger ⇒ more hits & longer search
Smaller ⇒ fewer hits, faster search





Improvements are possible in special cases

- If class has no subclasses, can generate direct call
 - → Class structure must be static or class must be FINAL
- If class structure is static
 - → Can generate complete method table for each class
 - → Single indirection through class pointer (1 or 2 operations)
 - → Keeps overhead at a low level
- If class structure changes infrequently
 - → Build complete method tables at run time
 - → Initialization & any time class structure changes





Unusual issues in OOL call

- Need to pass receiver's object record as (1st) parameter
 - → Becomes <u>self</u> or <u>this</u>
- Method needs access to its class
 - → Object record has static pointer to superclass, and so on ...
- Method is a full-fledged procedure
 - → It still needs an AR ...
 - → Can often stack allocate them

(HotSpot does ...)





How should the compiler represent them?

Answer depends on the target machine

Two classic approaches

- Numerical representation
- Positional (implicit) representation

Correct choice depends on both context and ISA





Numerical representation

- Assign values to TRUE and FALSE
- Use hardware AND, OR, and NOT operations
- Use comparison to get a boolean from a relational expression

Examples

$$x < y$$
 becomes $cmp_LT \ r_x, r_y \Rightarrow r_1$ if $(x < y)$ then $stmt_1$ else $stmt_2$ becomes $cmp_LT \ r_x, r_y \Rightarrow r_1$ $cbr \ r_1 \rightarrow _stmt_1, _stmt_2$





What if the ISA uses a condition code?

- Must use a conditional branch to interpret result of compare
- Necessitates branches in the evaluation

Example:

This "positional representation" is much more complex





What if the ISA uses a condition code?

- Must use a conditional branch to interpret result of compare
- Necessitates branches in the evaluation

Example:

Condition codes

- are an architect's hack
- allow ISA to avoid some comparisons
- complicates code for simple cases

This "positional representation" is much more complex





The last example actually encodes result in the PC If result is used to control an operation, this may be enough

Example
if (x < y)
then a ← c + d
else a ← e + f

VARIATIONS ON THE ILOC BRANCH STRUCTURE					
Straight Condition Codes			Boolean Compares		
	comp	$r_x, r_y \Rightarrow CC_1$		cmp_LT	$r_x, r_y \Rightarrow r_1$
	cbr_LT	$CC_1 \rightarrow L_1, L_2$		cbr	$r_1 \rightarrow L_1, L_2$
L ₁ :	add	$r_c, r_d \Rightarrow r_a$	L ₁ :	add	$r_c, r_d \rightarrow r_a$
	br	→L _{OUT}		br	→L _{OUT}
L ₂ :	add	$r_e, r_f \Rightarrow r_a$	L ₂ :	add	$r_e, r_f \Rightarrow r_a$
	br	$ ightarrow L_{OUT}$		br	\rightarrow L _{OUT}
L _{OUT} :	nop	_	L _{OUT} :	nop	

Condition code version does not directly produce (x < y)Boolean version does

Still, there is no significant difference in the code produced





Conditional move & predication both simplify this code

Example				
if (x < y)				
then a ← c + d				
else a ← e + f				

OTHER ARCHITECTURAL VARIATIONS					
Cond	litional Move	Predicated Execution			
comp	$r_x, r_y \Rightarrow cc_1$		стр_г	$r_x, r_y \Rightarrow r_1$	
add	$r_c, r_d \Rightarrow r_1$	(r_1) ?	add	$r_c, r_d \rightarrow r_a$	
add	$r_e, r_f \Rightarrow r_2$	$(-r_1)$?	add	$r_e, r_f \Rightarrow r_a$	
i2i_<	$cc_1,r_1,r_2 \Rightarrow r_a$				

Both versions avoid the branches
Both are shorter than CCs or Boolean-valued compare
Are they better?





Consider the assignment $x \leftarrow a < b \land c < d$

VARIAT	VARIATIONS ON THE ILOC BRANCH STRUCTURE					
Straight Condition Codes			Boolean Compare			
	comp	r _a ,r	_b ⇒CC ₁	cmp_LT	$r_a, r_b \Rightarrow r_1$	
	cbr_LT	CC ₁	\rightarrow L ₁ ,L ₂	cmp_LT	$r_c, r_d \Rightarrow r_2$	
L ₁ :	comp	r _c ,r	$_{d}\Rightarrow CC_{2}$	and	$r_1, r_2 \Rightarrow r_x$	
	cbr_LT	CC_2	\rightarrow L ₃ ,L ₂			
L ₂ :	loadl	0	$\Rightarrow r_x$			
	br		$\rightarrow L_{OUT}$			
L ₃ :	loadl	1	$\Rightarrow r_x$			
	br		\rightarrow L _{OUT}			
L _{OUT} :	nop					

Here, the boolean compare produces much better code





Conditional move & predication help here, too

$$x \leftarrow a < b \land c < d$$

OTHER ARCHITECTURAL VARIATIONS					
Conditional Move			Predicated Execution		
•	u , 10	•	cmp_LT	α, ν .	
i2i_<	$cc_1, r_T,$	$r_F \Rightarrow r_1$	cmp_LT	$r_c, r_d \Rightarrow r_2$	
	r_c, r_d			$r_1, r_2 \Rightarrow r_x$	
i2i_<	$cc_2, r_T,$	$r_F \Rightarrow r_2$			
and	r_1, r_2	$\Rightarrow r_x$			

Conditional move is worse than Boolean compares
Predication is identical to Boolean compares

Context & hardware determine the appropriate choice

Control Flow



If-then-else

 Follow model for evaluating relationals & booleans with branches

Branching versus predication (e.g., IA-64)

- Frequency of execution
 - \rightarrow Uneven distribution \Rightarrow do what it takes to speed common case
- Amount of code in each case
 - → Unequal amounts means predication may waste issue slots
- Control flow inside the construct
 - Any branching activity within the case base complicates the predicates and makes branches attractive

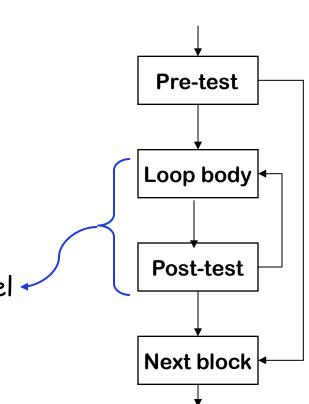
Control Flow



Loops

- Evaluate condition before loop (if needed)
- Evaluate condition after loop
- Branch back to the top (if needed)
 Merges test with last block of loop body

while, for, do, & until all fit this basic model



Loop Implementation Code



```
for (i = 1; i< 100; i++) { body }
next statement</pre>
```





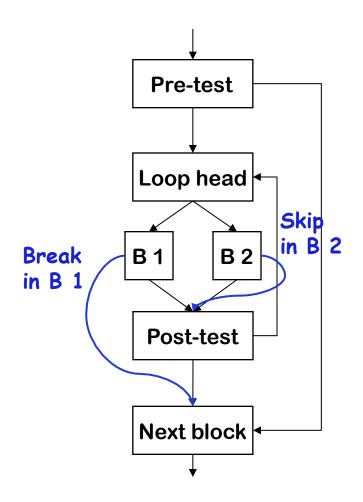
Many modern programming languages include a break

- Exits from the innermost control-flow statement
 - → Out of the innermost loop
 - → Out of a case statement

Translates into a jump

- Targets statement outside controlflow construct
- Creates multiple-exit construct
- Skip in loop goes to next iteration

Only make sense if loop has > 1 block



Control Flow



Case Statements

- 1 Evaluate the controlling expression
- 2 Branch to the selected case
- 3 Execute the code for that case
- 4 Branch to the statement after the case

Parts 1, 3, & 4 are well understood, part 2 is the key

Control Flow



Case Statements

- 1 Evaluate the controlling expression
- 2 Branch to the selected case
- 3 Execute the code for that case
- 4 Branch to the statement after the case

(use break)

Parts 1, 3, & 4 are well understood, part 2 is the key

Strategies

Surprisingly many compilers do this for all cases!

- Linear search (nested if-then-else constructs)
- Build a table of case expressions & binary search it
- Directly compute an address (requires dense case set)