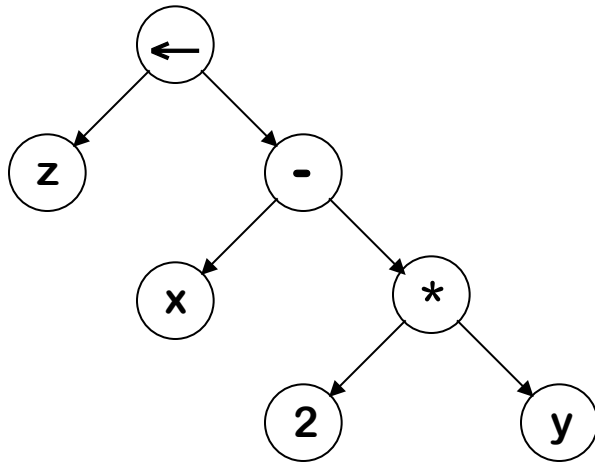




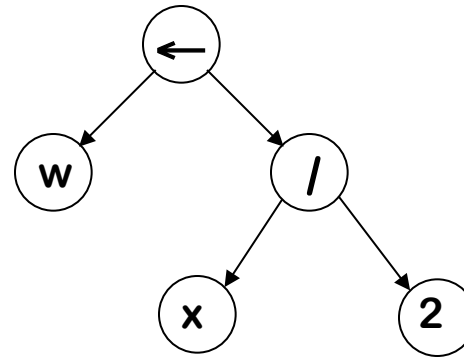
# Intermediate Representations Part II

## Directed Acyclic Graph

A directed acyclic graph (DAG) is an AST with a unique node for each value



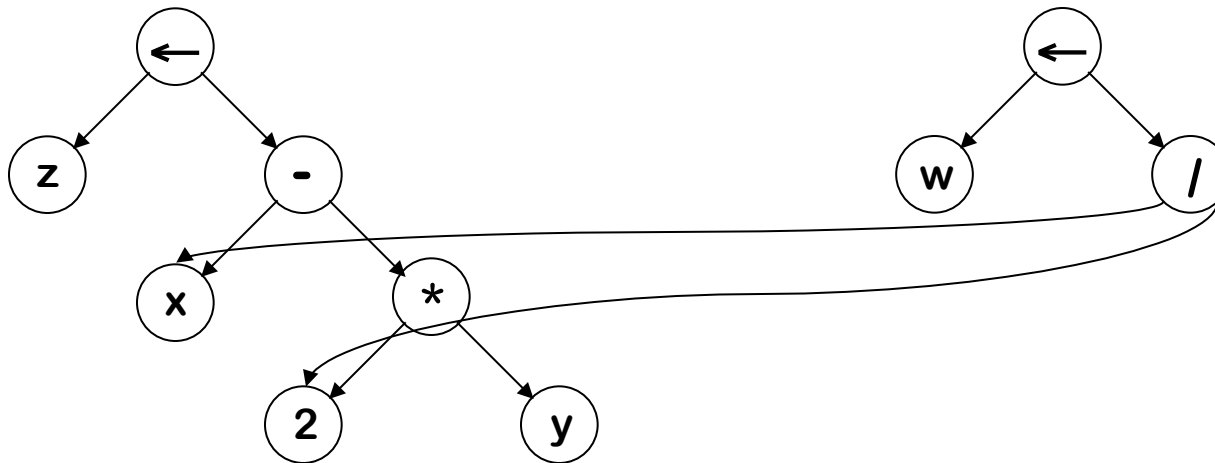
$z \leftarrow x - 2$



$w \leftarrow x / 2$

## Directed Acyclic Graph

A directed acyclic graph (DAG) is an AST with a unique node for each value



$$z \leftarrow x - 2$$

$$w \leftarrow x / 2$$



# Stack Machine Code

---

Originally used for stack-based computers,  
now Java

- Example:

$x - 2 * y$  becomes

```
push x
push 2
push y
multiply
subtract
```



## Stack Machine Code

---

- Operations take operands from a stack
- Compact form
- A form of one-address code
- Introduced names are *implicit*, not *explicit*
- Simple to generate and execute code

# Stack Machine Code Advantages



$x - 2 * y$

Result is stored in  
a temporary!  
Explicit name for  
result.

push 2  
push y  
multiply  
push x  
subtract

Multiply pops  
two items off of stack  
and pushes result!  
Implicit name for  
result



## Three Address Code

---

Different representations of three address code

- In general, three address code has statements of the form:

$$x \leftarrow y \text{ op } z$$

With 1 operator (op) and  
(at most) 3 names (x, y, & z)

# Three Address Code



Example:

$z \leftarrow x - 2 * y$  becomes

$t \leftarrow 2 * y$   
 $z \leftarrow x - t$

A diagram illustrating the transformation of the expression  $z \leftarrow x - 2 * y$  into two three-address code statements. The original expression has the sub-expression  $2 * y$  enclosed in a dashed blue box. A curved dashed blue arrow points from this box to a new variable  $t$  in the first statement,  $t \leftarrow 2 * y$ , where  $t$  is also enclosed in a dashed blue box. A solid black arrow points from the  $t$  in the first statement to the  $t$  in the second statement,  $z \leftarrow x - t$ , where  $t$  is again enclosed in a dashed blue box. Another solid black arrow points from the original  $2 * y$  box to the  $t$  in the second statement.

Explicit name for result.





## Three Address Code Advantages

- Resembles many real (RISC) machines
- Introduces a new set of names
- Compact form



## Three Address Code: Quadruples

### Naive representation of three address code

- Table of  $k * 4$  small integers

```
load  r1, y
loadI r2, 2
mult  r3, r2, r1
load  r4, x
sub   r5, r4, r3
```

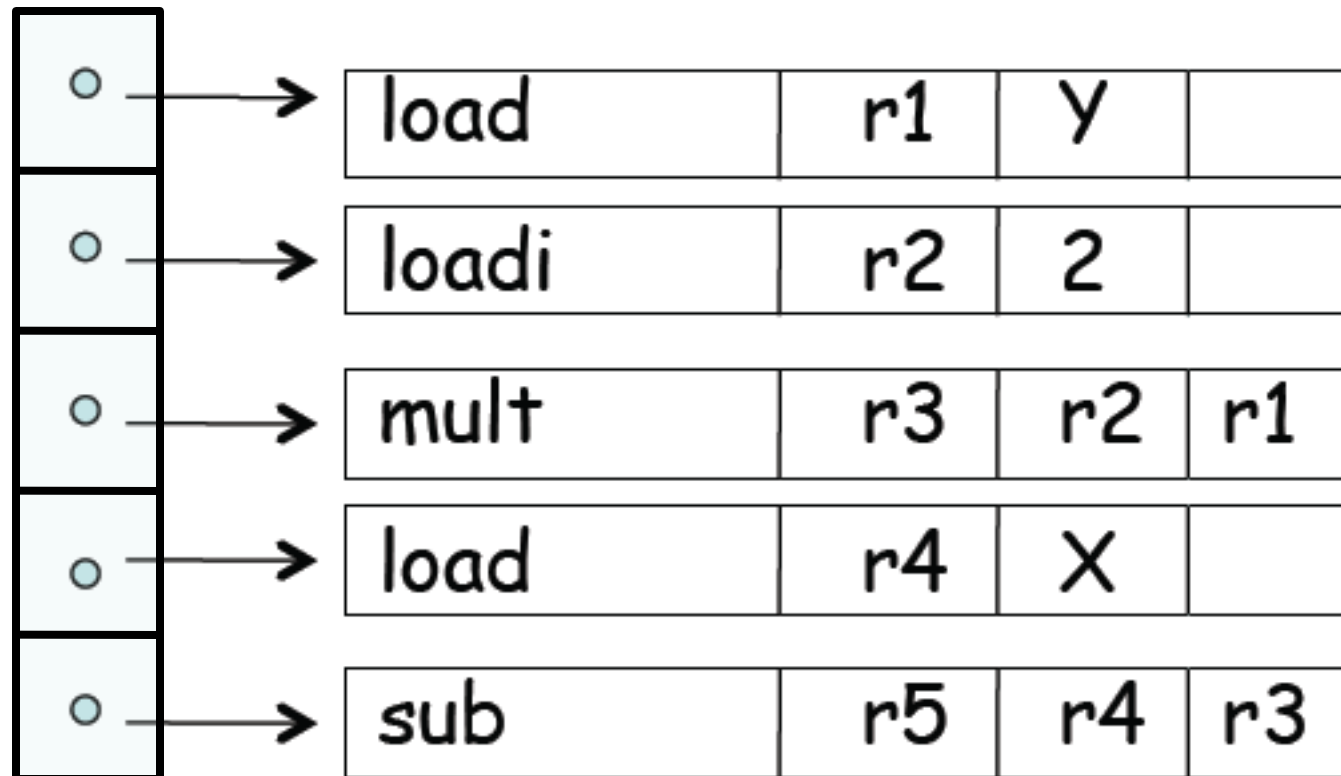
RISC assembly code

	Destination	Two operands	
load	1	y	
loadi	2	2	
mult	3	2	1
load	4	x	
sub	5	4	3

Quadruples

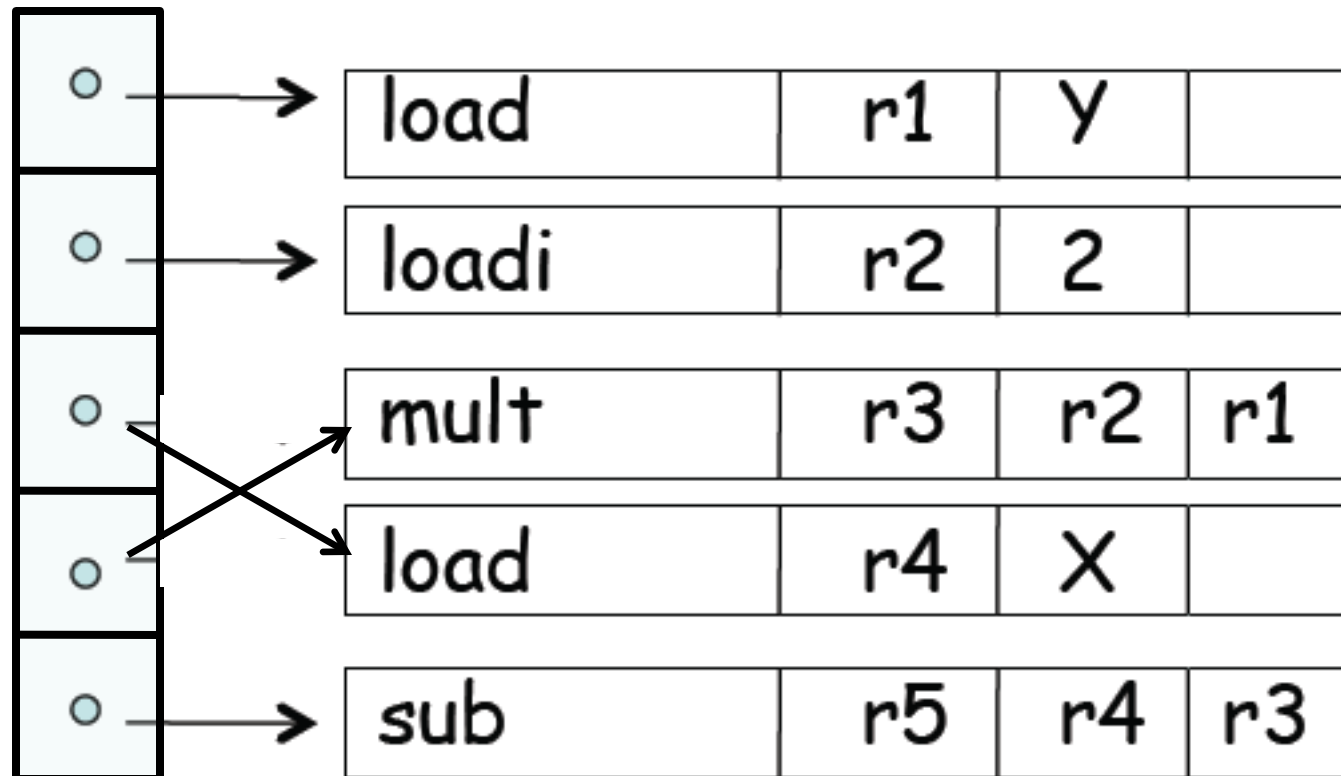
## Three Address Code: Array of Pointers

- Index causes level of indirection
- Easy (and cheap) to reorder
- Easy to add (delete) instructions



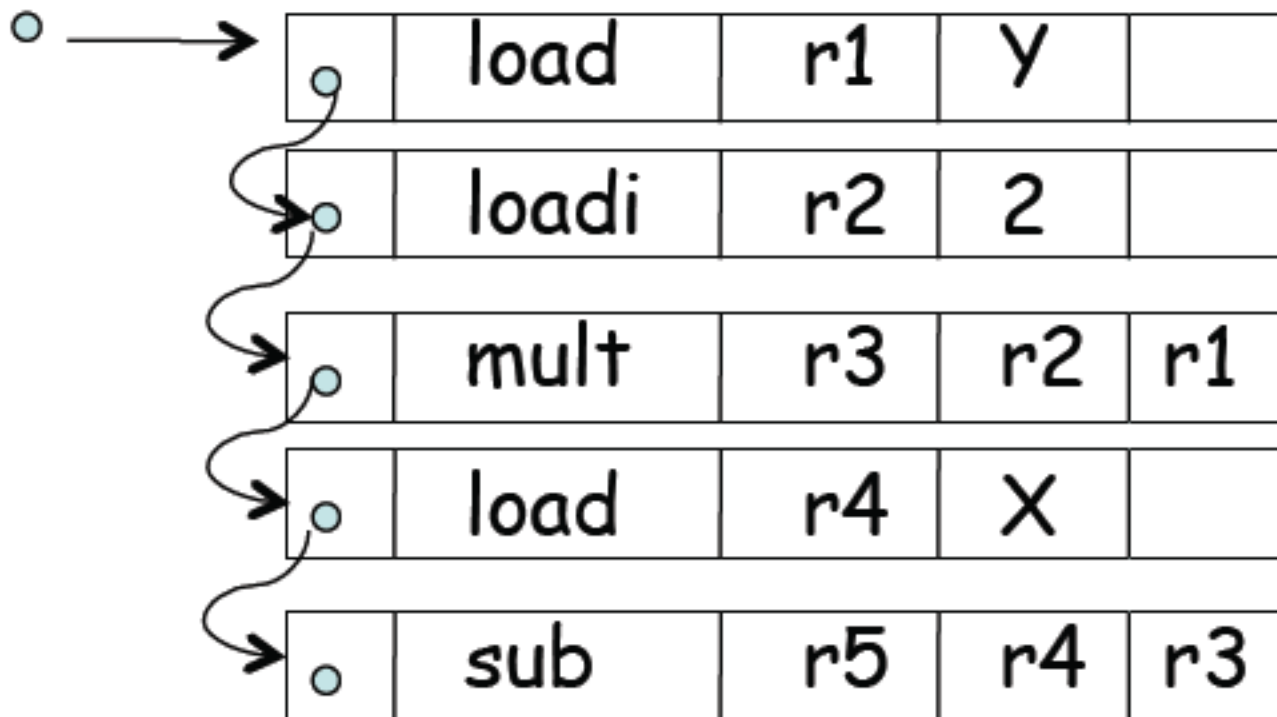
## Three Address Code: Array of Pointers

- Index causes level of indirection
- Easy (and cheap) to reorder
- Easy to add (delete) instructions



## Three Address Code: Array of Pointers

- No additional array of indirection
- Easy (and cheap) to reorder than simple table
- Easy to add (delete) instructions



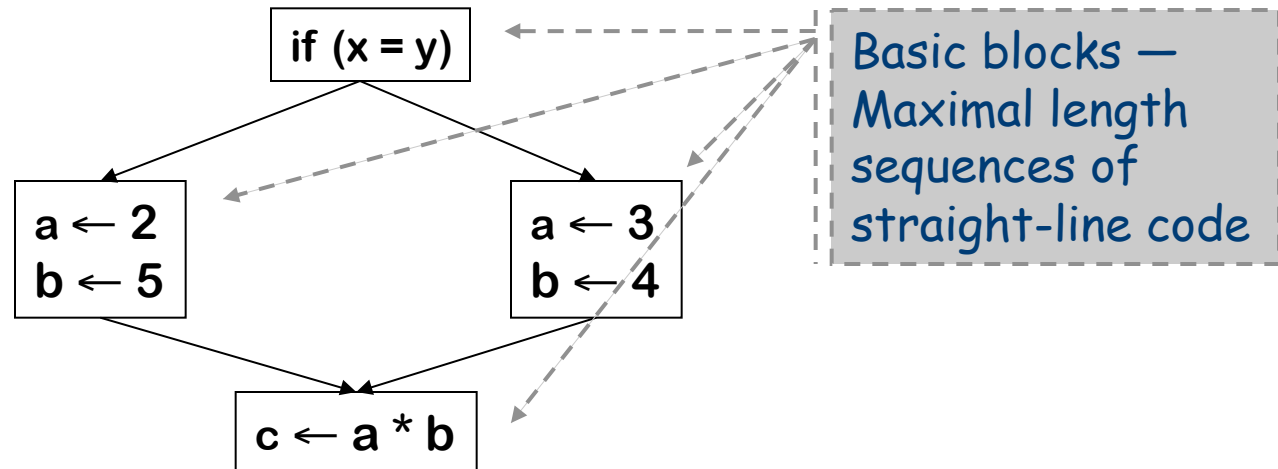


# Control-flow Graph

Models the transfer of control in the procedure

- Nodes in the graph are basic blocks
  - Can be represented with quads or any other linear representation
- Edges in the graph represent control flow

Example





# Control-Flow Graphs

---

- Node: an instruction or sequence of instructions (a **basic block**)
  - Two instructions  $i, j$  in same basic block  
*iff* execution of  $i$  *guarantees* execution of  $j$
- Directed edge: *potential* flow of control
- Distinguished start node *Entry*
  - First instruction in program



## Identifying Basic Blocks

---

- Input: sequence of instructions  $instr(i)$
- Identify **leaders**:  
first instruction of basic block
- Iterate: add subsequent instructions to basic block until we reach another leader





## Basic Block Partition Algorithm

---

```
leaders = instr(1)           // first instruction

for i = 1 to |n|             // iterate thru all instrs
    if instr(i) is a branch
        leaders = leaders  $\cup$  targets of instr(i)
        leaders = leaders  $\cup$  instr(i+1) // instr after
        branch

worklist = leaders
while worklist not empty
    x = first instruction in worklist
    worklist = worklist - {x}
    block(x) = {x}
    for (i = x + 1; i <= |n| && i not in leaders; i++)
        block(x) = block(x)  $\cup$  {i}
```



# Static Single Assignment Form

## Original

```
x ← ...  
y ← ...  
while (x < k)  
    x ← x + 1  
    y ← y + x
```

## SSA-form

```
x0 ← ...  
y0 ← ...  
if (x0 ≥ k) goto next  
loop: x1 ← φ(x0, x2)  
      y1 ← φ(y0, y2)  
      x2 ← x1 + 1  
      y2 ← y1 + x2  
      if (x2 < k) goto loop  
next: ...
```



# Static Single Assignment Form

Original

SSA-form

```
x ← ...  
y ← ...
```

```
while (x < k)  
    x ← x + 1  
    y ← y + x
```

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x0 ← ...  
y0 ← ...
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next: ...
```



# Static Single Assignment Form

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x ← ...  
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      y1 ← φ(y0, y2)  
      x2 ← x1 + 1  
      y2 ← y1 + x2  
if (x2 < k) goto loop  
next: ...
```



# Static Single Assignment Form

Original

SSA-form

$x \leftarrow \dots$

$x_0 \leftarrow \dots$

$y \leftarrow \dots$

$y_0 \leftarrow \dots$

**while (x < k)**

**if (x<sub>0</sub> ≥ k) goto next**

$x \leftarrow x + 1$

loop:  $x_1 \leftarrow \phi(x_0, x_2)$

$y \leftarrow y + x$

$y_1 \leftarrow \phi(y_0, y_2)$

$x_2 \leftarrow x_1 + 1$

$y_2 \leftarrow y_1 + x_2$

**if (x<sub>2</sub> < k) goto loop**

next: ...



# Static Single Assignment Form

## Original

```
x ← ...
y ← ...
while (x < k)
  x ← x + 1
  y ← y + x
```

## SSA-form

```
x0 ← ...
y0 ← ...
if (x0 ≥ k) goto next
loop: x1 ← φ(x0, x2)
      y1 ← φ(y0, y2)
      x2 ← x1 + 1
      y2 ← y1 + x2
      if (x2 < k) goto loop
next: ...
```

This is new! Inserted  
at points where diff.  
control flow merge.



# Static Single Assignment Form

## Original

```
x ← ...  
y ← ...  
while (x < k)  
    x ← x + 1  
    y ← y + x
```

Keeps single assign.  
property.

## SSA-form

```
x0 ← ...  
y0 ← ...  
if (x0 ≥ k) goto next  
loop: x1 ← φ(x0, x2)  
      y1 ← φ(y0, y2)  
      x2 ← x1 + 1  
      y2 ← y1 + x2  
      if (x2 < k) goto loop  
next: ...
```



# Static Single Assignment Form Advantages

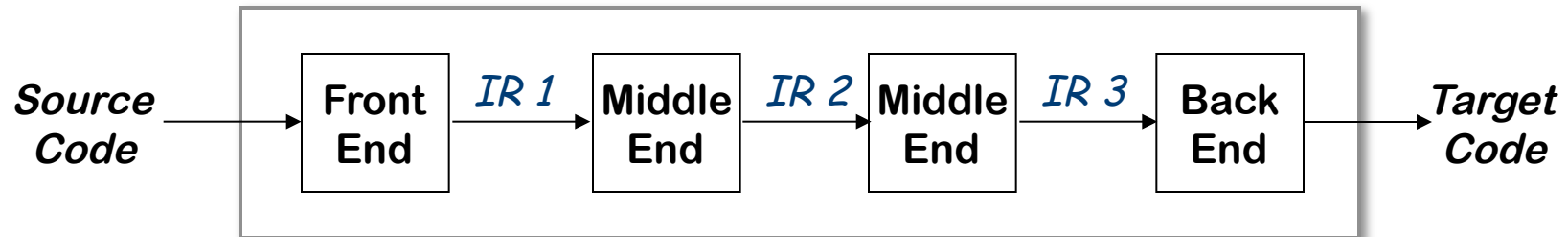
## Strengths of SSA-form

- Sharper analysis because values never redefined
- Simplifies and improves optimizations
- (Sometimes) faster algorithms





# Using Multiple Representations



- Repeatedly lower the level of the intermediate representation
  - Each intermediate representation is suited towards certain optimizations
- Example: the Open64 compiler
  - WHIRL intermediate format
    - Consists of 5 different *IRs* that are progressively more detailed and less abstract



# Memory Models

---

## Two major models

- Register-to-register model
  - Keep all values that can legally be stored in a register in registers
  - Ignore machine limitations on number of registers
  - Compiler back-end must insert loads and stores
- Memory-to-memory model
  - Keep all values in memory
  - Only promote values to registers directly before they are used
  - Compiler back-end can remove loads and stores
- Compilers for RISC machines usually use register-to-register
  - Reflects programming model
  - Easier to determine when registers are used



## The Rest of the Story...

---

Representing the code is only part of an *IR*

There are other necessary components

- Symbol table
- Constant table
  - Representation, type
  - Storage class, offset
- Storage map
  - Overall storage layout
  - Overlap information
  - Virtual register assignments



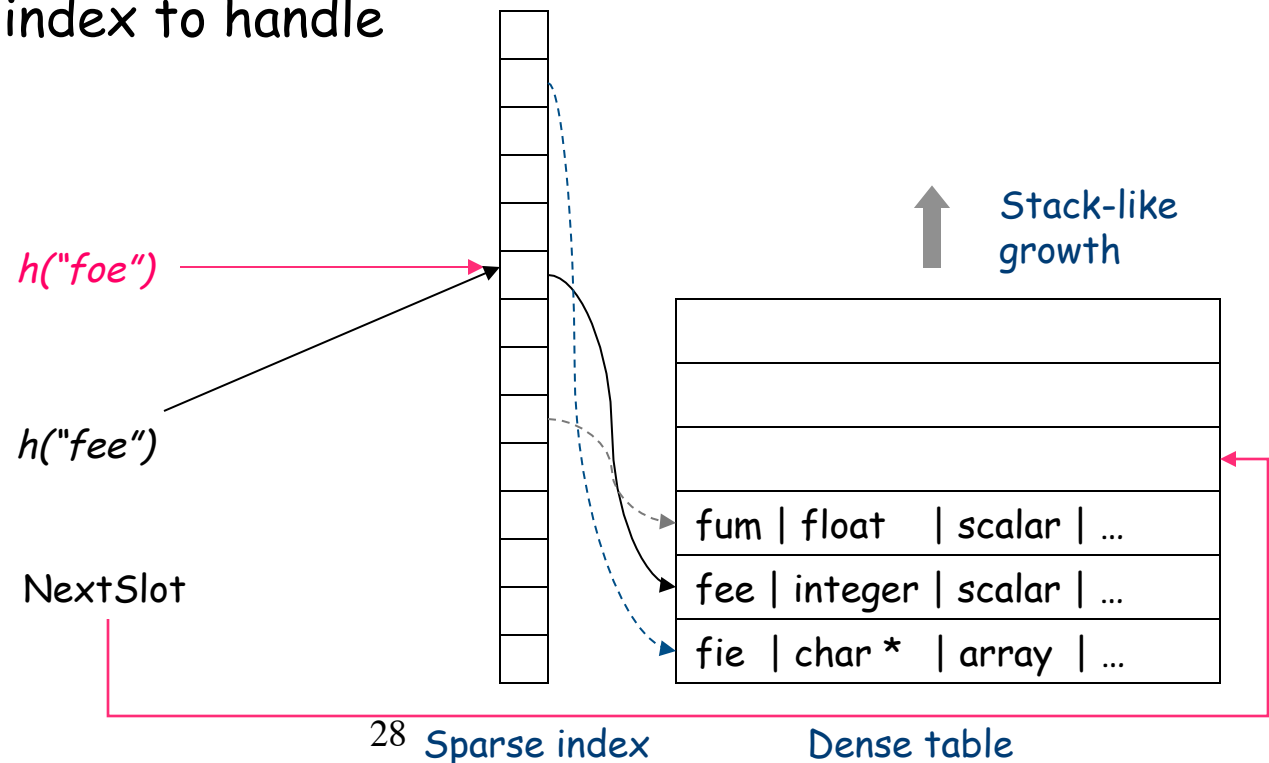
# Symbol Tables

Classic approach to building a symbol table uses hashing

- Personal preference: a two-table scheme
  - Sparse index to reduce chance of collisions
  - Dense table to hold actual data
    - Easy to expand, to traverse, to read & write from/to files
- Use chains in index to handle collisions

See SB.3 in EaC for a longer explanation

Collision occurs when  $h()$  returns a slot in the sparse index that is already full.

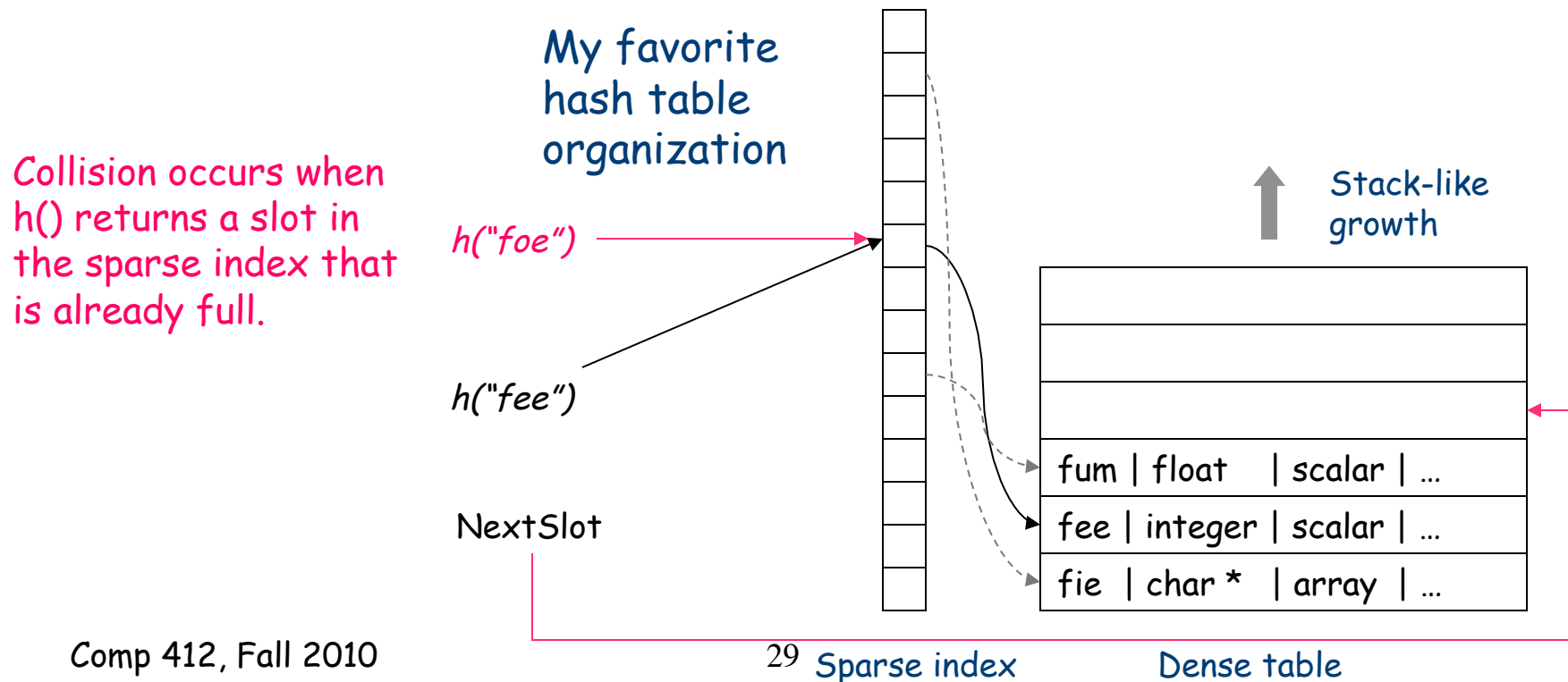




# Hash-less Symbol Tables

Classic approach to building a symbol table uses hashing

- Some concern about worst-case behavior
  - Collisions in the hash function can lead to linear search
  - Some authors advocate "perfect" hash for keyword lookup
- Automata theory lets us avoid worst-case behavior





# Hash-less Symbol Tables

---

One alternative is Paige & Cai's *multiset discrimination*

- Order the name space offline
- Assign indices to each name
- Replace the names in the input with their encoded indices

Digression on page 241 of EaC

Using DFA techniques, we can build a guaranteed linear-time replacement for the hash function  $h$

- DFA that results from a list of words is acyclic
  - RE looks like  $r_1 \mid r_2 \mid r_3 \mid \dots \mid r_k$
  - Could process input twice, once to build DFA, once to use it
- We can do even better

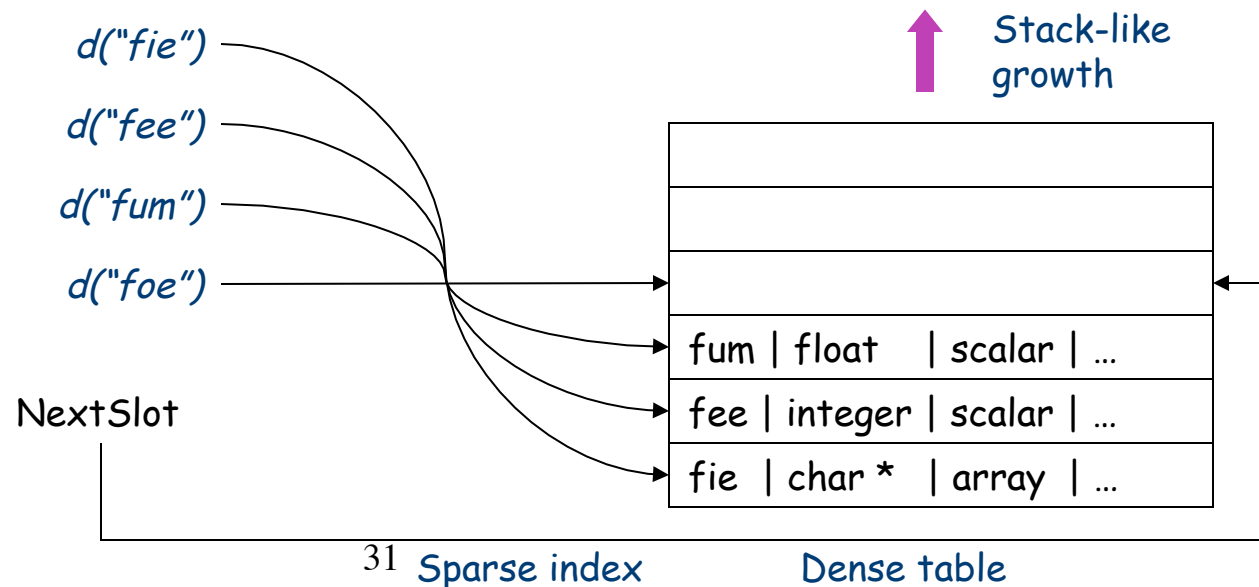


# Hash-less Symbol Tables

Classic approach to building a symbol table uses hashing

- Some concern about worst-case behavior
  - Collisions in the hash function can lead to linear search
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- Automata theory lets us avoid worst-case behavior

Replace the hash function,  $h$ , and the sparse index with an efficient direct map,  $d$ , ...





# Hash-less Symbol Tables

---

## Incremental construction of an acyclic DFA

- To add a word, run it through the DFA
  - At some point, it will face a transition to the error state
  - At that point, start building states & transitions to recognize it
- Requires a memory access per character in the key
  - If DFA grows too large, memory access costs become excessive
  - For small key sets (e.g., names in a procedure), not a problem
- Optimizations
  - Last state on each path can be explicit
    - Substantial reduction in memory costs
    - Instantiate when path is lengthened
  - Trade off granularity against size of state representation
  - Encode capitalization separately
    - Bit strings tied to final state?