

A large, faint, circular seal of the University of Delaware is visible in the background on the left side. It contains the text 'UNIVERSITY OF DELAWARE' around the perimeter, '1743' at the bottom, and 'SOL' in the center. Inside the seal are two open books with the following text: 'GRAMM', 'PHIOL', 'RHETOR', 'ETHICA' on the left page and 'METAPH', 'LOGIC', 'MATHEM', 'PHYSICA' on the right page.

FSAN/ELEG815: Statistical Learning

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2b. Matrix Completion

Outline

Matrix Completion

Introduction

Problem Formulation

Optimization Problem

Algorithms

Image Inpainting

Additive Matrix Decomposition

Matrix Approximations and Completion

Given an $m \times n$ matrix $\mathbf{Z} = \{z_{ij}\}$, find a matrix $\hat{\mathbf{Z}}$ that approximates \mathbf{Z} .

- ▶ $\hat{\mathbf{Z}}$ may have simpler structure.
- ▶ Missing entries in \mathbf{Z} , a problem known as *matrix completion*.

Approach based on optimization:

$$\hat{\mathbf{Z}} = \arg \min_{\mathbf{M} \in \mathbb{R}^{m \times n}} \|\mathbf{Z} - \mathbf{M}\|_F^2 \text{ subject to } \Phi(\mathbf{M}) \leq c \quad (1)$$

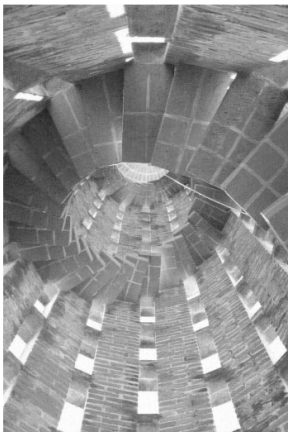
where $\|\mathbf{A}\|_F^2 = \sum \sum_{i,j} |a_{ij}|^2$ is the Frobenius Norm, and $\Phi(\cdot)$ is a constraint function that encourages $\hat{\mathbf{Z}}$ to be sparse in some sense.

Constraint $\Phi(\mathbf{Z})$	Resulting method
(a) $\ \hat{\mathbf{Z}}\ _{\ell_1} \leq c$	Sparse matrix approximation
(b) $\text{rank}(\hat{\mathbf{Z}}) \leq k$	Singular value decomposition
(c) $\ \hat{\mathbf{Z}}\ _* \leq c$	Convex matrix approximation

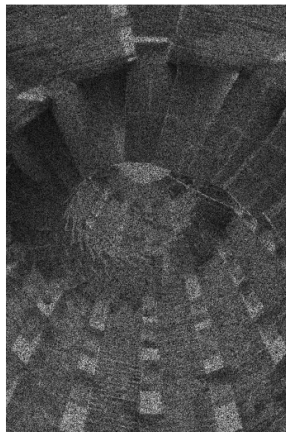
- ▶ (a) ℓ_1 -norm of all entries of $\hat{\mathbf{Z}}$. Leads to a soft-thresholding $\hat{z}_{ij} = \text{sign}(z_{ij})(|z_{ij}| - \gamma)_+$, where $\gamma > 0$ is such that $\sum_{i=1}^m \sum_{j=1}^n |\hat{z}_{ij}| = c$.
- ▶ (b) Bounds the rank of $\hat{\mathbf{Z}}$, or the number of nonzero singular values in $\hat{\mathbf{Z}}$. Approximation is non-convex, but solution found by computing the SVD and truncating it to its top k components.
- ▶ (c) Relaxes the rank constraint to a *nuclear norm* ($\|\mathbf{A}\|_* = \sum_{i=1}^{\min\{m,n\}} \sigma_i$). Solved by computing the SVD and soft-thresholding its singular values.

Motivation: Image Reconstruction from Incomplete Data

Reconstructed image



Incomplete image 50% of the pixels



Matrices with missing elements can be solved exactly using method (c), whereas methods based on (b) are more difficult to solve in general.

Constraint	Resulting method
$\hat{\mathbf{Z}} = \mathbf{L} + \mathbf{S}, \Phi_1(\mathbf{L}) \leq c_1, \Phi_2(\mathbf{S}) \leq c_2$	Additive matrix decomposition

- ▶ Seeks an additive decomposition of the matrix, imposing penalties on both components in the sum.

The Singular Value Decomposition

Given an $m \times n$ matrix \mathbf{Z} with $m \geq n$, its *singular value decomposition* takes the form

$$\mathbf{Z} = \mathbf{U}\mathbf{D}\mathbf{V}^T \quad (2)$$

- ▶ \mathbf{U} is an $m \times n$ orthogonal matrix ($\mathbf{U}^T \mathbf{U} = \mathbf{I}_n$) whose columns $\mathbf{u}_j \in \mathbb{R}^m$ are the *left singular vectors*.
- ▶ \mathbf{V} is an $n \times n$ orthogonal matrix ($\mathbf{V}^T \mathbf{V} = \mathbf{I}_n$) whose columns $\mathbf{v}_j \in \mathbb{R}^n$ are the *right singular vectors*.
- ▶ The $n \times n$ matrix \mathbf{D} is diagonal, with $d_1 \geq d_2 \geq \dots \geq d_n \geq 0$ known as the *singular values*.

The Singular Value Decomposition

- ▶ If columns of \mathbf{Z} are centered (zero mean), then the right singular vectors $\{\mathbf{v}_j\}_{j=1}^n$ define the *principal components* of \mathbf{Z} .
- ▶ The unit vector \mathbf{v}_1 yields the linear combination $\mathbf{s}_1 = \mathbf{Z}\mathbf{v}_1$ with highest sample variance among all possible choices of unit vectors.
- ▶ \mathbf{s}_1 is the *first principal component* of \mathbf{Z} , and \mathbf{v}_1 is the corresponding *direction* or *loading* vector.

The Singular Value Decomposition

Suppose $r \leq \text{rank}(\mathbf{Z}) = 800$, and let \mathbf{D}_r be a diagonal matrix with all but the first r diagonal entries of \mathbf{D} set to zero. The optimization problem

$$\hat{\mathbf{Z}}_r = \min_{\text{rank}(M)=r} \|\mathbf{Z} - \mathbf{M}\|_F \quad (3)$$

has a closed form solution $\hat{\mathbf{Z}}_r = \mathbf{U}\mathbf{D}_r\mathbf{V}^T \triangleq$ the rank- r SVD. $\hat{\mathbf{Z}}_r$ is sparse in the sense that all but r singular values are zero.



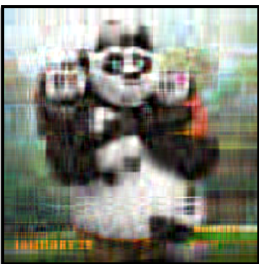
800 Singular Values



164 Singular Values



24 Singular Values



12 Singular Values

Matrix Completion

Problem Formulation: Recover an $m \times n$ matrix \mathbf{Z} when we only get to observe $p \ll mn$ of its entries.

- ▶ Impossible without additional information!
- ▶ Assumption: Matrix is known to be low-rank or approximately low-rank.
- ▶ Matrix Completion: Fill the missing entries.
- ▶ Used in: machine learning, computer vision...

Optimization Problem

- ▶ Observe the entries of the $m \times n$ matrix \mathbf{Z} indexed by the subset $\Omega \subset \{1, \dots, m\} \times \{1, \dots, n\}$.
- ▶ Seek the lowest rank approximating matrix $\hat{\mathbf{Z}}$ that interpolates the entries of \mathbf{Z}

$$\begin{aligned} & \text{minimize} && \text{rank}(\mathbf{M}) \\ & \text{subject to} && m_{ij} = z_{ij}, (i, j) \in \Omega, \end{aligned} \tag{4}$$

- ▶ Rank minimization problem is NP-hard.
- ▶ Forcing interpolation leads to overfitting.

Optimization Problem

- ▶ Better to allow \mathbf{M} to make some errors on the observed data:

$$\begin{aligned} & \text{minimize} && \text{rank}(\mathbf{M}) \\ & \text{subject to} && \sum_{(i,j) \in \Omega} (z_{ij} - m_{ij})^2 \leq \delta, \end{aligned} \quad (5)$$

or equivalently

$$\begin{aligned} & \text{minimize} && \sum_{(i,j) \in \Omega} (z_{ij} - m_{ij})^2, \\ & \text{rank}(\mathbf{M}) \leq r && \end{aligned} \quad (6)$$

- ▶ Both problems are non-convex, and exact solutions are generally not available.

Matrix Completion Using the Nuclear Norm

- ▶ Nuclear norm of $\mathbf{M}_{m \times n}$:

$$\|\mathbf{M}\|_* = \sum_{k=1}^n \sigma_k(\mathbf{M}) \quad (7)$$

- ▶ Convex relaxation of the rank minimization problem:

$$\begin{aligned} & \text{minimize} && \|\mathbf{M}\|_* \\ & \text{subject to} && m_{ij} = z_{ij}, (i, j) \in \Omega, \end{aligned} \quad (8)$$

- ▶ Whereas the rank counts the number of nonzero singular values, the nuclear norm sums their amplitude.
- ▶ Analogous to the ℓ_1 norm as a relaxation for the ℓ_0 norm as sparsity measure.

Notation

Given an observed subset Ω of matrix entries, define the projection operator as:

$$[P_{\Omega}(\mathbf{Z})]_{i,j} = \begin{cases} z_{ij} & \text{if } (i,j) \in \Omega \\ 0 & \text{otherwise} \end{cases}$$

P_{Ω} replaces the missing entries in \mathbf{Z} with zeros, and leaves the observed entries alone.

The optimization criterion is then :

$$\sum_{(i,j) \in \Omega} (z_{ij} - m_{ij})^2 = \|P_{\Omega}(\mathbf{Z}) - P_{\Omega}(\mathbf{M})\|_F^2 \quad (9)$$

where $\|\cdot\|_F$ is the Frobenius norm of a matrix defined as the element-wise sum of squares.

Singular Value Thresholding for Matrix Completion,⁺

- ▶ Solves the optimization problem:

$$\begin{aligned} & \text{minimize} && \|\mathbf{M}\|_* \\ & \text{subject to} && P_{\Omega}(\mathbf{M}) = P_{\Omega}(\mathbf{Z}), \end{aligned} \tag{10}$$

- ▶ The SVD of a matrix \mathbf{M} of rank r is:

$$\mathbf{M} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T, \quad \mathbf{\Sigma} = \text{diag}(\{\sigma_i\}_{1 \leq i \leq r}) \tag{11}$$

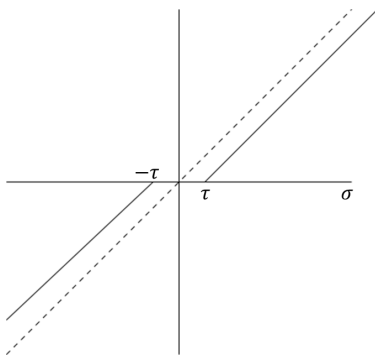
⁺Cai et al. (2010), SIAM Journal on Optimization, Vol. 20, No. 4

Singular Value Thresholding (SVT)

- ▶ For each $\tau \geq 0$, the soft-thresholding operator D_τ is defined as:

$$D_\tau(\mathbf{M}) = \mathbf{U}D_\tau(\mathbf{\Sigma})\mathbf{V}^T, \quad D_\tau(\mathbf{\Sigma}) = \text{diag}(\text{sgn}(\sigma_i) \{|\sigma_i| - \tau\}_+) \quad (12)$$

where $t, t_+ = \max(0, t)$. Operator applies soft-thresholding to the singular values of \mathbf{M} , effectively shrinking them towards zero.



SVT Algorithm - Shrinkage Iterations

Fix $\tau > 0$ and a sequence $\{\delta_k\}$ of positive step sizes. Starting with $\mathbf{Y}^0 = \mathbf{0}$, inductively define for $k = 1, 2, \dots$,

$$\begin{cases} \mathbf{M}^k = D_\tau(\mathbf{Y}^{k-1}) \\ \mathbf{Y}^k = \mathbf{Y}^{k-1} + \delta_k P_\Omega(\mathbf{Z} - \mathbf{M}^k) \end{cases}$$

$$\mathbf{M}^1 = D_\tau(\mathbf{Y}^0) = \mathbf{0}$$

$$\begin{aligned} \mathbf{Y}^1 &= \mathbf{0} + \delta_1 P_\Omega(\mathbf{Z} - \mathbf{0}) \\ &= \delta_1 P_\Omega(\mathbf{Z}) \end{aligned}$$

$$\mathbf{M}^2 = D_\tau(\mathbf{Y}^1) = \delta_1 P_\Omega(\mathbf{Z})$$

$$\mathbf{Y}^2 = \delta_1 P_\Omega(\mathbf{Z}) + \delta_1 P_\Omega(\mathbf{Z} - \delta_1 P_\Omega(\mathbf{Z}))$$

until a stopping criterion is reached. At each step, we only need to compute an SVD and perform elementary matrix operations.

SVT Algorithm - Shrinkage Iterations



Netflix Movie Challenge - Revisited

- ▶ Dataset: $n = 17,770$ movies (columns) and $m = 480,189$ customers (rows).
- ▶ Customers rated movies on a scale from 1 to 5. Matrix is very sparse with “only” 100 million of the ratings present in the training set.
- ▶ Goal: Predict the ratings for unrated movies.

Netflix Prize **COMPLETED**

Home Rules Leaderboard Update

Leaderboard

Showing Test Score. Click here to view past scores

Display top 20 leaders.

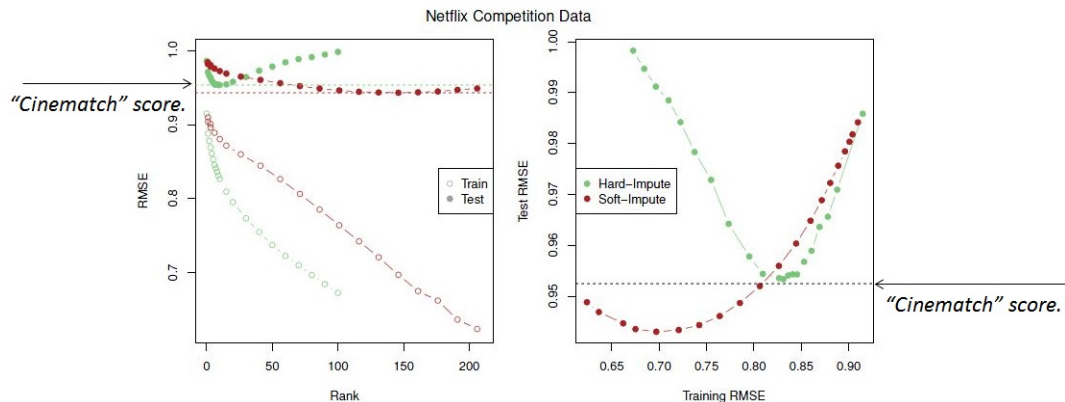
Rank	Team Name	Best Test Score	Improvement	Best Submit Time
Grand Prize - RMSE = 0.8837 - Winning Team: Bellkor's Pragmatic Chaos				
1	Bellkor's Pragmatic Chaos	0.8837	10.06	2009-07-26 18:19:28
2	The Ensemble	0.8927	10.06	2009-07-26 18:36:22
3	Claris (Pete Tass)	0.8982	9.96	2009-07-15 21:29:40
4	Claris Solutions and Velocity United	0.9088	9.84	2009-07-15 01:12:31
5	Velocity United 1	0.9191	9.81	2009-07-15 00:52:20
6	PragmaticTheory	0.9294	9.77	2009-06-24 12:06:58
7	Bellkor in BigChaos	0.9351	9.72	2009-05-13 08:14:09
8	Claris	0.9412	9.59	2009-07-04 17:18:43
9	Teedee	0.9522	9.48	2009-07-12 13:11:81
10	BigChaos	0.9623	9.47	2009-04-07 12:33:59
11	Claris Solutions	0.9653	9.47	2009-07-04 00:19:47
12	Bellkor	0.9824	9.46	2009-07-26 17:19:11
Progress Prize 2008 - RMSE = 0.8627 - Winning Team: Bellkor in BigChaos				
13	Teedee	0.8642	9.27	2009-07-15 14:53:22
14	Claris	0.8643	9.26	2009-04-22 18:31:32
15	Claris	0.8651	9.18	2009-06-21 19:28:53
16	Pragmatic Theory	0.8653	9.18	2009-07-15 18:53:04
17	Just a Guy (J. A. Johnson)	0.8682	9.06	2009-05-24 10:02:04
18	J. Dennis Su	0.8686	9.02	2009-03-07 17:16:17
19	Claris (Cristian)	0.8688	9.02	2009-07-26 18:05:14
20	Teedee	0.8688	9.02	2009-03-21 14:20:30
Progress Prize 2007 - RMSE = 0.8723 - Winning Team: Bellkor				
Cinematch 2006 - RMSE = 0.9525				

There are currently 81851 contestants on 41326 teams from 186 different countries. We have received 44574 valid submissions from 5185 different teams. 3 submissions in the last 24 hours. Questions about interpreting the leaderboard? Please read this.

- ▶ (2006) “Cinematch” algorithm used by Netflix RMSE=0.9525 over a large test set.
- ▶ Competition started in 2006, winner should improve this RMSE by at least 10%.
- ▶ 2009 “Bellkor’s Pragmatic Chaos,” uses a combination of many statistical techniques to win.

Netflix Movie Challenge

(Left) RMSE over the training and test sets as the rank of the SVD was varied (Hard-impute). Also estimates based on nuclear norm regularization (soft-impute). (Right) Test error only, plotted against training error, for the two methods.



SVT Algorithm Solution

Viewers rated movies on a scale from 1 to 5, 0 for movies that were not rated by the user.

- ▶ Each column j is a different movie
- ▶ Each row i is a different viewer
- ▶ Each element $a_{i,j}$ represents the rating of movie j by viewer i

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5
Viewer 1	0	1	0	0	5
Viewer 2	4	2	0	0	0
Viewer 3	0	0	3	3	0
Viewer 4	4	2	0	0	0
Viewer 5	0	0	0	0	5
Viewer 6	0	0	3	3	0
Viewer 7	1	0	0	0	4
Viewer 8	2	1	0	0	4
Viewer 9	1	0	0	0	4

$$\mathbf{A} = \begin{bmatrix} a_{1,1} & \cdots & \cdots & a_{1,n} \\ \vdots & \ddots & \ddots & \vdots \\ a_{m,1} & \cdots & \cdots & a_{m,n} \end{bmatrix}$$

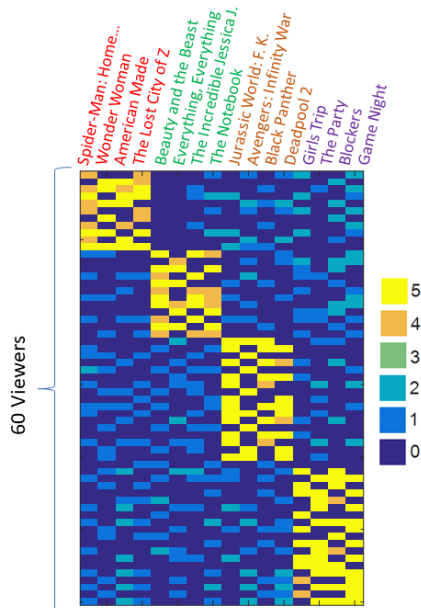
Goal: Use **SVT algorithm** to predict unobserved data or the rating of a movie that hasn't come out yet.

SVT Algorithm Solution

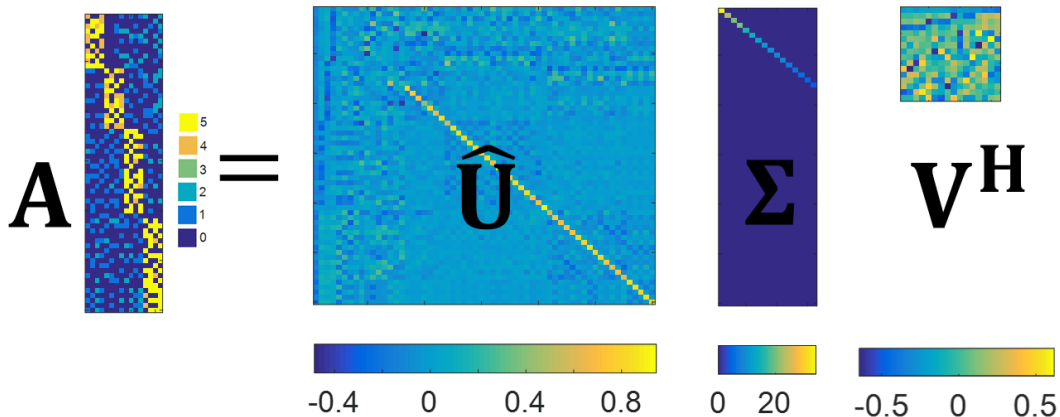
Considering the rating from 60 viewers to 16 movies of 4 different genres (action, romance, sci-fi, comedy), we generate $\mathbf{A} \in \mathbb{R}^{60 \times 16}$

- ▶ Viewers rated movies on a scale from 1 to 5, 0 for movies that were not rated by the user.
- ▶ Observe the same 4 categories of viewers.

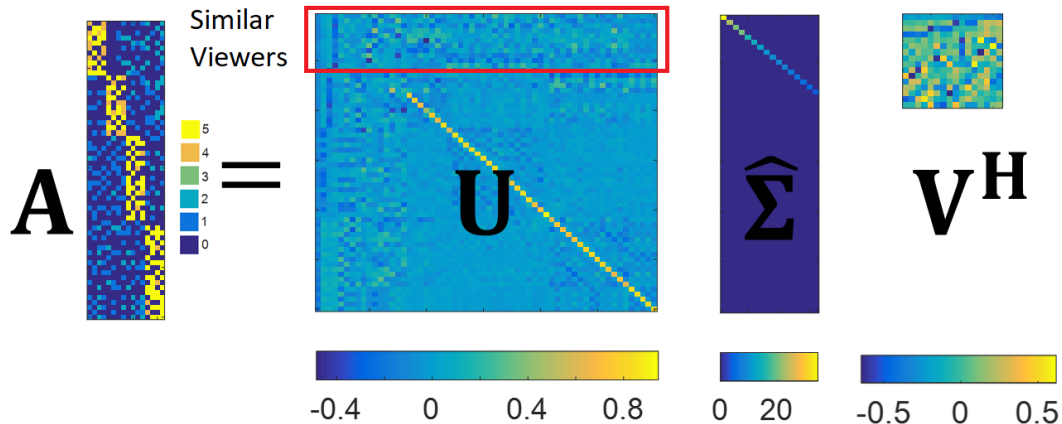
$\mathbf{A} =$



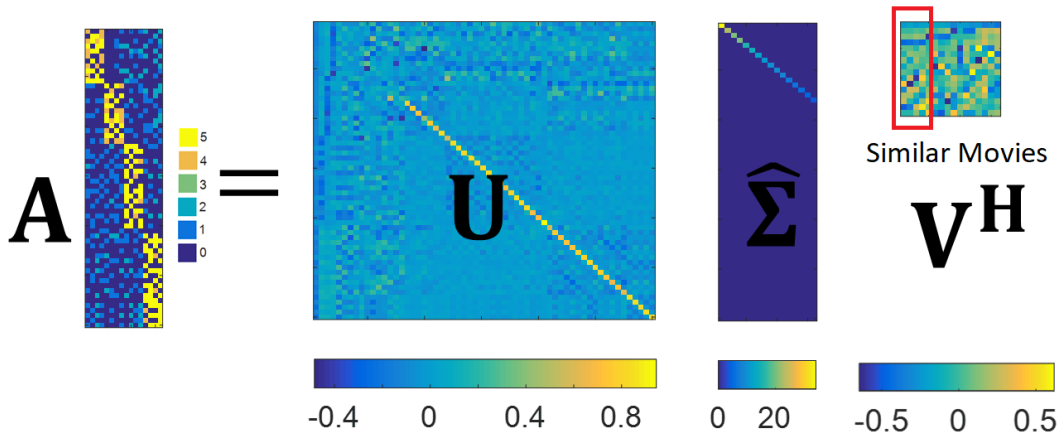
SVT Algorithm Solution



SVT Algorithm Solution



SVT Algorithm Solution



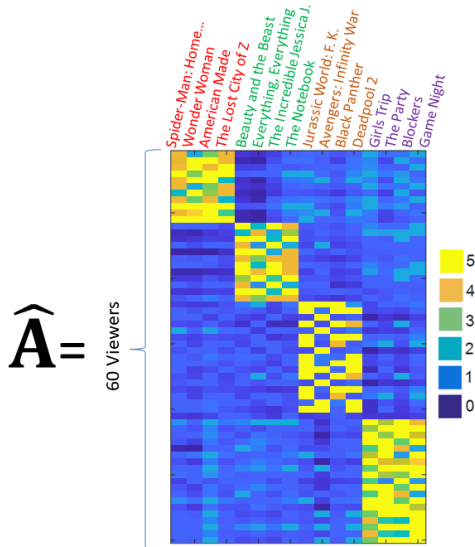
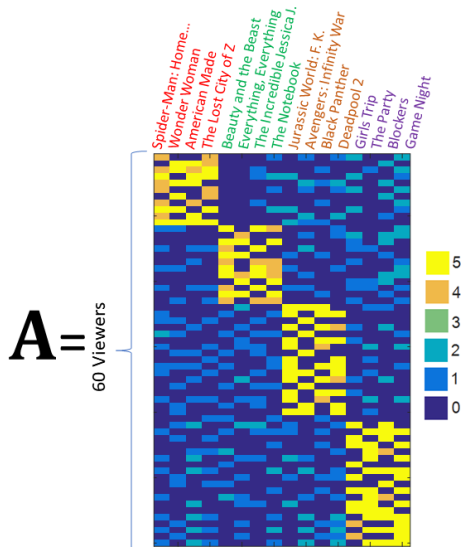
SVT Algorithm Solution

Use SVT Algorithm to estimate not rated movies (zero entries in \mathbf{A}), solving the optimization problem:

$$\begin{aligned} & \text{minimize} && \|\hat{\mathbf{A}}\|_* \\ & \text{subject to} && P_{\Omega}(\hat{\mathbf{A}}) = P_{\Omega}(\mathbf{A}), \end{aligned}$$

Note: The ratings matrix \mathbf{A} is expected to be low-rank since user preferences can be described by a few categories (k), such as the movie genres.

SVT Algorithm Solution



SVT Algorithm Solution

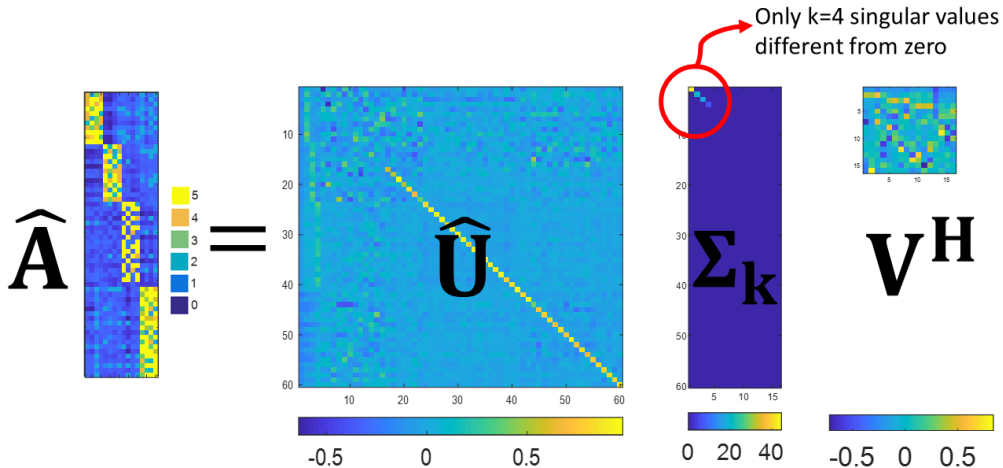
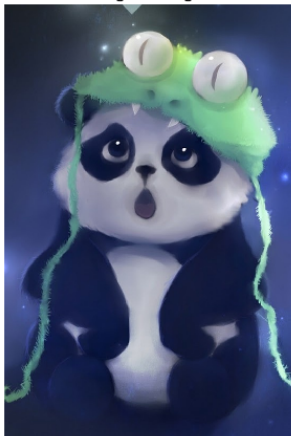


Image Inpainting - Convex Optimization Solver

With 70% of the Information.

Original Image



Noisy Image



Reconstructed

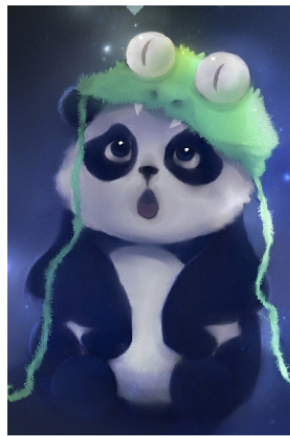
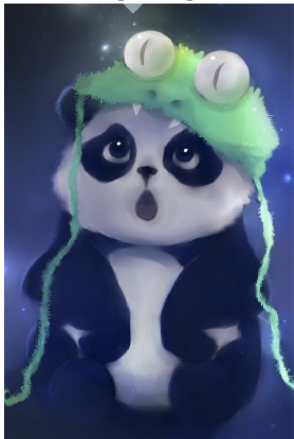


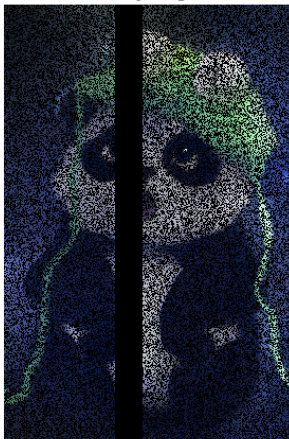
Image Inpainting - Convex Optimization Solver

With 50% of the Information. And multiple columns missing.

Original Image



Noisy Image



Reconstructed

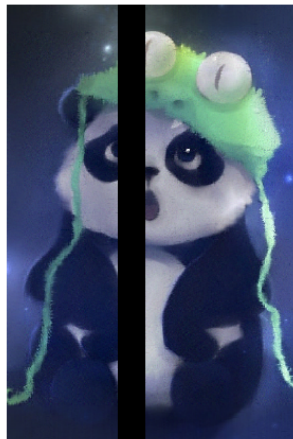
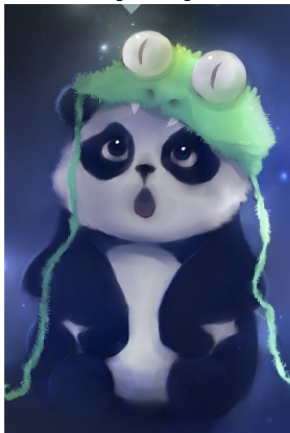


Image Inpainting - Convex Optimization Solver

With 50% of the Information. PSNR=35.9 dB.

Original Image



Noisy Image



Reconstructed

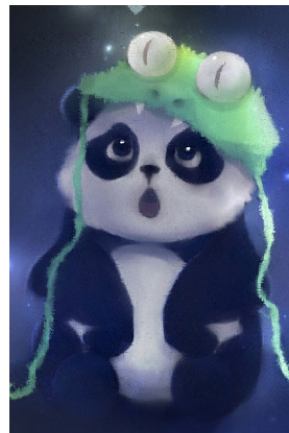
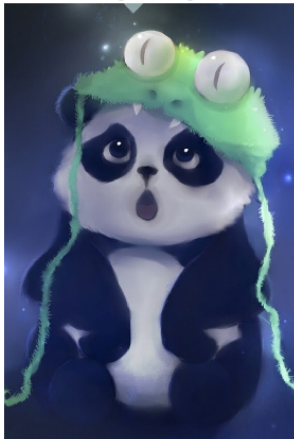


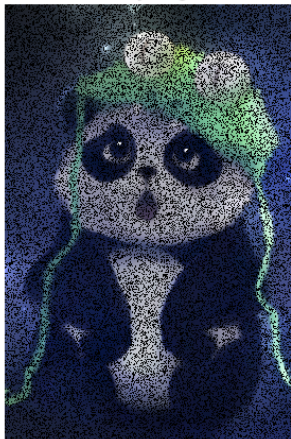
Image Inpainting - SVT Algorithm⁺

With 50% of the Information. PSNR=38.1 dB.

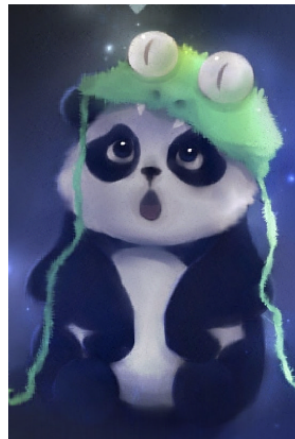
Original Image



Noisy Image



Reconstructed



⁺Cai et al. (2010), SIAM Journal on Optimization, Vol. 20, No. 4

Text Removal - Convex Optimization Solver

Original Image



Noisy Image



Reconstructed

