

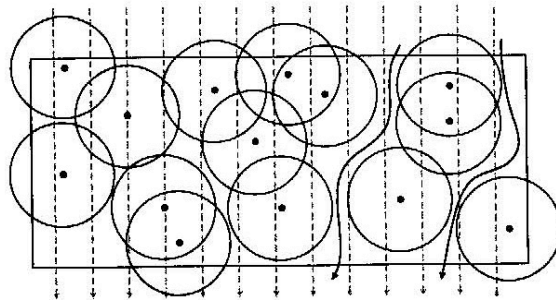
# University of Delaware -- Computer and Information Science

## CIS621 -- Homework 4

**Handed out:** October 25, 2011  
**Due date:** November 8, 2011

### 10. [Individual Problem]

Consider a set of  $n$  sensors deployed in a “belt region” – that is, a rectangular region  $R$  that is aligned with the  $x$ - $y$  axes, where typically the width along the  $x$ -axis is much larger than the height along the  $y$ -axis. Assume that each sensor has a **sensing range** of  $r$ . That is, the sensor can **detect** movement anywhere in or on the circle of radius  $r$  centered at the sensor. This set of sensors provides  **$k$ -weak barrier coverage** for  $R$  if an intruder moving across  $R$  on any path parallel to the  $y$  axis will be detected by at least  $k$  sensors. Here is an example where the sensors provide 1-weak barrier coverage:



An illustration of weak 1-barrier coverage: any orthogonal crossing path (dashed lines) is covered by at least one sensor. However, uncovered path(s) may exist, such as the ones shown in the solid curves.

Give an  $O(n \log n)$  algorithm to determine if a set of  $n$  sensors provides  $k$ -weak barrier coverage for  $R$ .

### 11. [Individual Problem]

Consider a connected, undirected, edge weighted graph  $G$  with  $n$  vertices and  $e$  edges. For any spanning tree  $T$  of  $G$ , a **bottleneck edge of  $T$**  is an edge of largest weight in  $T$ . A **bottleneck spanning tree** for  $G$  is a spanning tree for  $G$  which, among all spanning trees for  $G$ , has the smallest weight bottleneck edge.

- [3 pts] It follows easily from Kruskal’s algorithm that any minimum spanning tree for  $G$  is also a bottleneck spanning tree for  $G$ . Give an example showing that the reverse however is not necessarily true. That is, show that a bottleneck spanning tree of  $G$  need not be a minimum spanning tree of  $G$ .
- [7 pts] Give an  $O(e+n)$  algorithm for finding a bottleneck spanning tree of  $G$ .

### 12. [Group Problem]

A **scorpion** on  $n$  vertices is a graph that has a vertex of degree 1 (the tail), connected to a vertex of degree 2 (the body), connected to a vertex of degree  $n-2$  (the head). The other  $n-3$  vertices (the feet) can be arbitrarily interconnected.

Give an  $O(n)$  algorithm for deciding whether or not an arbitrary graph is a scorpion, assuming that the graph is represented by an adjacency matrix.